

Plasma integrated control and trajectory optimization via reinforcement learning: applications in magnetic confinement fusion

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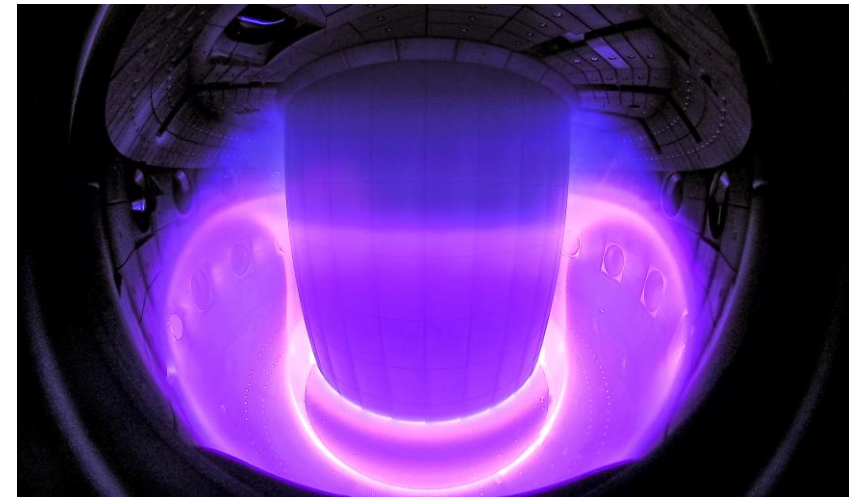
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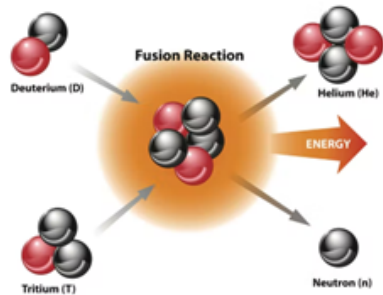


Tokamak a Configuration Variable (TCV)



■ Magnetic confinement fusion in brief

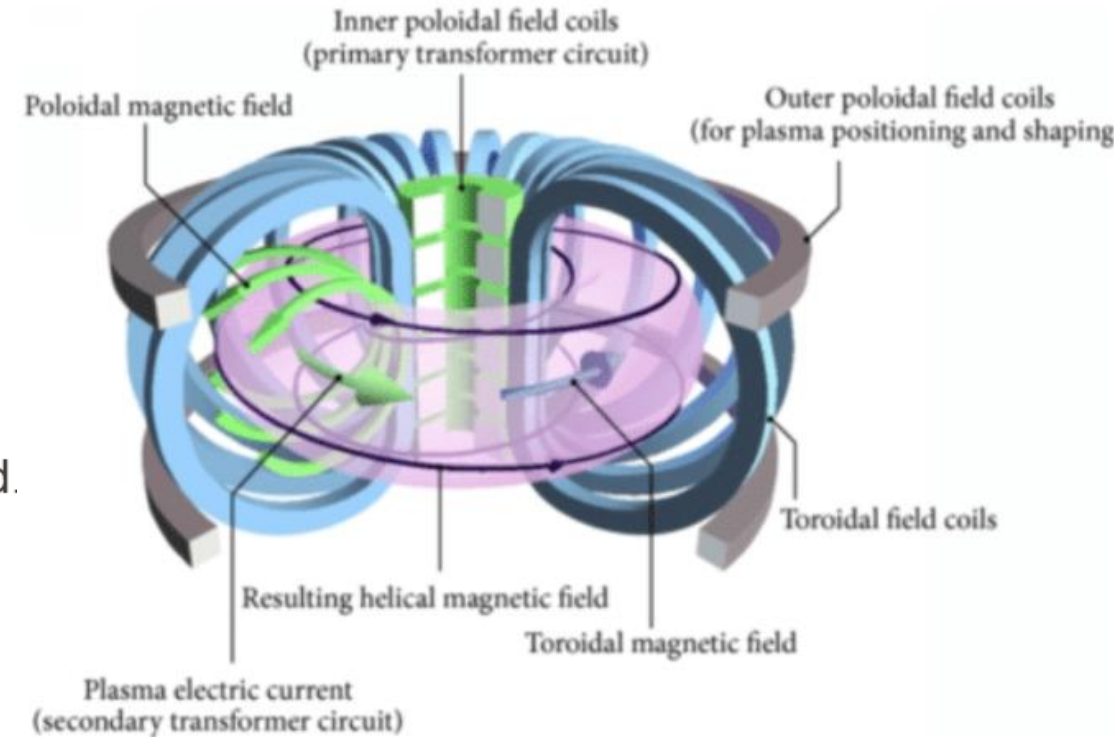
- For thermonuclear fusion one needs a high product of temperature, density, and confinement. Typically, $T > 100\text{MK}$



- Matter is in the **plasma state**
 - ions and electrons are dissociated.
- Magnetic fusion: keep the plasma confined by **magnetic fields**

■ Tokamaks

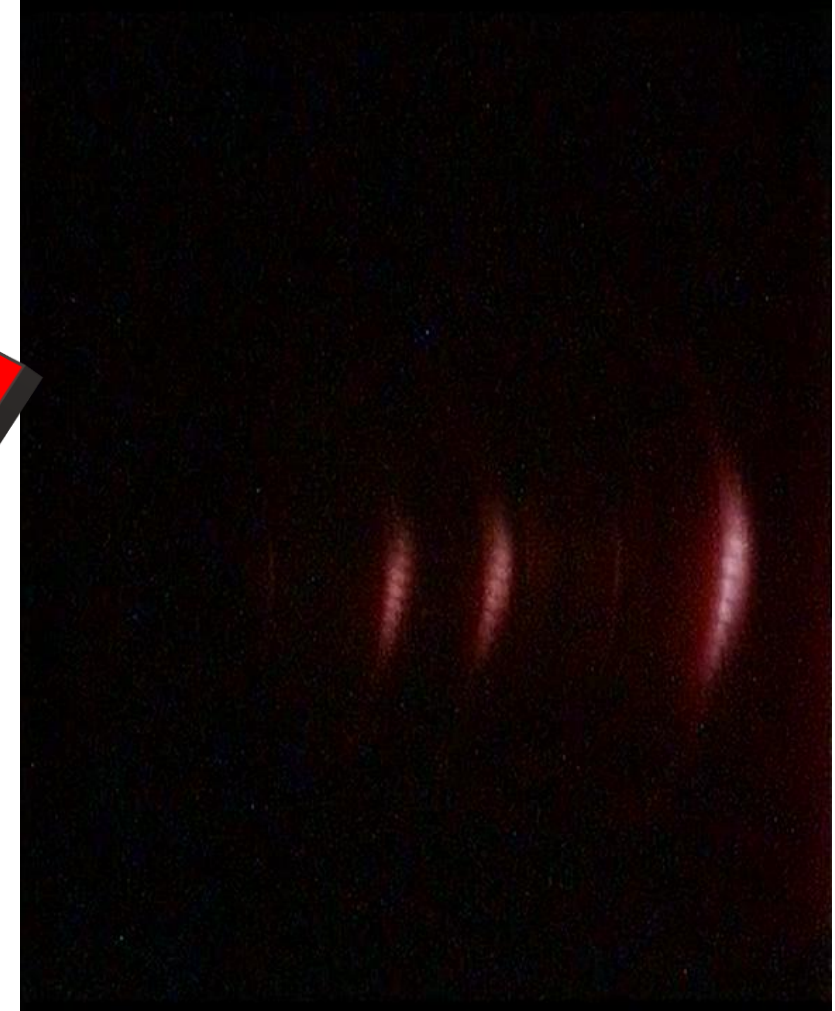
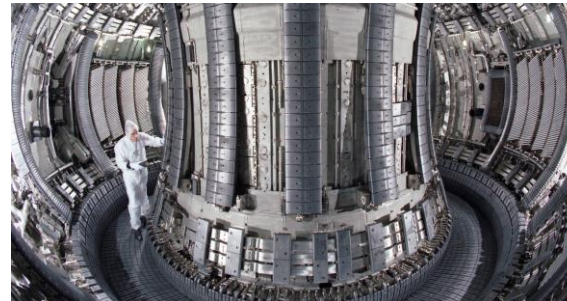
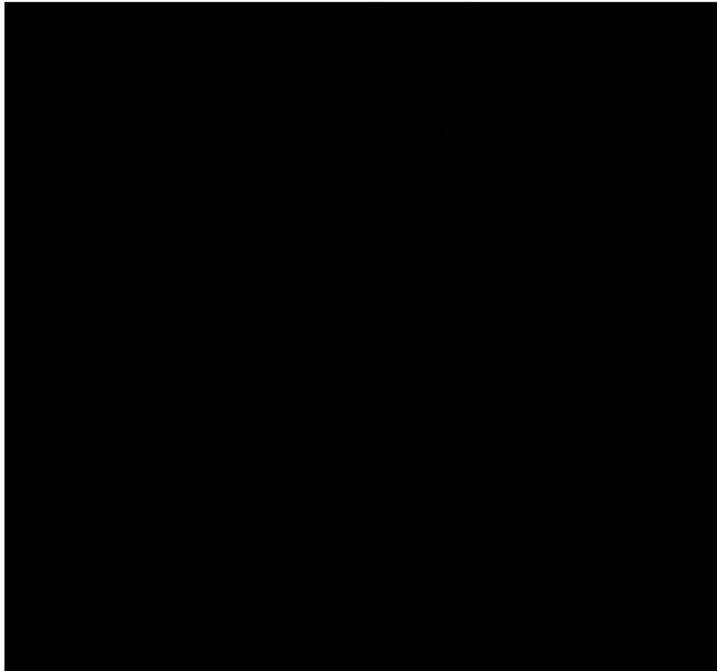
- Axisymmetric configuration: **toroidal** (donut) shape with nested flux surfaces.
- plasma confined by superposition of 2 magnetic fields:
 - Toroidal** field generated by external coils
 - Poloidal** field generated by current in plasma



EPFL Why Tokamaks? Record of produced energy at JET

JET, EU, Dec 21st, 2021

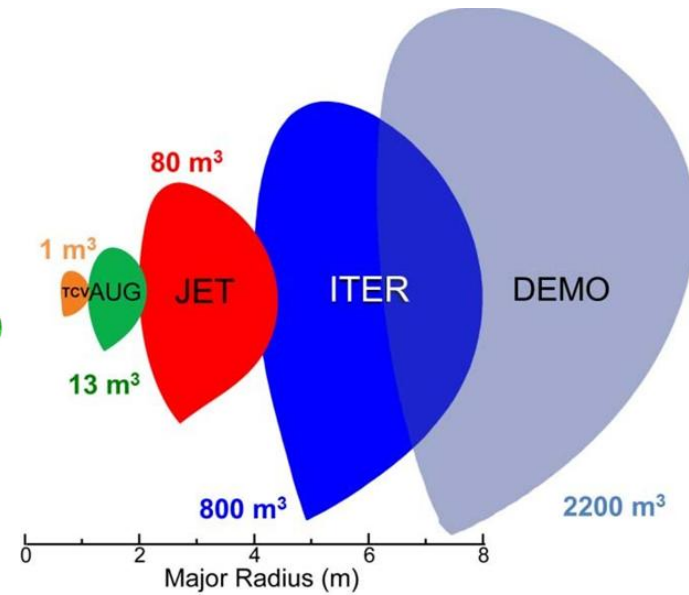
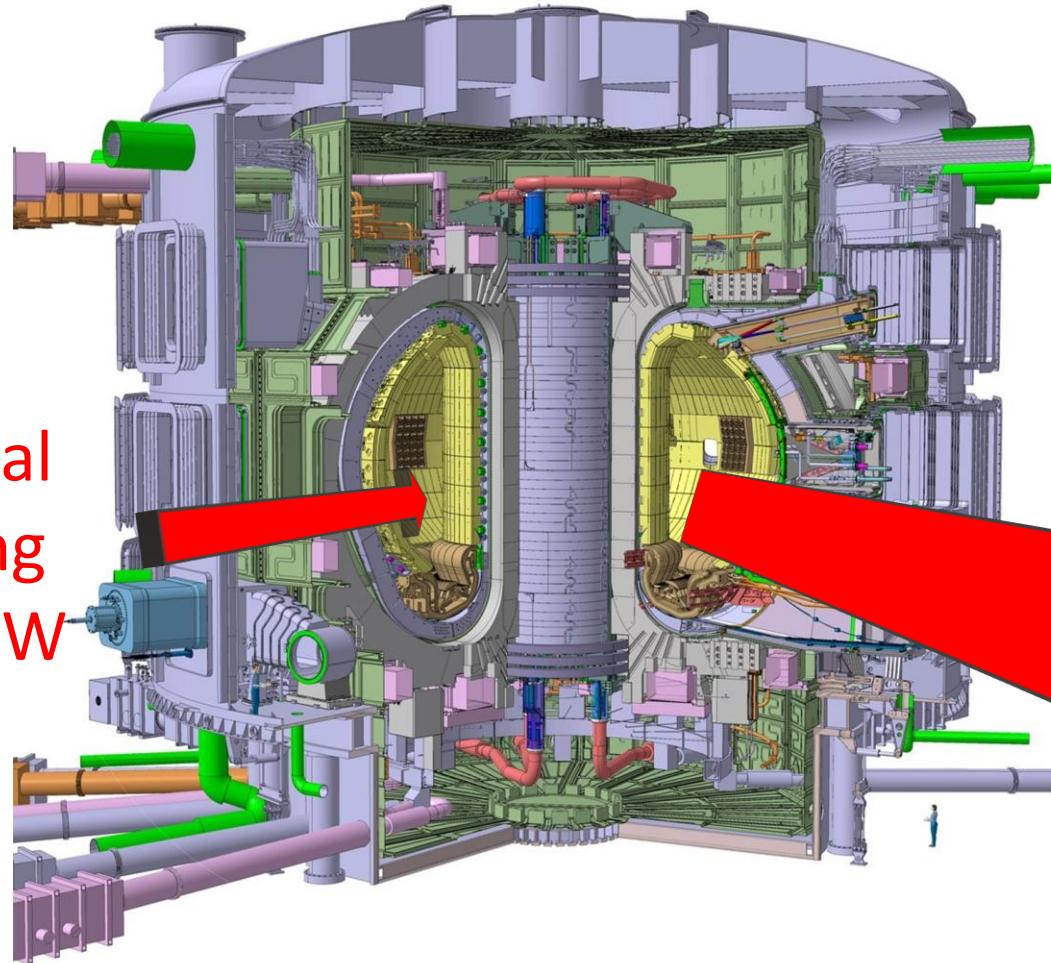
**59 MJ
for 5s!**



