## Permanent Magnets program for PETRA IV

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**Outline** 

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Proposed DLQ design

Latest DLQ configurations

Present status and future tasks

• Introduction and evolution of DL design



### **PETRA III is one of the core facilities at DESY**

#### Each year ~5000h users operation serve more than 2000 users



#### Ada Yonath Hall

Extension Hall East



Max von Laue Hall

Paul P. Ewald Hall Extension Hall North

Parameter	PETRA III
Energy [GeV]	6
Circumference [m]	2304
Emittance (hor./vert.) [nm.rad]	1.3/ 0.013
Total current [mA]	100

Courtesy of R. Bartolini

### **PETRA IV project:**

replacing PIII with an ultra low emittance ring (20 pm) adding a new Experimental Halls in two more octants

### A new lattice proposal was evaluated

There is a new lattice H6BA performing better than the previous one







Courtesy of D. Einfeld

- Based on H6BA cell 8 octants with 9 cells each
- Strongly favored as the present PIIIbeamlines can be conserved
- In the octants "U" there is the lattice H6BA\_23.00 m and in the octants "A" is the lattice H6BA\_22.75 m (Same magnet arrangement, they only differ in the straight section length)
  - There are overall 432 permanent Bendings, 1348 Quadrupoles, 432 Sextupoles, 286
     Octupoles and 1126 Correctors. This makes overall 3626 magnets.
  - In addition there are 40 damping wigglers in the octants A and 30 undulators for users in the octants U.

### The H6BA outperforms the combi lattice

Justification and consequences of the changes investigated

H6BA lattice [9 cells per octant] vs combi lattice [modified H7BA 8 cells per octant]

Emittance kept to 20 pm albeit with a different concept, Based on extensive use of DW in long straight sections (as now in PIII)

#### Pros

- Larger Dynamic Aperture (off axis injection and accumulation looks now feasible)
- Larger Momentum Acceptance (Touschek lifetime 2.5-fold improvement)
- More PM magnets (resistive DQs changed to PM based DQs changed DLs to DLQs)
- Overall performance improved (sensitivity to errors and instabilities)
- One more beamline per octant
- Possibility of keeping the existing source point fixed in the Max von Laue Experimental Hall

#### Cons

- Stronger focusing quadrupoles (max 115 T/m) but weaker sextupoles in dispersion bump
- Reduced straight section length 5.3 m to 4.7 m
- Reduced brightness, despite smaller and equal beta functions in the straight sections
- All bending magnets become more demanding combined-function magnets



### **Evolution of DL design**







Cross section of the previous DL



### **Combi lattice**

- Maximum field 0.38 T
- No transverse gradient
- "Flat" pole
- Uniform field along the transverse direction
- 2 types of DLs

### **H6BA** lattice

- Maximum field ~0.29 T
- Moderate transverse gradient ~11.7 T/m
- Tapered pole
- 3 types: 1 DLQ, 2 DQs

### From the combi cell to H6BA cell

- 4 DLs and 3 central DQs substituted with 2 DLQs and 4 PM DQs
- Same cell structure replicated across all octants



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### **Latest DLQ Configurations**



#### Parameters for the 23m cell

	Element	Length	Field	Gradient	$x_0 = B/G$
		(m)	(T)	(T/m)	(mm)
	DL1A_4	0.303	0.2771	-11.3144	
	DL1A_3	0.303	0.2878	-11.7471	24 5
DLQ	DL1A_2	0.303	0.2558	-10.4426	24.5
	DL1A_1	0.303	0.2238	-9.1382	

DQ DL2A 1.084 0.1907	-7.7184	24.7
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DQ DL3B 1.84 0.1901 -6.5972 2	28.8
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- Maximum gradient -11.7 T/m
- 50% higher G/B compared to "26m-version"
- Gradient hardly achieved (at the limit for a tapered 2-pole design)
- 3 types of DLQs (DQs), 432 magnets in total
- Different module length for each DLQ
- DL2A and DL3B will be split to 4 and 6 modules each





Difference to pure DLs ("Combi")

- Magnetic and mechanical design

- Measurement concept (curved)

- Modules are straight but must be

placed on curve trajectory

- Tuning and alignment

- ~50% more PMs to build

- More challenging:



Intermediate Design for 26m H6BA cell: ✓

- Maximum gradient -9.7 T/m, achievable with previous 2-pole design
- 3 types of DLQs with same G/B
- Same modules length 0.414 m for all

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### **Proposed DLQ Design**

#### **Open structure**



Off axis vacuum chamber by 5 - 6 mm ( $\phi$  25 mm)

- GFR center: -5.1 mm with a range of 11 mm
- Field and gradient at center of GFR: 0.334 T 13.65 T/m
- Gradient homogeneity ΔG/G0 in GFR: 0.000228
- Pole Gap at center of GFR: 30 mm
- Outer diameter of vacuum chamber: 25 mm
  - GFR center: **-6.3 mm** with a range of **10 mm**
  - Field and gradient at center of GFR: 0.31 T 12.68 T/m
  - Gradient homogeneity  $\Delta G/G0$  in GFR: **0.00036**
  - Pole Gap at center of GFR: 32 mm
  - Outer diameter of vacuum chamber: 25 mm

	Open structure	Structure with yoke
Advantages	<ul> <li>Good field quality enhanced</li> <li>Larger GFR and center close to geometrical axis</li> <li>More degree of freedom for tuning</li> <li>Compactness</li> <li>Larger opening for vacuum chamber</li> </ul>	<ul> <li>Good feedback from ESRF-DL experience (measurement, thermal shimming)</li> <li>Less challenging in terms of mechanical assembly</li> <li>Less sensitive to ambient field changes</li> </ul>
Drawbacks	<ul> <li>Mechanical magnet assembly more challenging : assembly errors, magnetic forces</li> <li>Higher sensitivity to magnet block errors</li> <li>Field tuning needs to be revisited due to decoupled poles</li> <li>More sensitive (magnetic behavior)</li> </ul>	<ul> <li>Tighter opening for Vacuum chamber</li> <li>Smaller GFR (present optimization state)</li> </ul>





### **Preliminary Results**

### **Open structure**



- GFR center: -5.1 mm with a range of 11 mm
  - Field and gradient at center of GFR: 0.334 T 13.65 T/m
- Gradient homogeneity ΔG/G0 in GFR: 0.000228
- Pole Gap at center of GFR: 30 mm
- Outer diameter of vacuum chamber: 25 mm

#### 0.0008 0.0006 0.0004 0.0002 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 -0.0004 -0.0006 -0.0006 -0.0006

Structure with yoke



Harmonics



- GFR center: -6.3 mm with a range of 10 mm
- Field and gradient at center of GFR: 0.31 T 12.68 T/m
- Gradient homogeneity ΔG/G0 in GFR: 0.00036
- Pole Gap at center of GFR: 32 mm
- Outer diameter of vacuum chamber: 25 mm



Transverse direction [mm]

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### **Present status and future tasks**

### **Design status**

- Ist solution (2D) achieved in August 2021
- Present preliminary results of new DLQs are promising
- Mechanical design can start with some overlap to magnetic refinement
- Collaboration with ESRF is well established
- Schedule for the WP needs adjustment due to lattice change

### Next Tasks

- 3D model needs to be worked out
- Cross-talk, magnetic and mechanical error assessments
- Launch prototype(s)
- Elaborate alignment concept
- Develop assembly and measurement procedures
- Work out logistics for production phase

### Personnel

InnovEEA-related PostDoc will start soon (Nov.21)



# Thank you for your attention!