

# (Fast) Machine Learning for Belle II at ETP 16.09.2022

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![](_page_0_Picture_5.jpeg)

# **Overview for ML usage**

## Actively used:

- used in most analysis for event classification. Most advanced tools "Full Event Reconstruction" and CNN-based flavour tagger with significant contribution from ETP.
- used in offline reconstruction (mostly BDTs) for background-rejection in sub-detectors and particle identification
- "NeuroZ" neural network trigger on multi-FPGAs lead by KIT-ITIV
- Active development:
  - Generative background generation (waveforms, pixel-patterns, ...)
  - More complex real-time algorithms (vertexing, track-finding, cluster-splitting)
  - Anomaly detection for model-independent searches (much better SM understanding than ad pp colliders)

![](_page_1_Picture_10.jpeg)

![](_page_1_Figure_12.jpeg)

![](_page_1_Picture_13.jpeg)

# (Real-time) tracking using Graph Neural Networks (GNNs)

## Physics challenges:

- Very high beam backgrounds
- low pt tracks
- (non-pointing) displaced vertices

## Technical challenges:

- Need (very) low latency of  $O(\mu s) \rightarrow FPGAs$ 
  - Limited ressources on FPGA
  - Slow development cycles for everything nonstandard
- Stereolayers

![](_page_2_Picture_11.jpeg)

![](_page_2_Figure_12.jpeg)

![](_page_2_Picture_14.jpeg)

# (Real-time) tracking using Graph Neural Networks (GNNs)

![](_page_3_Figure_1.jpeg)

![](_page_3_Picture_3.jpeg)

![](_page_3_Picture_5.jpeg)

![](_page_3_Picture_6.jpeg)

# n-dimensional clustering

## Physics challenges:

- High dimensional input data on irregular grids:
  - "5D": x, y, z, time, energy (e.g. CALICE)
  - $\theta$ ,  $\phi$ , time, energy, pulse-shape, crystal dimensions
- Very high backgrounds (noise)

![](_page_4_Figure_6.jpeg)

![](_page_4_Picture_8.jpeg)

![](_page_4_Figure_9.jpeg)

#### **Belle II ECAL (full luminosity)**

![](_page_4_Figure_14.jpeg)

![](_page_4_Figure_16.jpeg)

# **One-stage multi-object reconstruction: Object condensatio**

## Physics challenges:

- Clustering (ECAL) and trackfinding for unknown(!) number of objects
- Overlapping clusters and crossing tracks

### Technical challenges:

Optimization trade-off (multiple regression and classification targets)

![](_page_5_Figure_6.jpeg)

![](_page_5_Picture_8.jpeg)

![](_page_5_Figure_9.jpeg)

#### position resolution and splitting

#### energy resolution and threshold

![](_page_5_Figure_14.jpeg)

![](_page_5_Picture_16.jpeg)

# Model-independent searches with anomaly detection

## Physics challenges:

Extended dark sector models with multiple mass scales, couplings, and lifetimes over potentially large SM backgrounds (No "out-of-distribution" events)

### Current strategy: Autoencoders

# Challenge for future application:

- Real-time trigger application (inputs with much less) precision compared to offline)
- validation with data

![](_page_6_Picture_8.jpeg)

![](_page_6_Picture_10.jpeg)

![](_page_6_Figure_12.jpeg)