ITER, feasibility of fusion energy



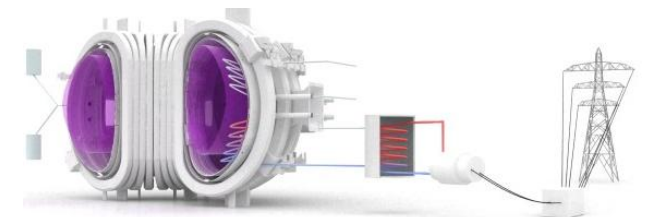
External
Heating
~50 MW



~500 MW

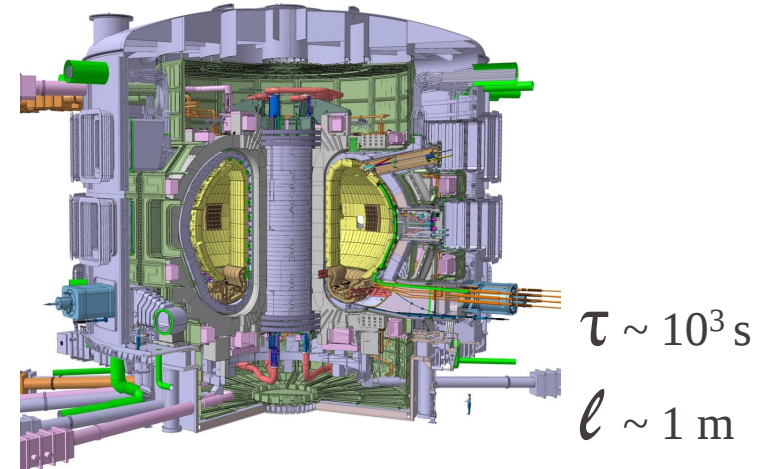
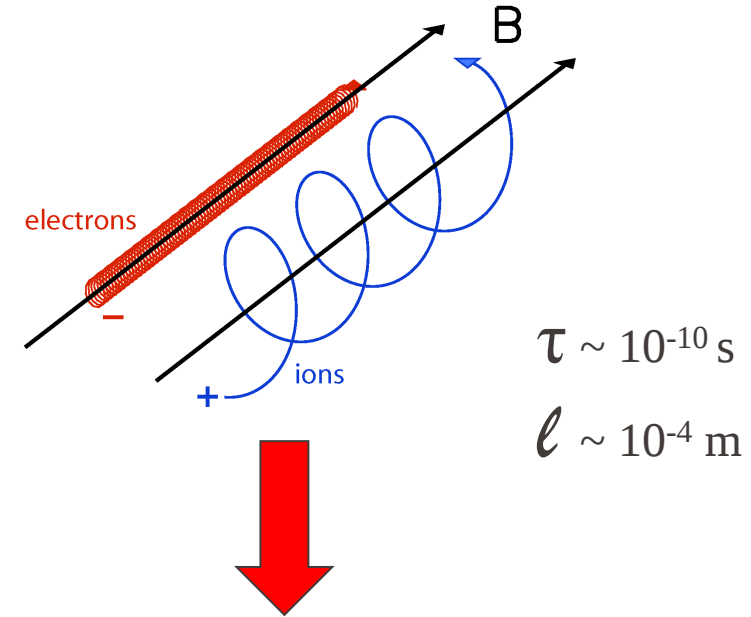
~1g of fuel in 840m³!

The step before DEMO
(demonstration fusion reactor)

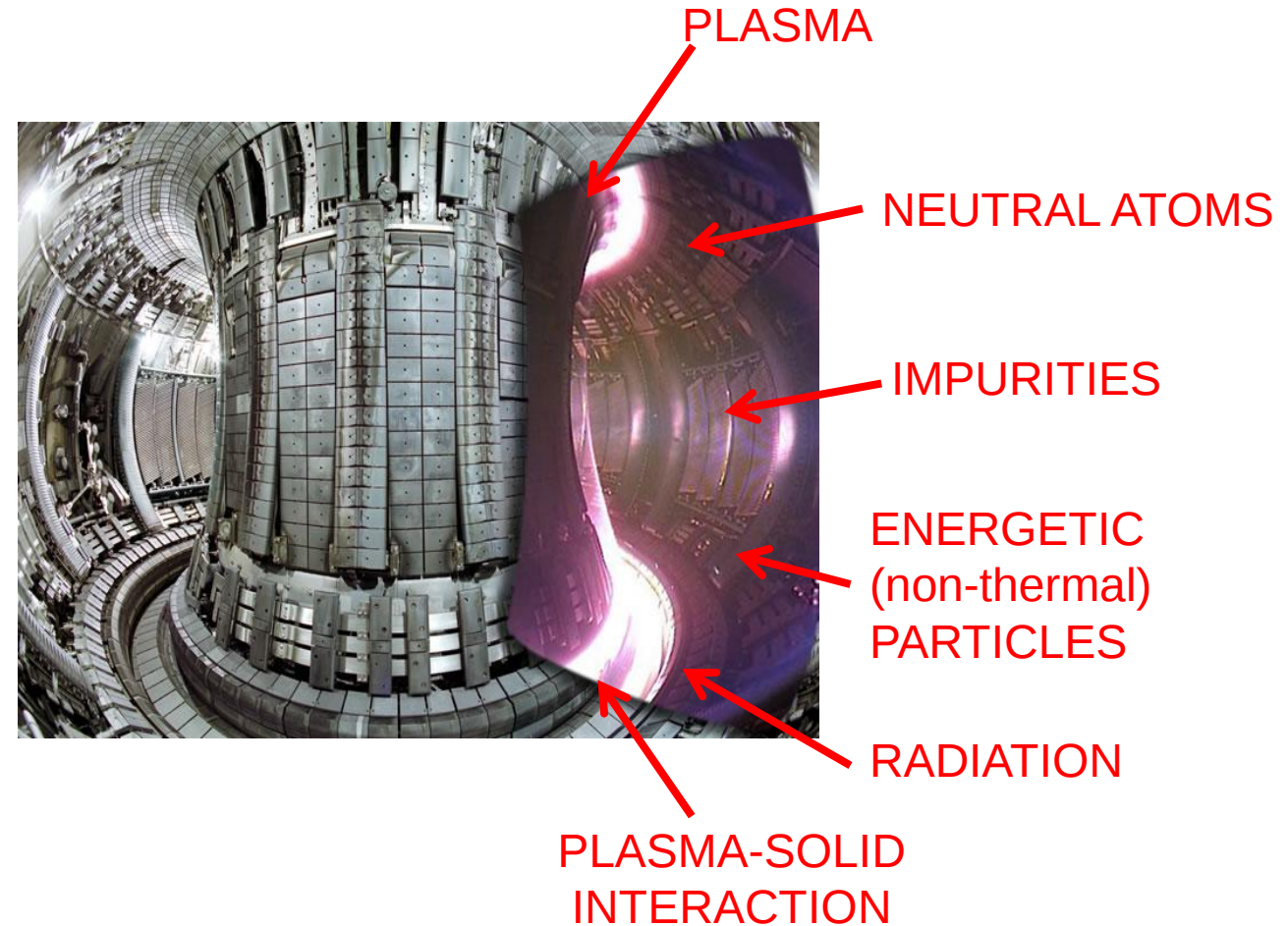


Simulations and control in fusion: a fascinating challenge

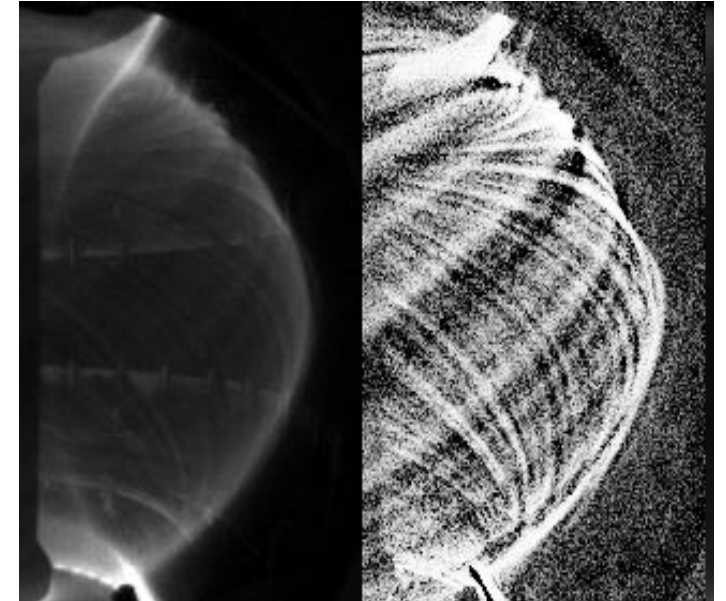
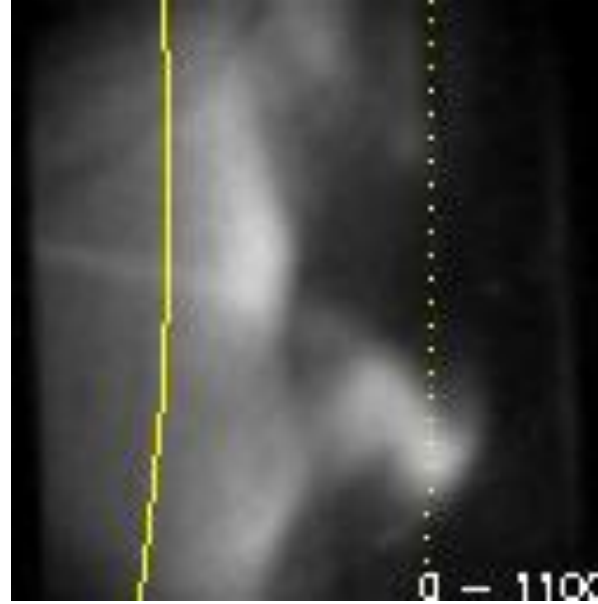
- Multiscale
- Multiphysics
- Intrinsic nonlinearity
- Turbulent dynamics
- Extreme anisotropy
- Complex geometry



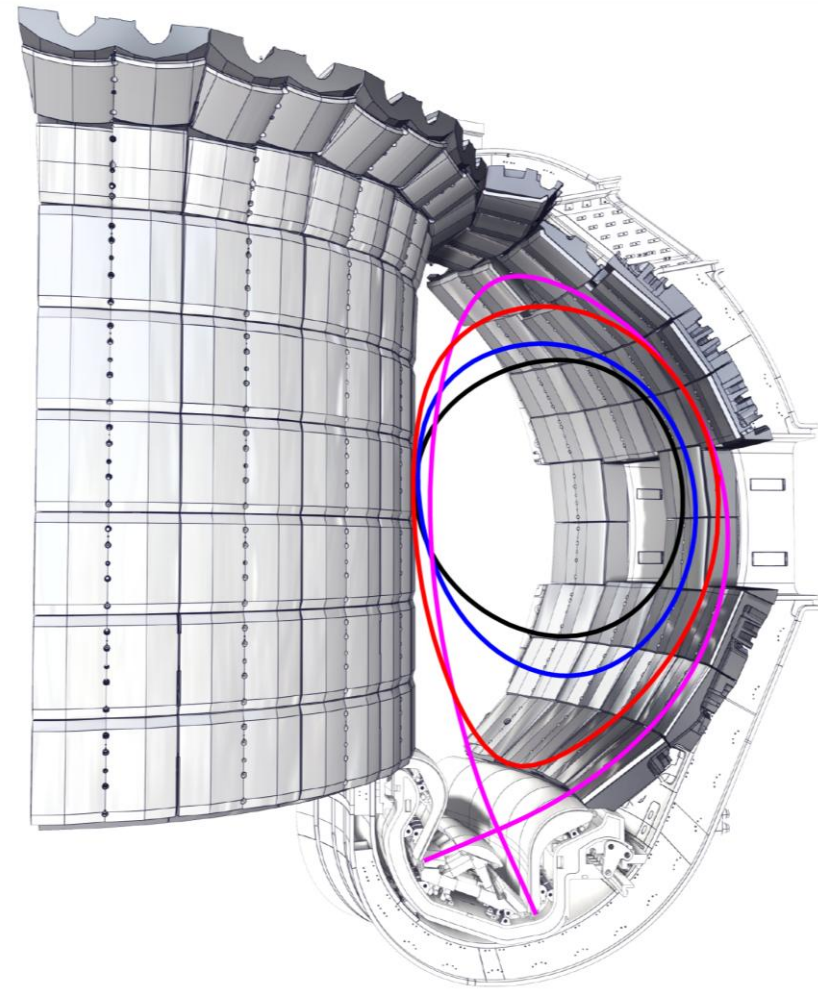
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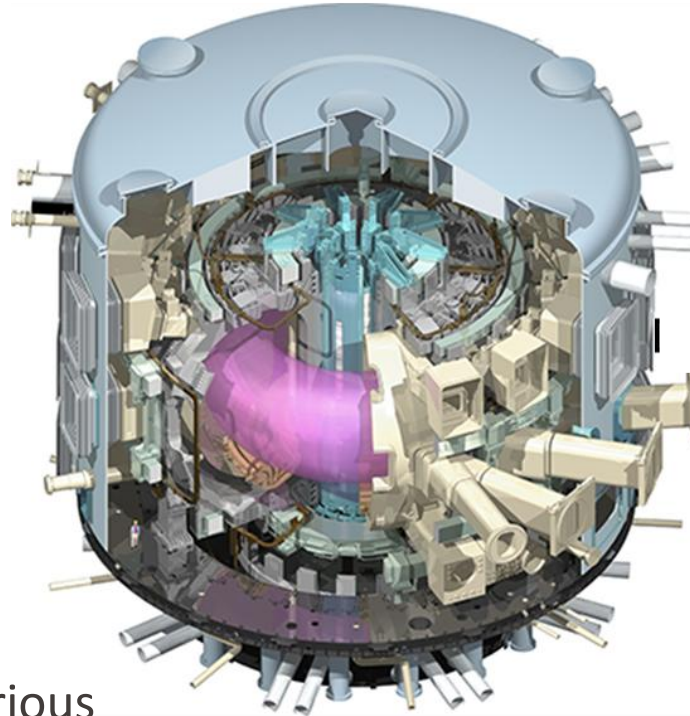
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- Extreme anisotropy
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Data in fusion: another challenge

■ **Tokamaks** are one of the most complex system in nature...

■ **Massive amount of data** (Big data – 2PB/day at ITER, high bandwidth diagnostics)

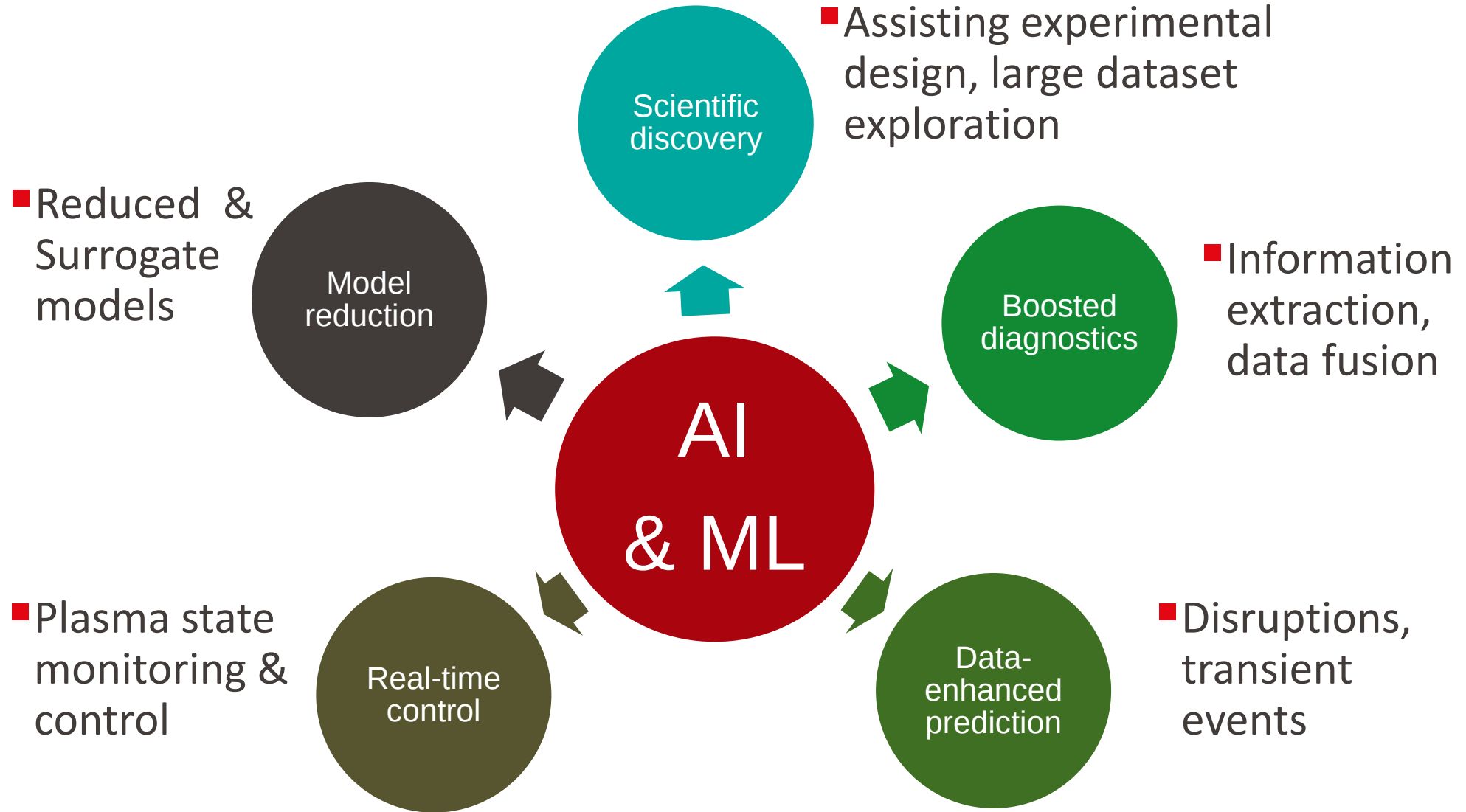


■ **High-dimensionality** (many diagnostics measuring various plasma properties)

■ **Heterogenous** (various formats, facility dependent data ecosystem)

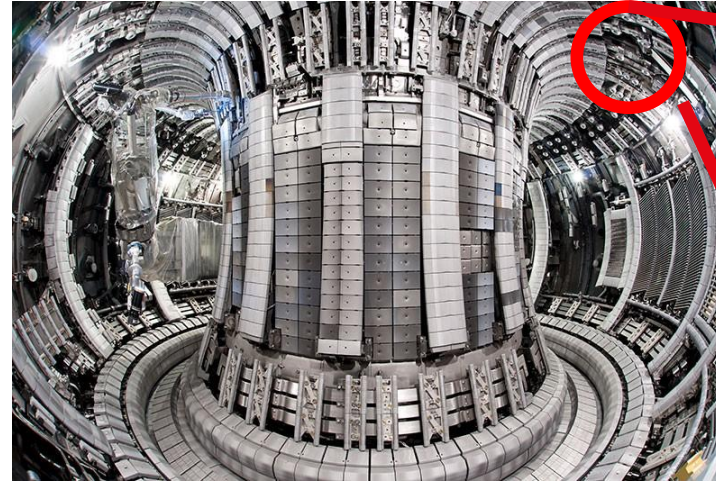
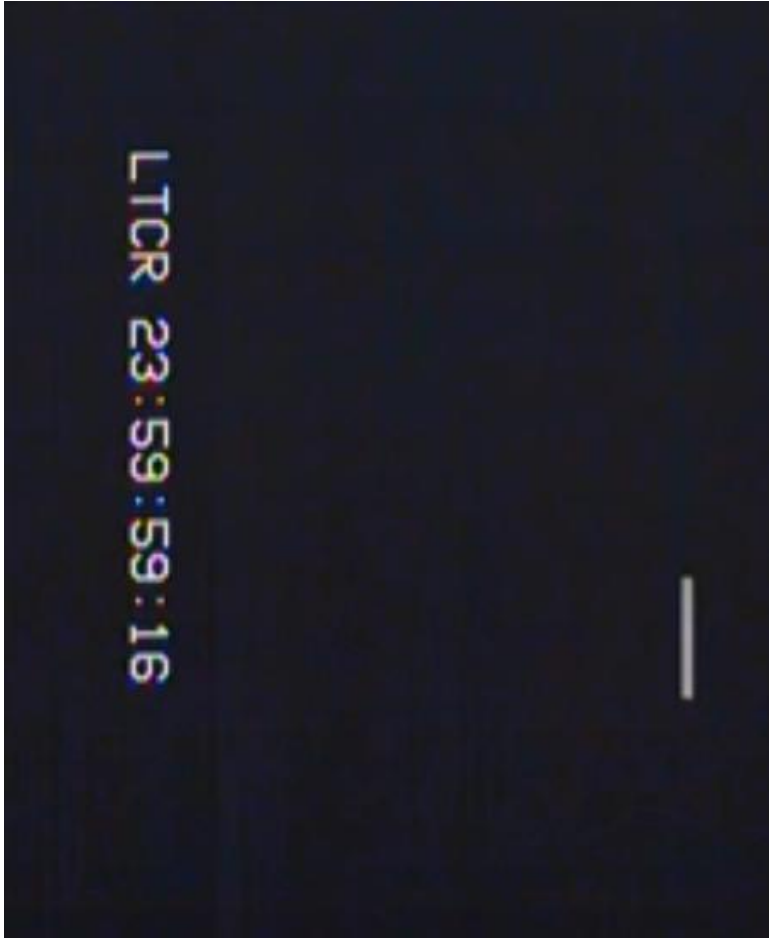
■ **Multi-scales, multi-physics** (integrated tokamak modeling)

Advancing fusion with ML & AI

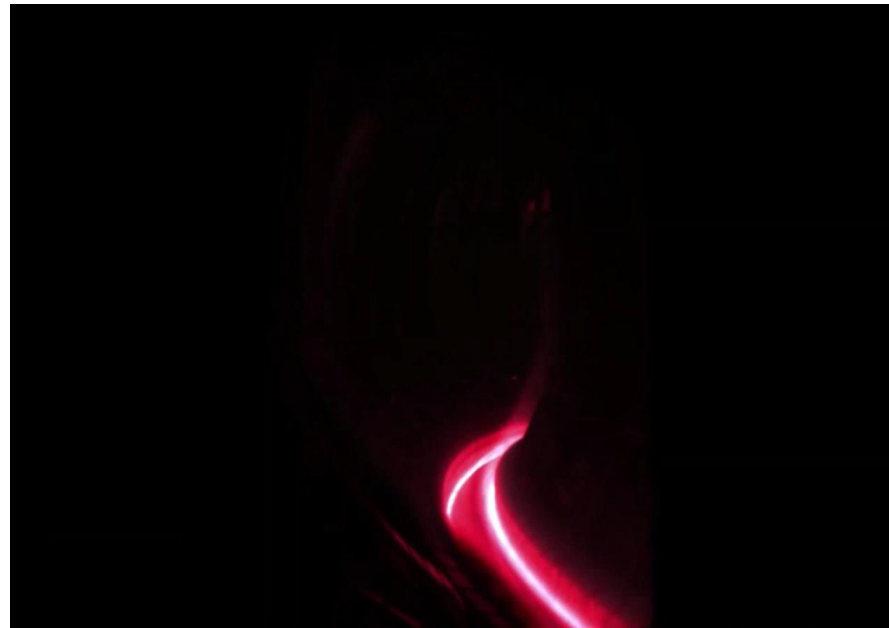


Thermal loads & catastrophic losses of confinement

A. Pau | RL4AA 2025 | Hamburg, 3rd April. 2025



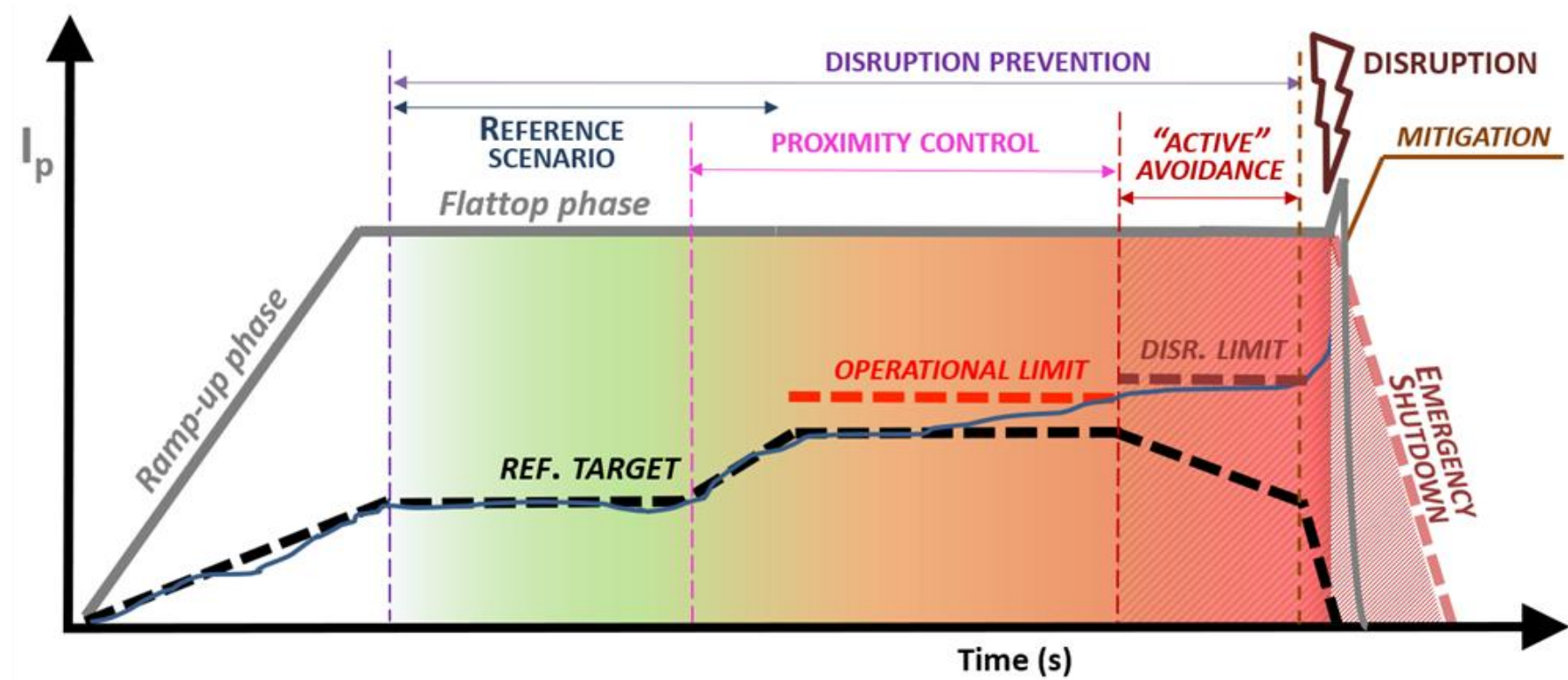
Possible serious
damage to ITER
structure



Continuous control and disruption prevention

DISRUPTION PREVENTION

a key requirement for plasma control throughout the entire evolution of the discharge

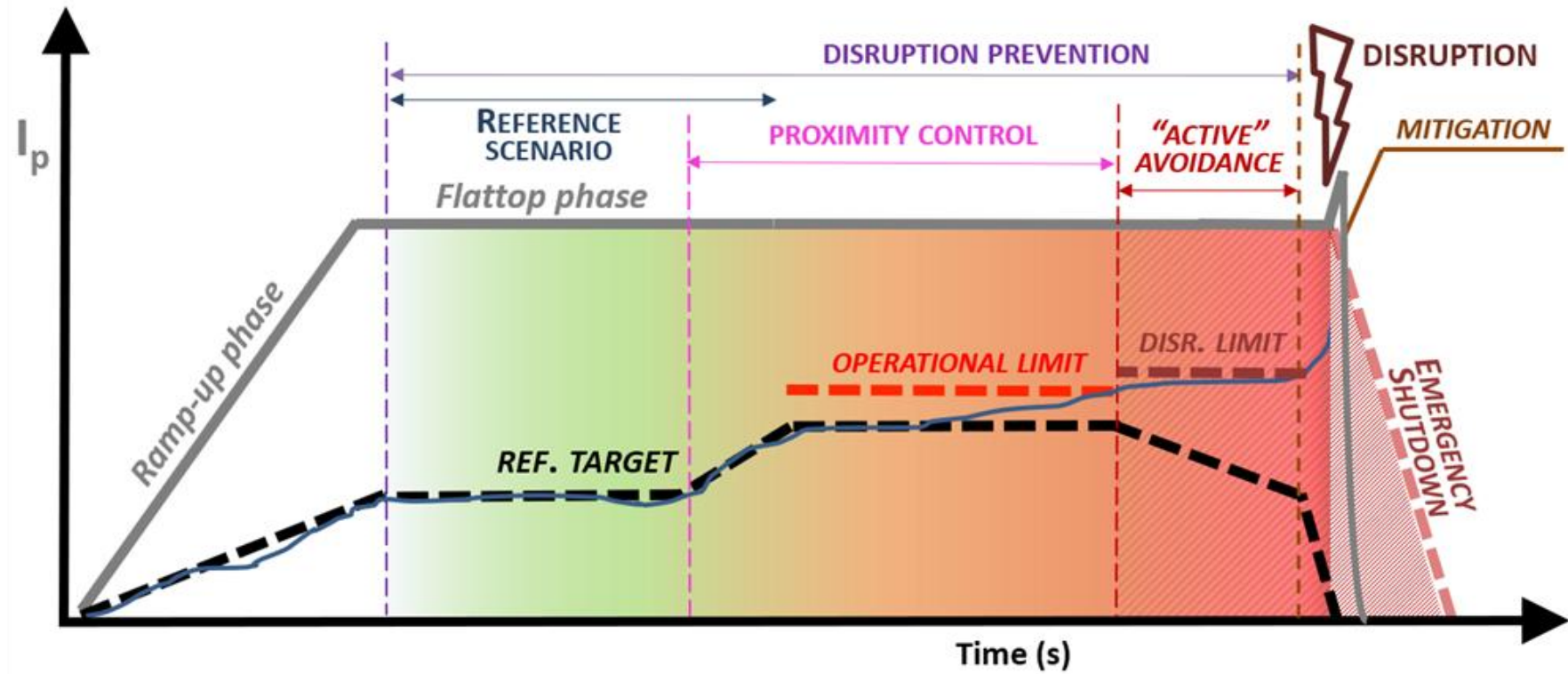


REF: [A. Pau et al IAEA TM on Disruptions 2020]

REF: [J. Barr et al IAEA TM on Disruptions 2020]

DISRUPTION PREVENTION

Break down in different “control phases”:



REF. SCENARIO

- keep the target scenario stable again disturbances (ST, ELM, MHD modes, etc.)

PROXIMITY CONTROL

- keep stability while pushing performance by regulating proximity to stability & controllability boundaries

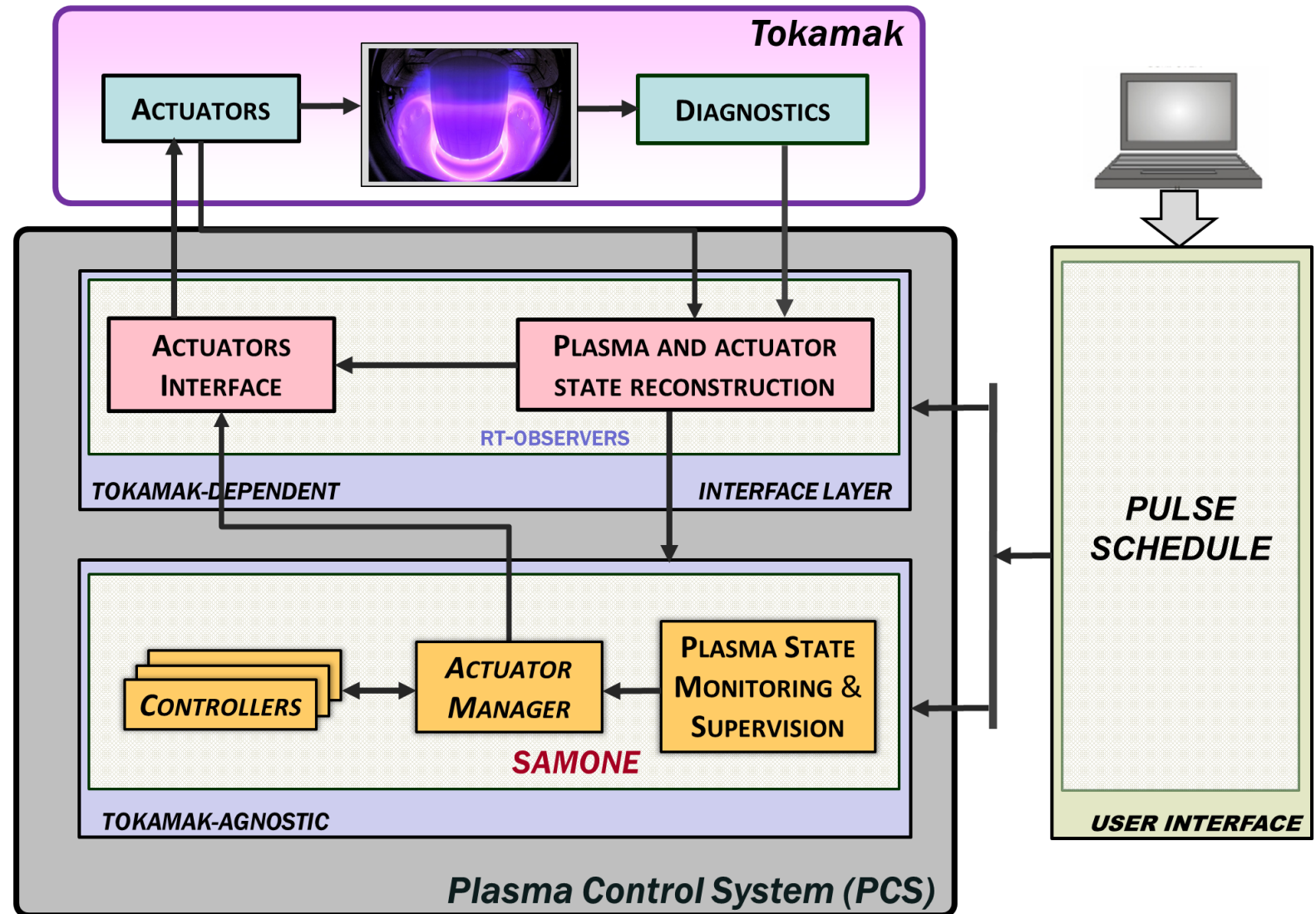
ACTIVE AVOIDANCE

- asynchronous response when crossing operational boundaries (danger levels)

EMERGENCY SHUTDOWN

- Fast controlled shutdown
- mitigation

- Separation of tokamak **dependent** and **agnostic** layers
- **Generic** implementation
- **Flexible** framework allowing easy **maintenance** and **upgrade**
- Concepts of **integration** and **portability**

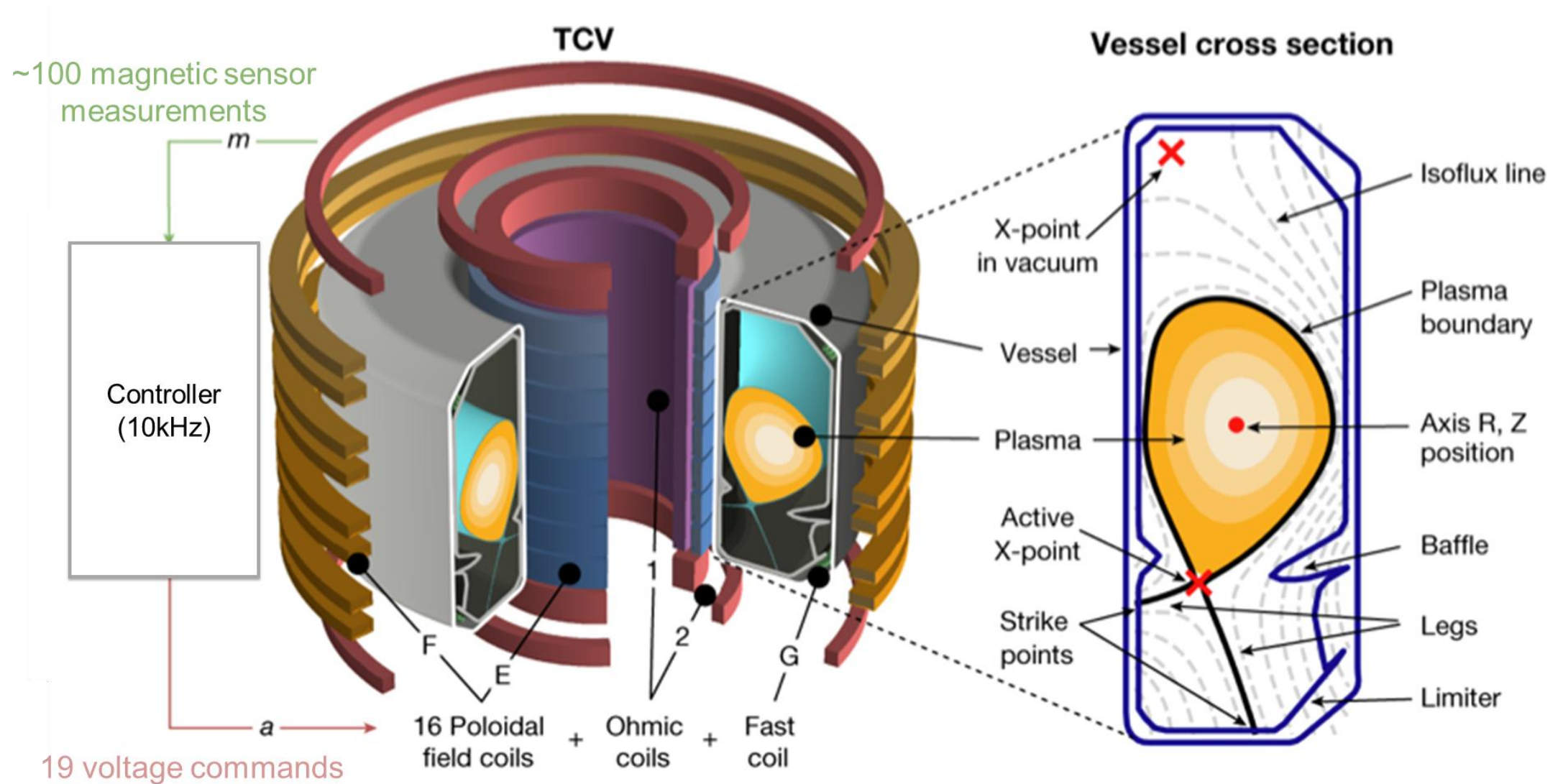


REF: [T. Vu et al. IEEE TNS 2021]

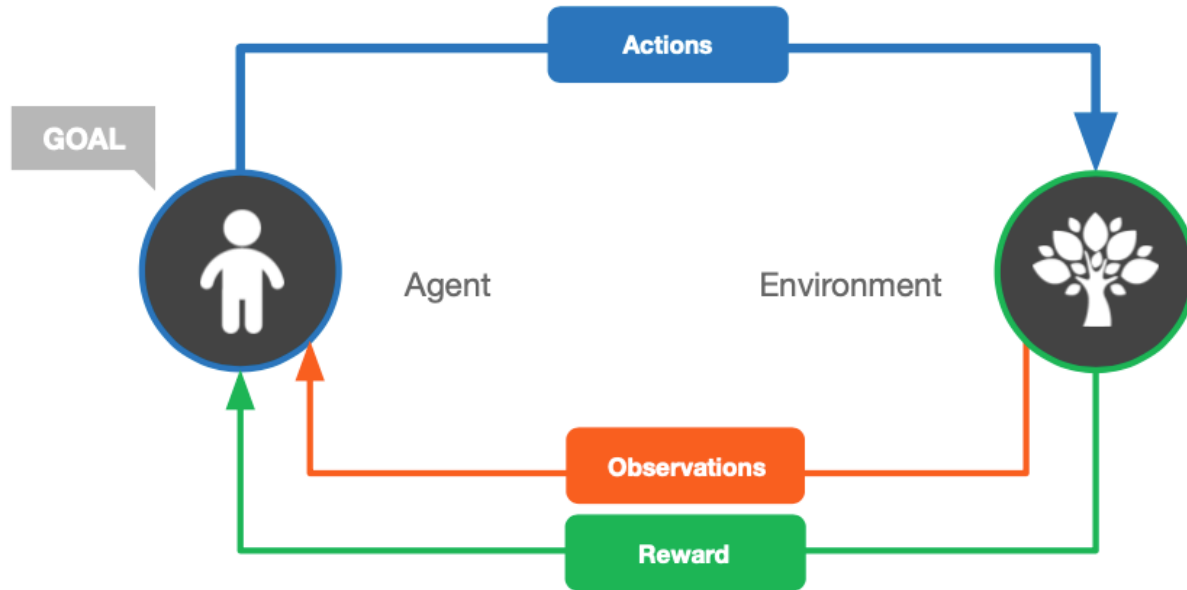
REF: [F. Felici et al. IAEA 2021]

REF: [C. Galperti et al IAEA TM on Plasma Control Systems 2021]

Plasma control by deep reinforcement learning



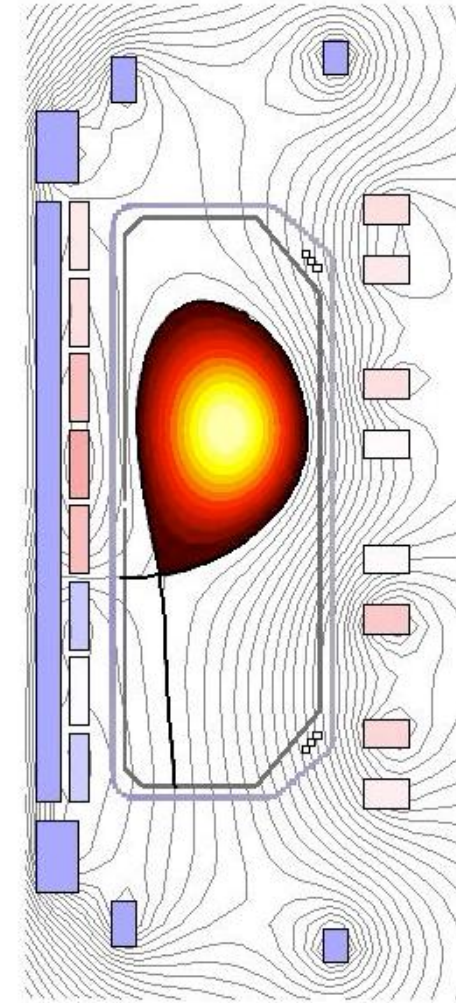
Plasma control by deep reinforcement learning



[Figure and RL slide material from hereon: courtesy A. Abdolmaleki]

- Agent tries to learn a **control policy** mapping states (observations) to actions
- **MPO: Actor-Critic RL** implementation for continuous-valued states
- **Deep RL**: recurrent architecture to efficient model of long-range dependencies (plasma dynamics)

TCV Free-boundary simulator



Plasma control by deep reinforcement learning

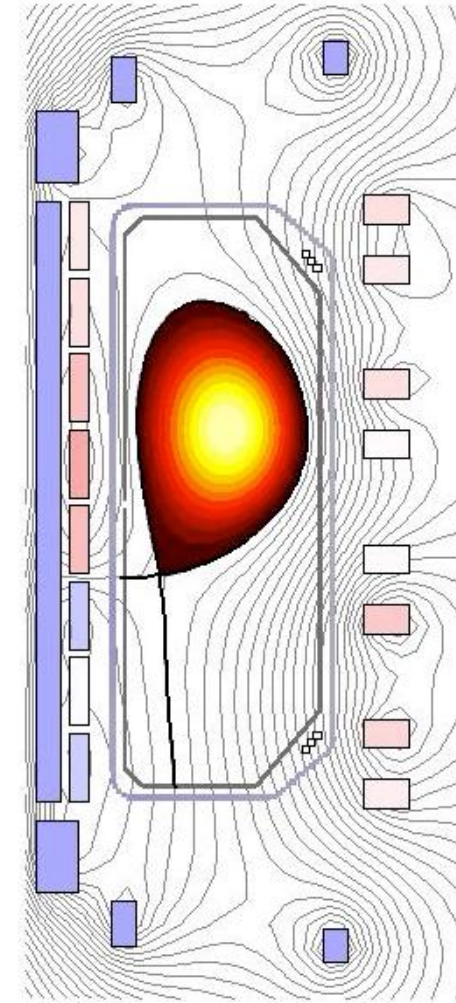
- **Free-boundary simulator** for the Tokamak magnetic equilibrium

- Solve coupled system of equations:
 - **Circuit equations** for time evolution of currents, coupled equations for *Coils*, *Passive conductors* (vessel), *Plasma*
 - **Grad-Shafranov equation** (ideal MHD force balance: 2D static, elliptic PDE) to determine plasma equilibrium depending on external currents and internal constraints (provided)
- Typically, **~hours for simulating** a few seconds discharge (50,000 steps / s) of plasma evolution.

- **What we need to control:**

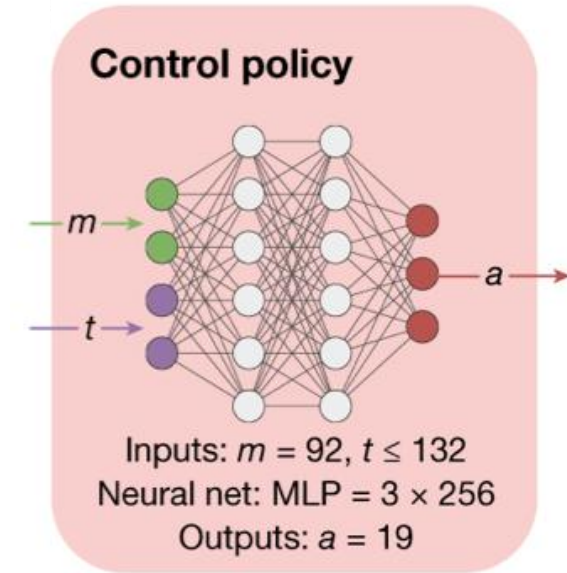
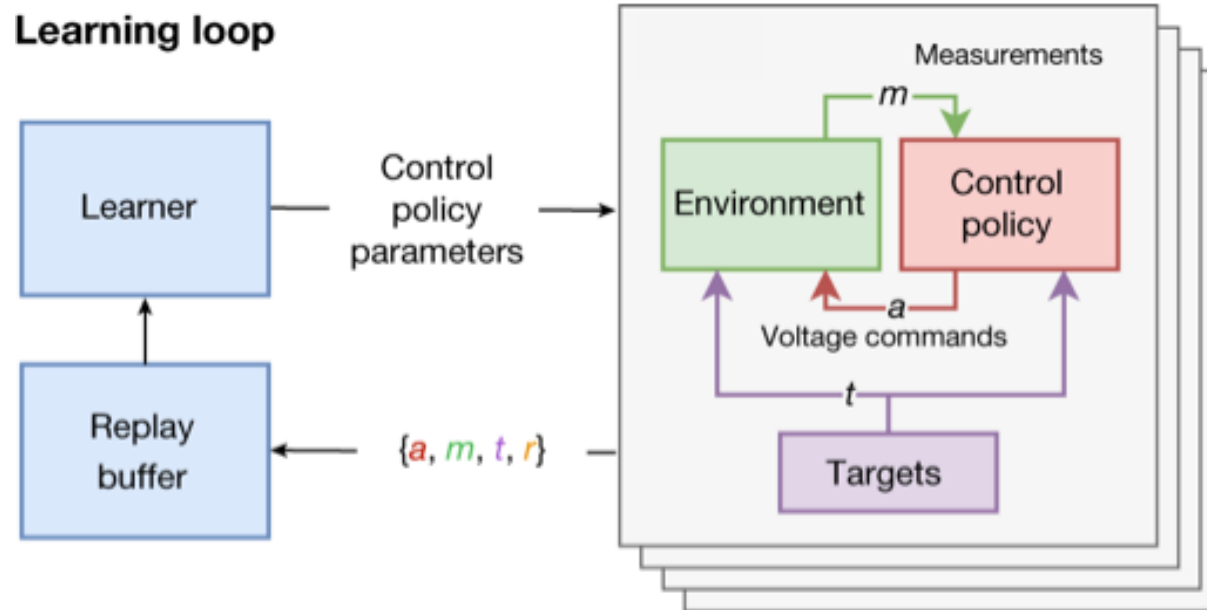
- Total plasma current I_p ; Radial position R
- Vertical position Z ; Plasma shape (**LCFS**, etc.)

- **TCV Free-boundary simulator**



Plasma control by deep reinforcement learning

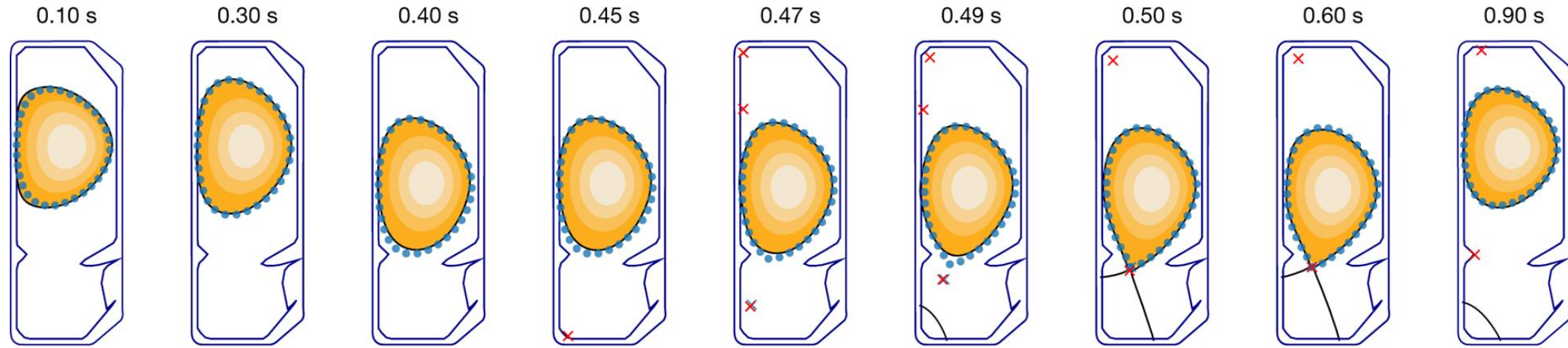
- **MPO: Actor-Critic RL** implementation for continuous-valued states
 - Stable (constrains deviation from the current policy)
 - efficiently explores **continuous state-action spaces**
 - Efficient data sampling
 - Robust against **uncertainties**
- **Distributed implementation:** many actors run in parallel...
- **Off-policy:** also use data generated using previous policies



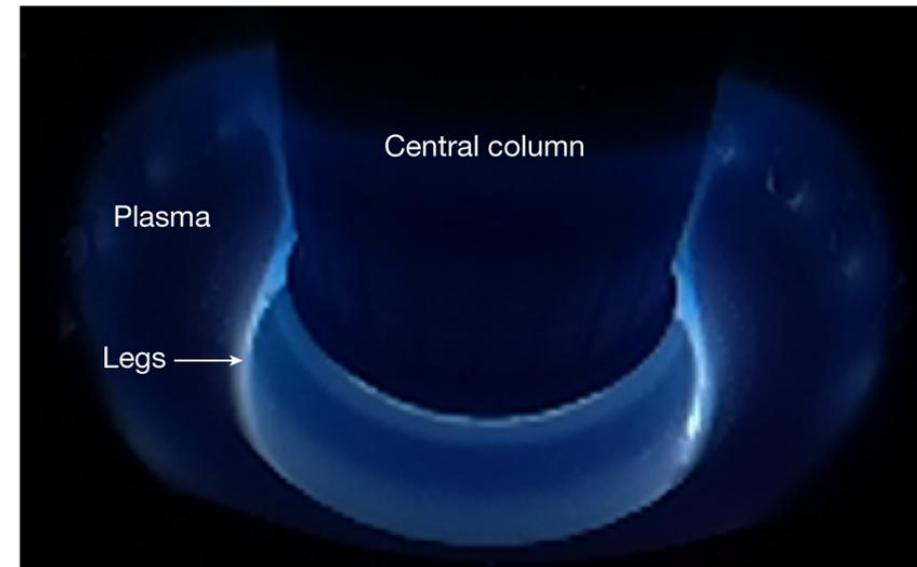
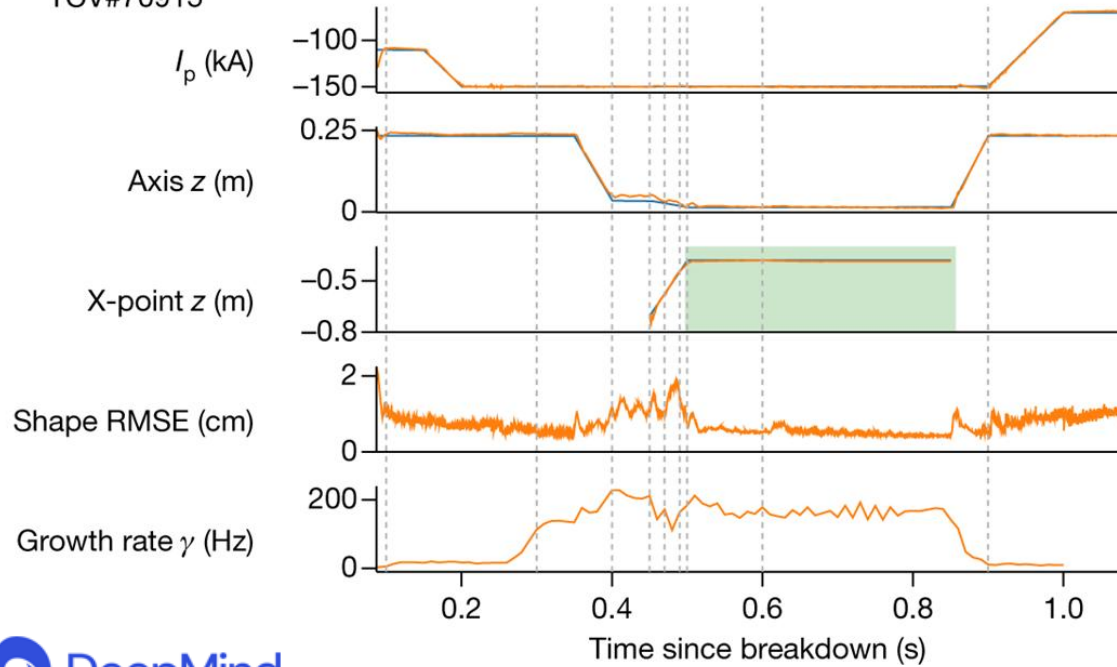
Actor: learns the control **policy** π (taking policy gradients on the Q function learned by the critic) -> “**small**” **feedforward NN**

Critic: learns the **Q function** from the data generated by the interaction of the actor(s) with the environment (estimates expected cumulative future rewards) -> **deep recurrent NN**

Plasma control by deep reinforcement learning



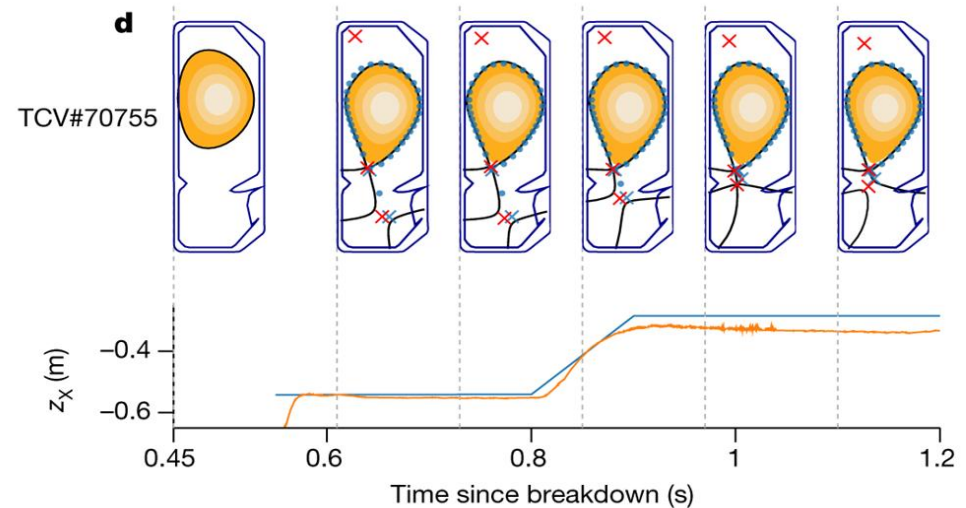
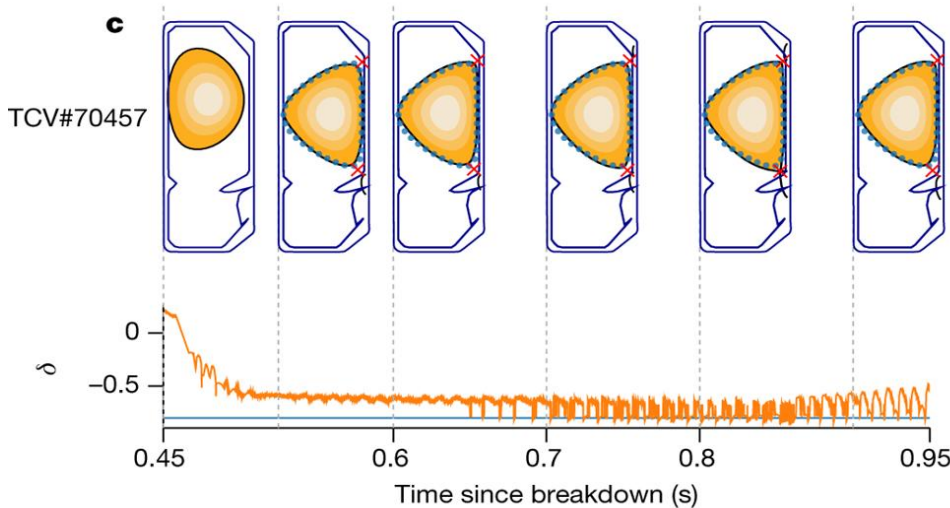
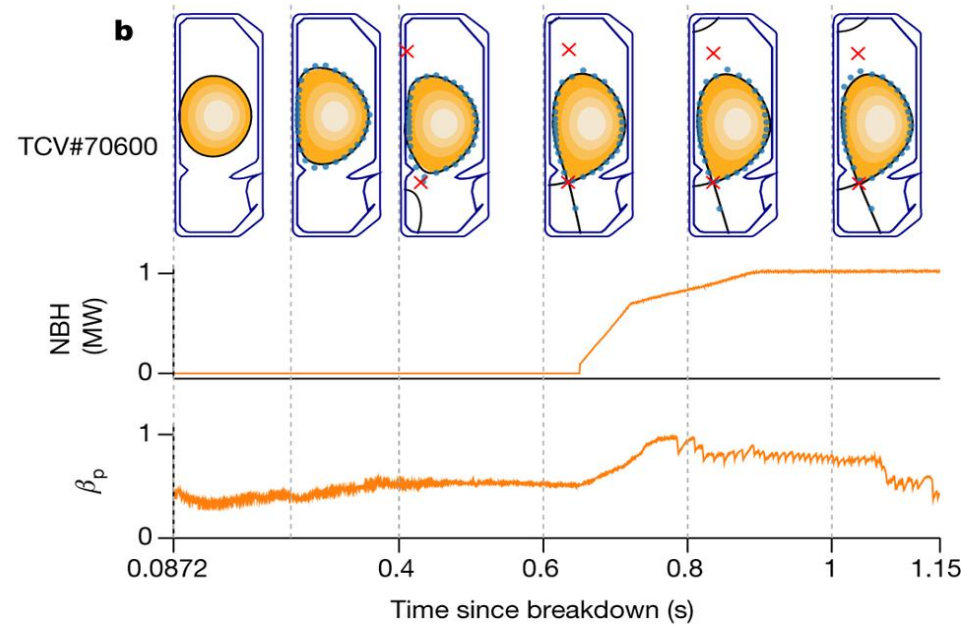
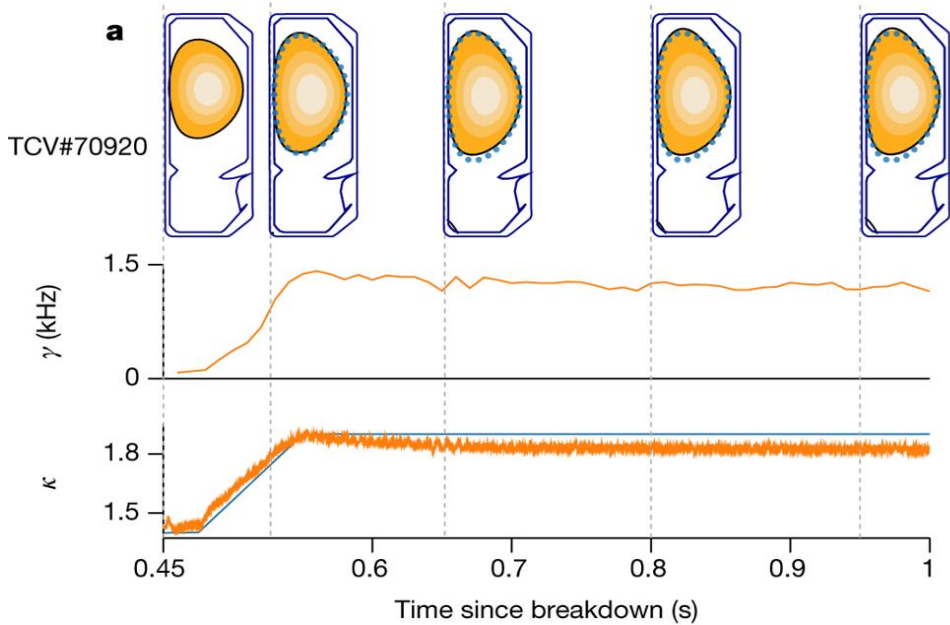
TCV#70915



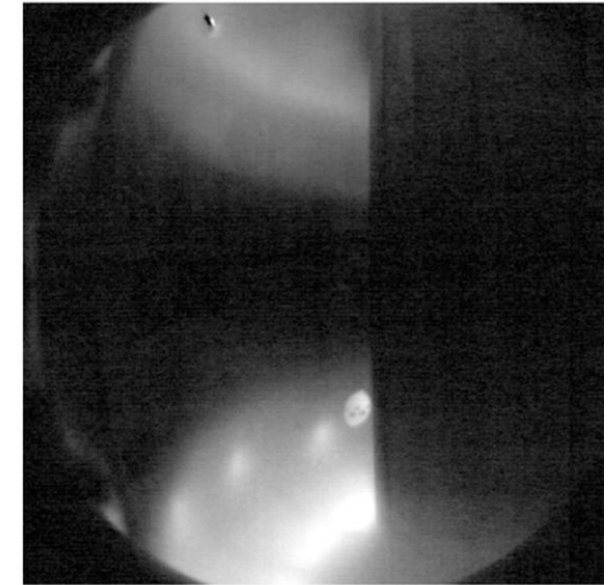
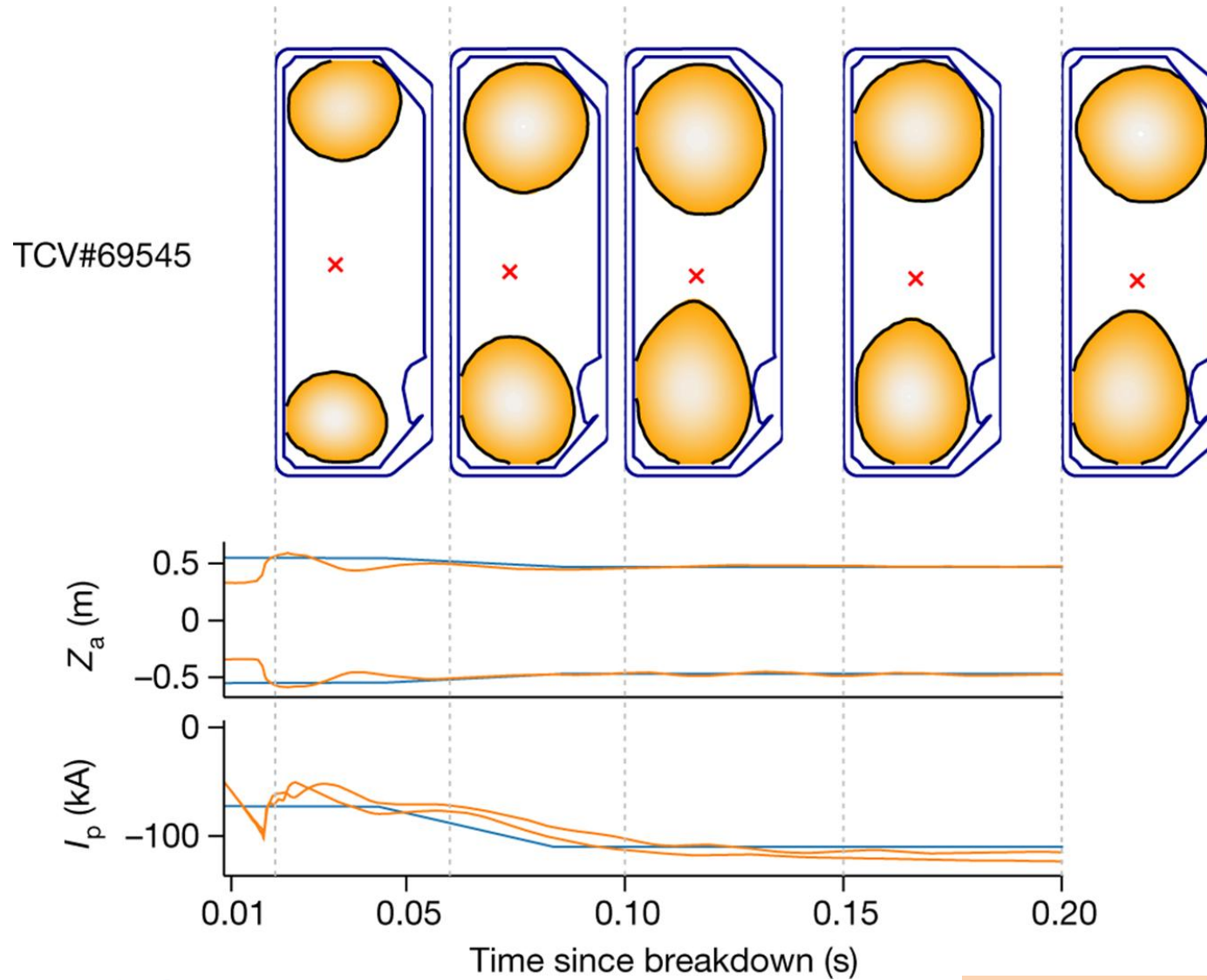
Inside view at 0.6 s

REF: J. Degraeve, F. Felici et al., *Nature*, vol. 602, no. 7897, pp. 414–419, Feb. 2022

Plasma control by deep reinforcement learning



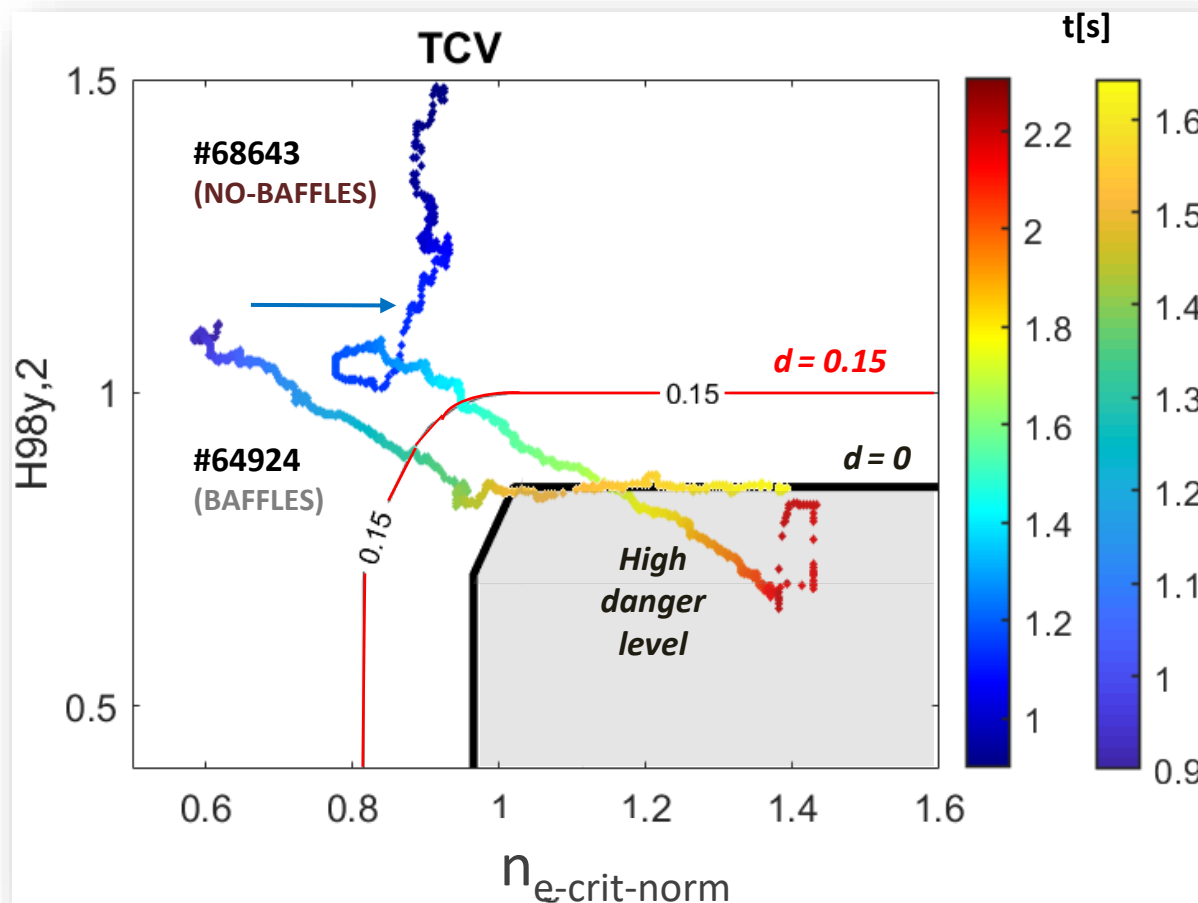
Plasma control by deep reinforcement learning





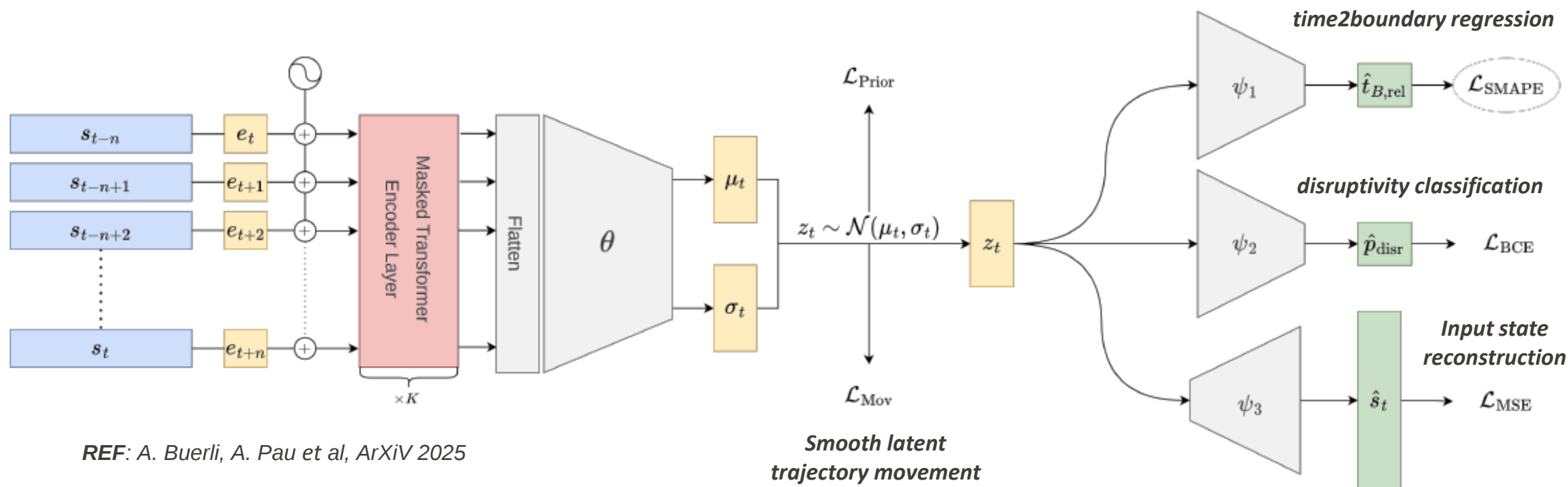
DISRUPTION

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Center



- **High-performance Density Limit** dynamics described through trajectories in a physics-based “state space” [$H_{98y,2}$ - $n_{e-crit-norm}$]
- **Reduced set of variables** to describe the relevant system dynamics... but sometimes the operational space is complex and high-dimensional (hidden factor, etc.)

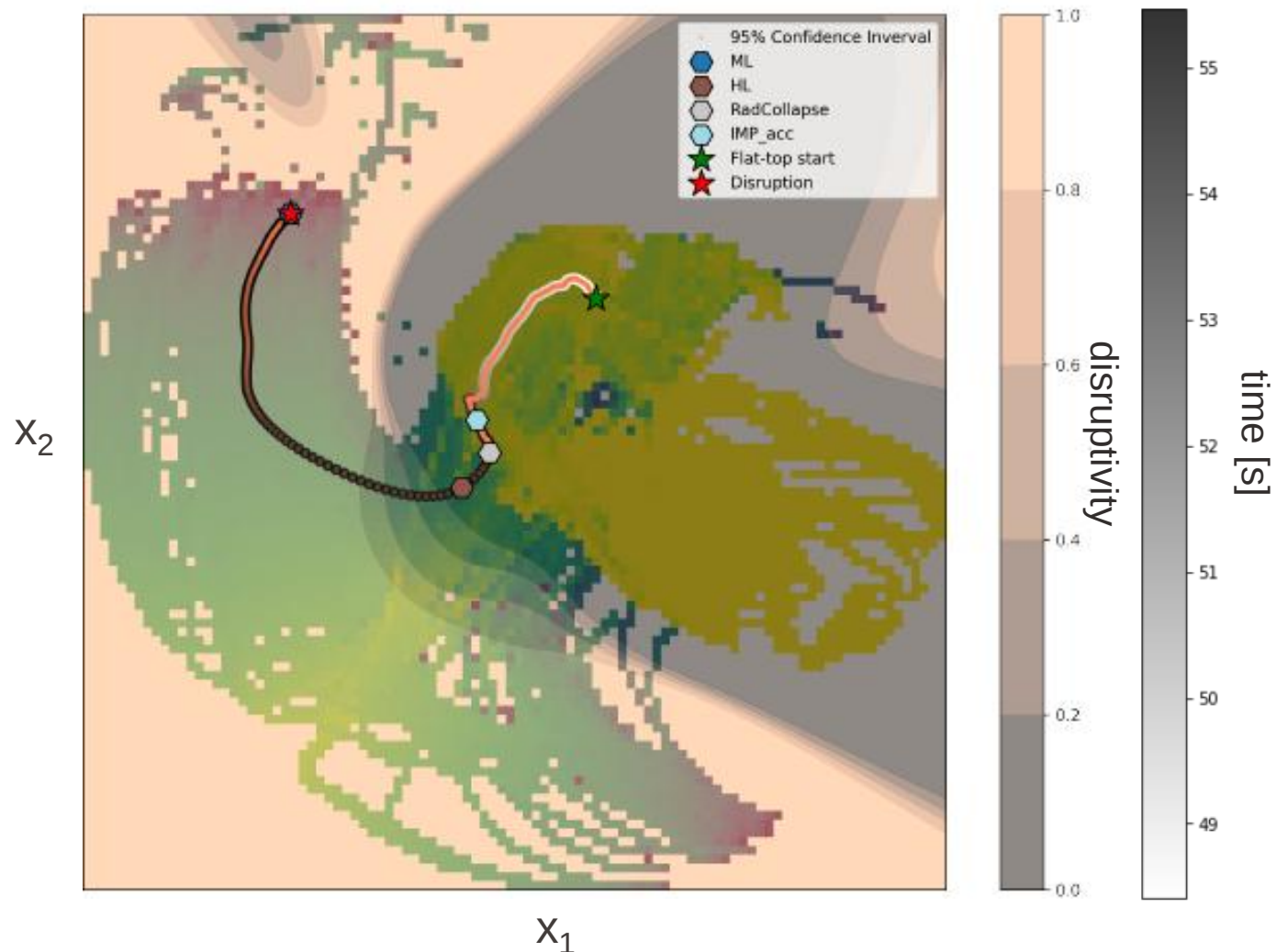
- **Trajectory** allows mapping the distance from operational/disruption boundaries to **probabilities of transition** to specific **states** (occurrence of an **event**)



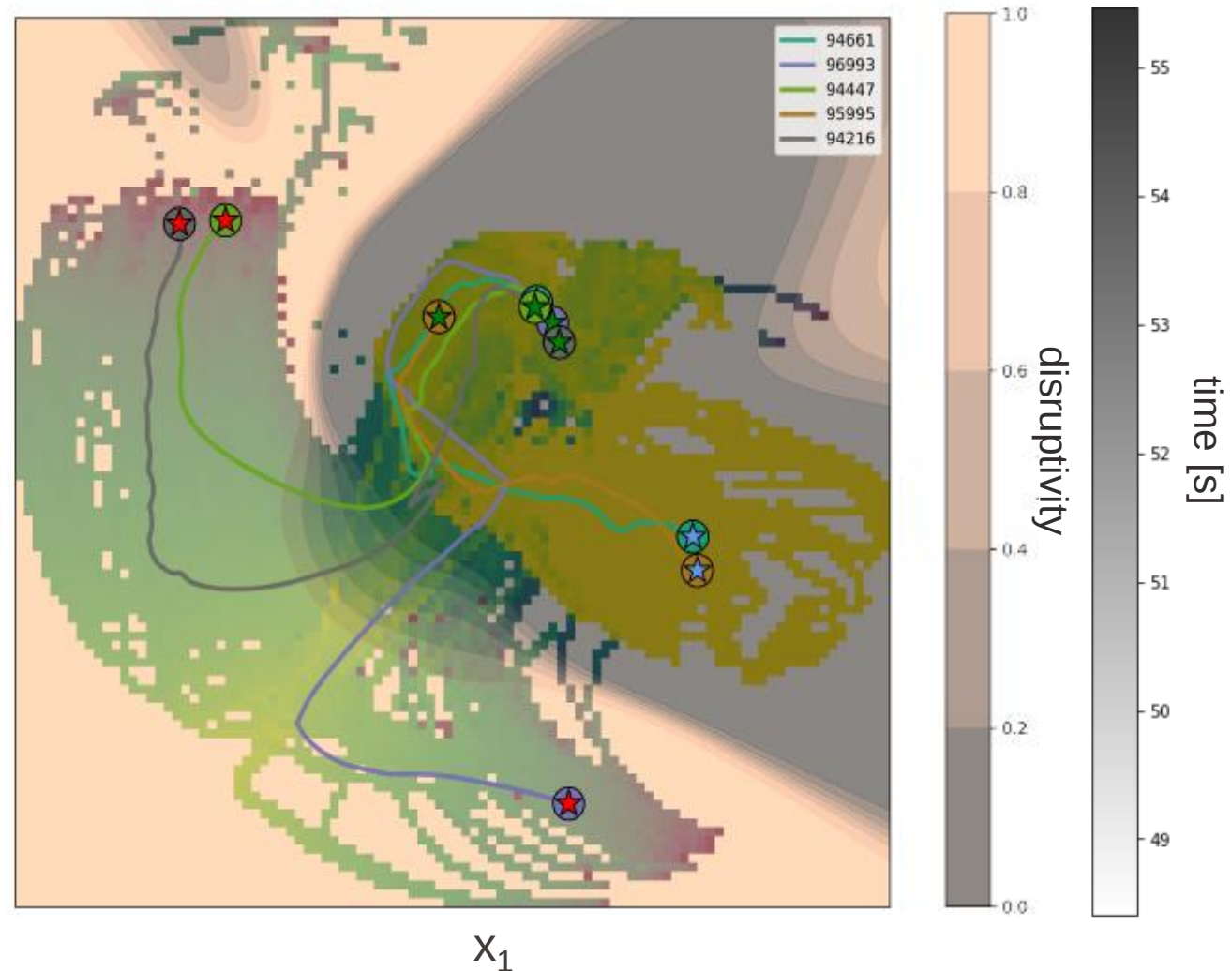
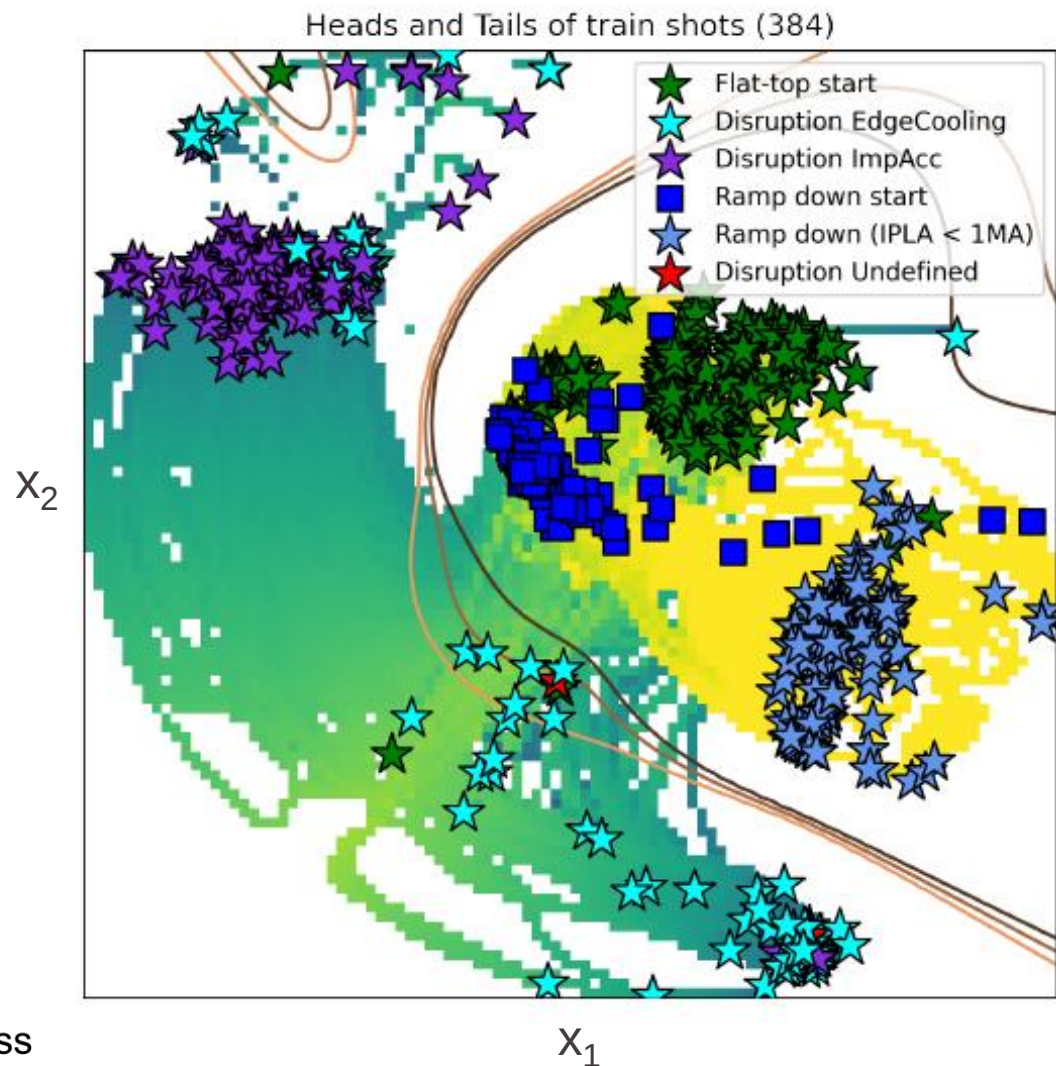
- **Sequence-based** model: a variational autoencoder (transformer, GPT-alike architecture) leveraging **multi-task learning**.
- **Multi-task learning**: by learning tasks jointly (supervised and unsupervised), the model can discover common features or structures across tasks (shared representation).

REF: A. Buerli, A. Pau et al, paper submitted

- Discharge **plasma state evolution** in time projected on the learned low-D latent space representation (zero-centred and with spherical edges).
- Smoother trajectories with **movement penalty**
- Two main and **diverging paths** along which the state can evolve towards the **boundary condition**, which corresponds to **two different disruptions dynamics** at JET



REF: A. Buerli, A. Pau et al, paper submitted

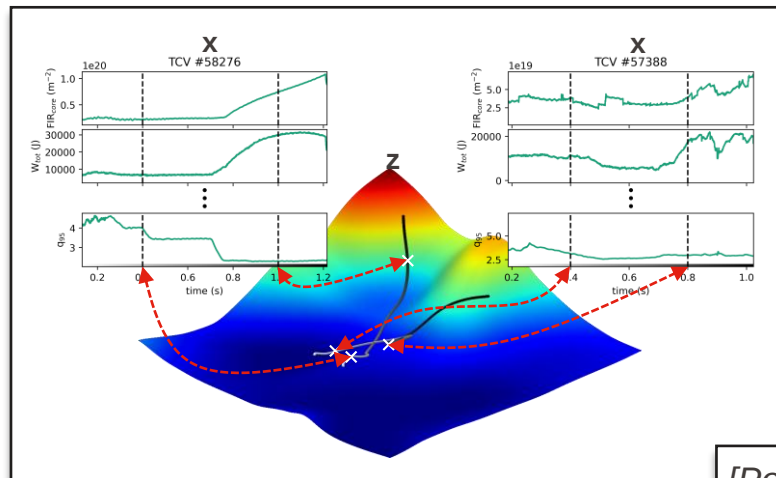


Latent variable models for disruption monitoring

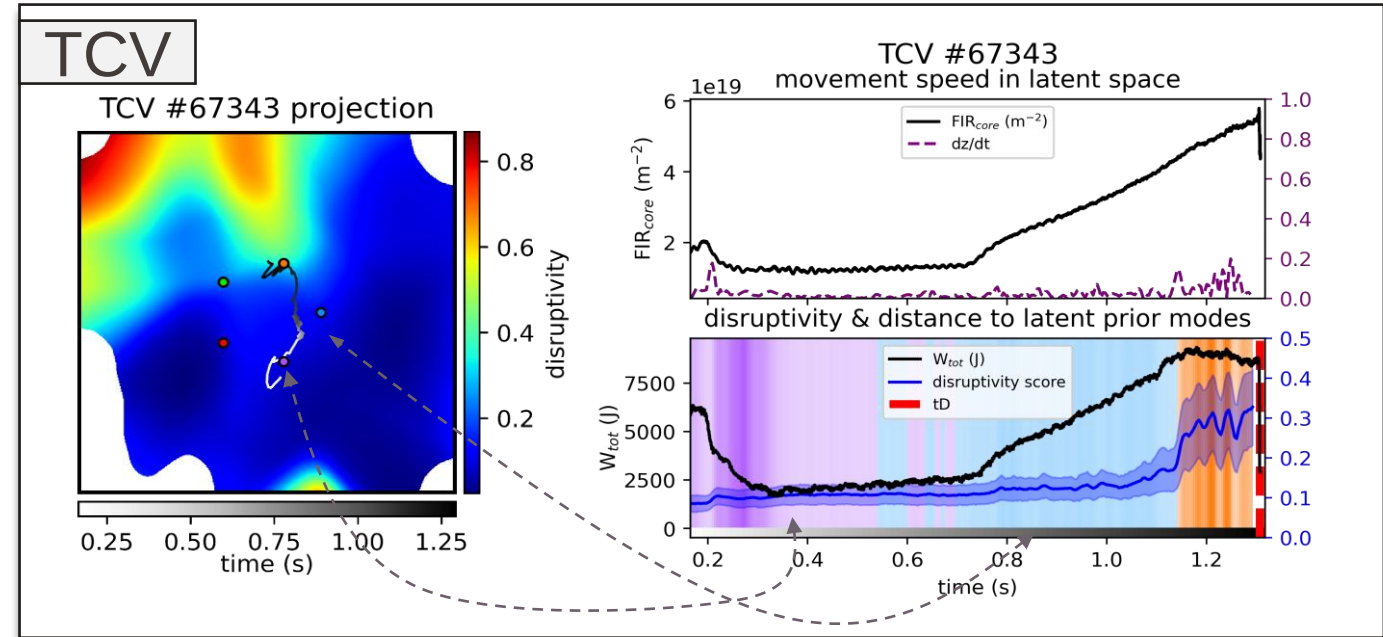
Sequential VAE with multimodal prior

- Project **disruptive boundaries** & physics quantities to inspect connections
- Project full discharges to track proximity to disruption
- Future: Investigate identified modes in posterior distribution*
- Future: Discretize projections as sequences of states*

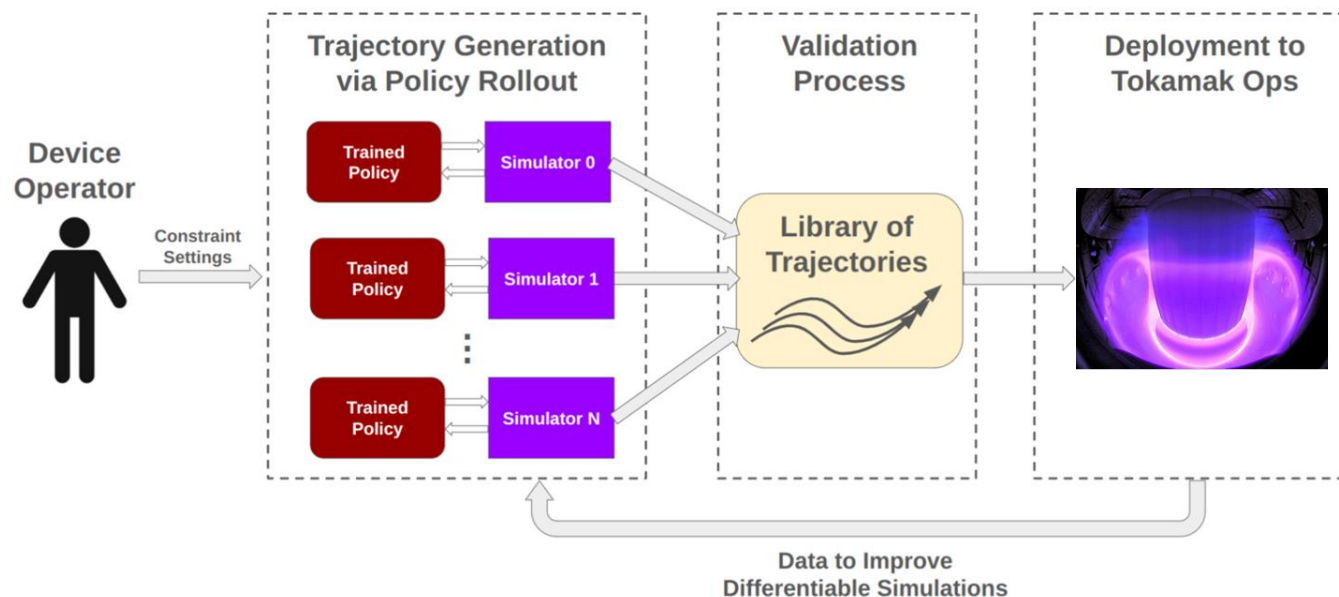
Swiss Data Science Center



[Poels et al. WIP]



- Scientific machine learning for building simulators that **combine physics + machine learning**
- Reinforcement learning to design **trajectories** and **controllers** to meet operator specifications that are robust to **physics uncertainty**



A. Wang, A. Pau, et al. Submitted to Nature Communications

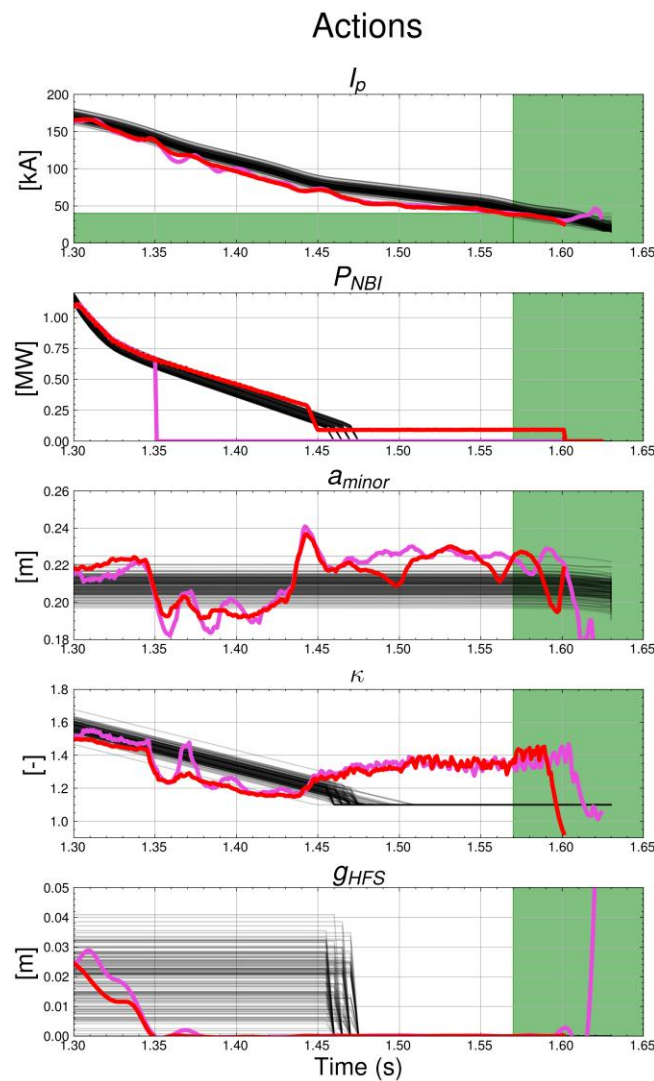
- Trajectory:** sequence of states, actions, and rewards that an agent experiences as it interacts with the environment.
- Neural State Space Models (NSSM)** to learn the temporal dynamics of some observed quantities in response to actions (physics structure and data-driven models).

Reward function

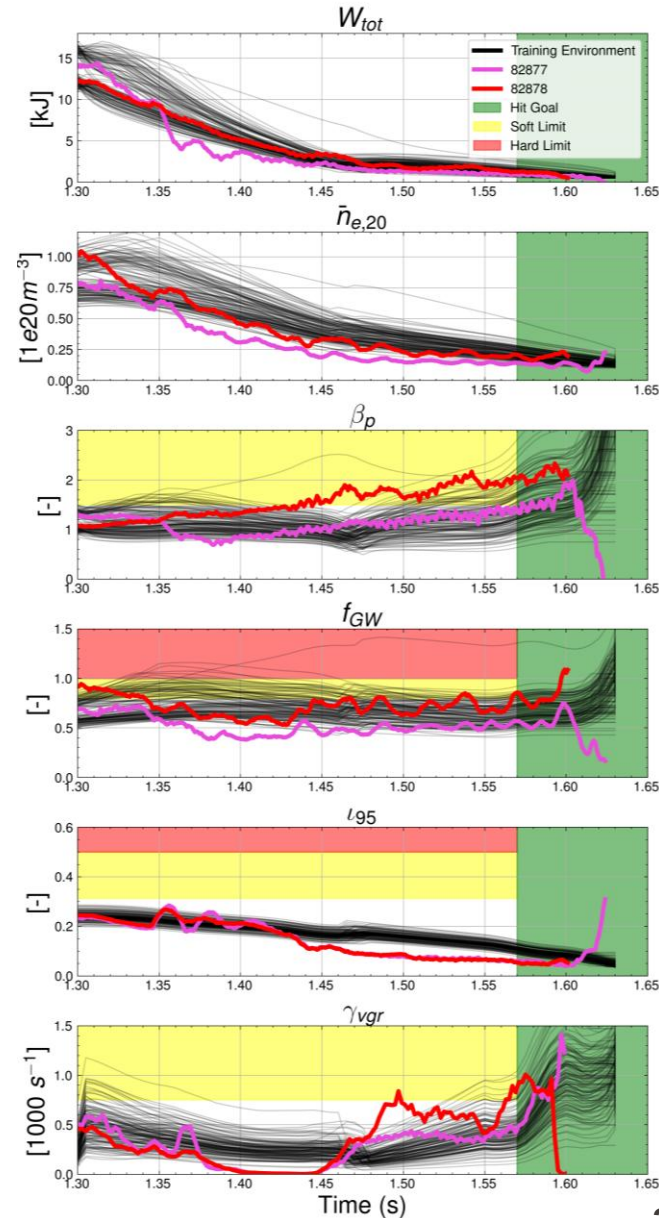
$$r(\mathbf{x}(t), \mathbf{a}(t)) = \underbrace{-c_{time}}_{\text{Penalty for time}} - \underbrace{c_W W_{tot}(t) - c_{I_p} I_p(t)}_{\text{Penalty for current and energy}} - \underbrace{\sum_{i=1}^{n_{soft}} c_{soft} s_i(\mathbf{x}(t))}_{\text{Soft chance-constraints}} - \underbrace{\sum_{i=1}^{n_{hard}} c_{hard} h_i(\mathbf{x}(t))}_{\text{Hard chance-constraints}}$$

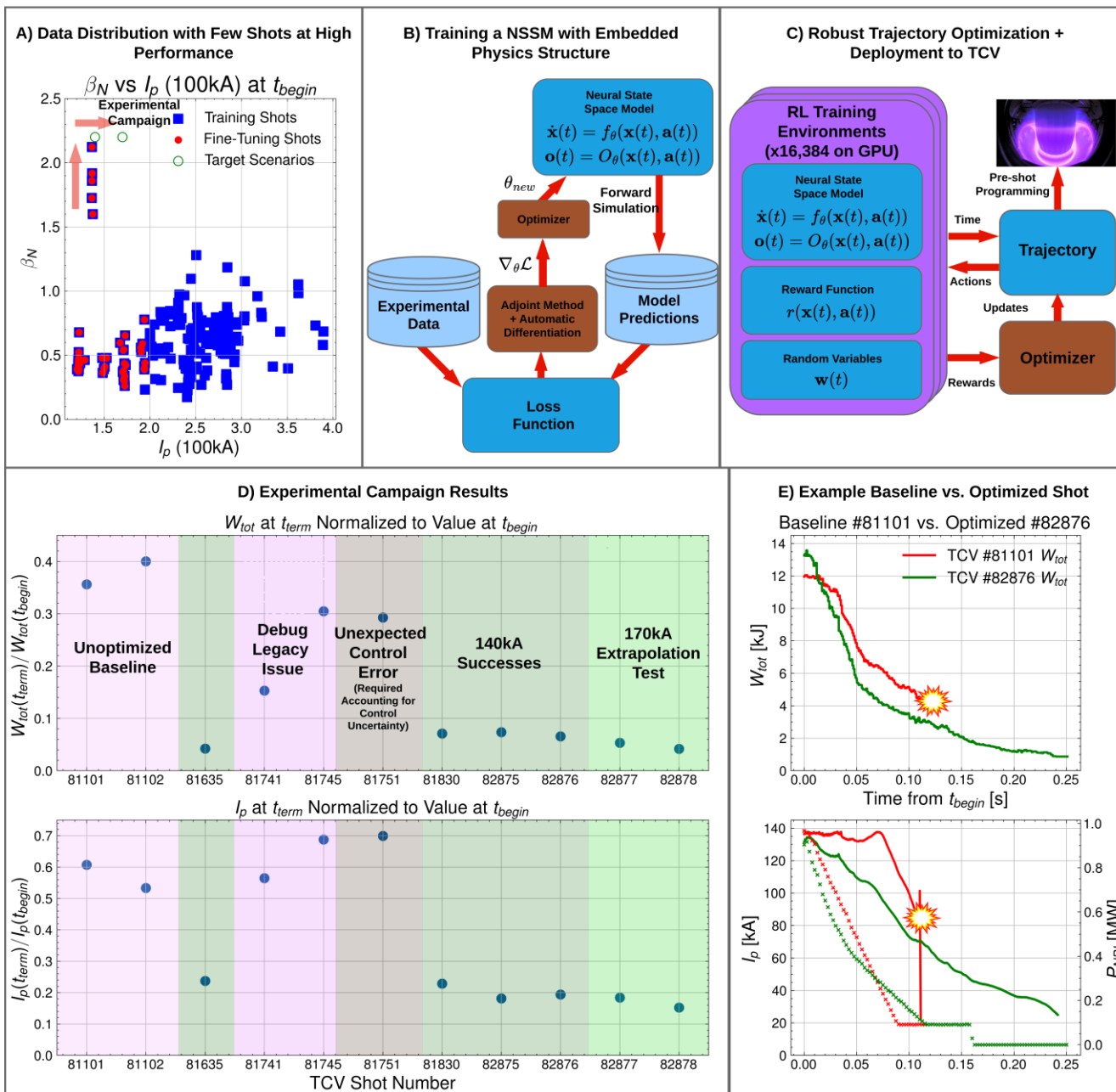
Reward function parameters

Category	Parameter	Value
Hard Limits	f_{GW}	1.0
	t_{95}	0.5
Soft Limits	f_{GW}	0.8
	β_p	1.75
	γ_{vgr}	0.75
	t_{95}	0.313
Parameters	c_{time}	5.0
	c_{I_p}	1.0
	c_W	1.0
	c_{soft}	1.0×10^3
	c_{hard}	5.0×10^4



Predictions and Constraints

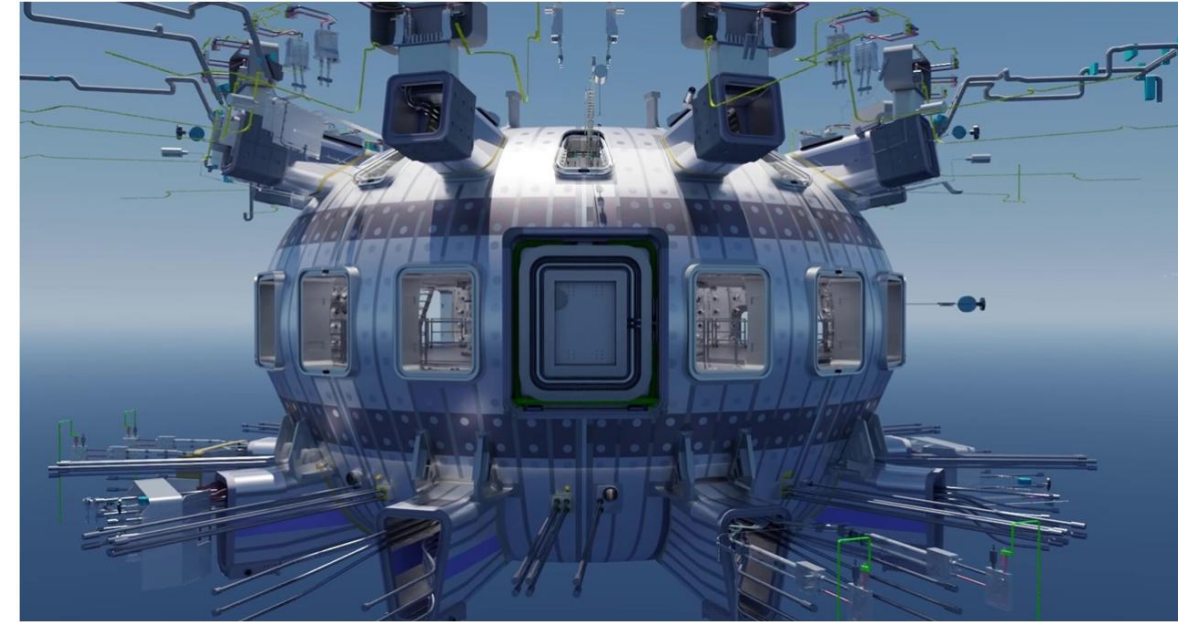




- Initial trial with Proximal Policy Optimization (PPO), before moving to an “**Evolutionary Strategies**” (OpenAI-ES), an algorithm designed for policy optimization.
- ES approaches provide an efficient framework for problems with **long time horizons** and actions that have **long-lasting effects**.

- AI & ML bridging the gaps between **modeling, simulation** and **experiments**:

THE FUTURE: DIGITAL TWINS



NVIDIA Omniverse

- **Integration of AI technologies** to enhance interpretation capabilities, exploration of alternative ideas in virtual simulated environments to enable scientific discovery.
- **Reinforcement learning** can enable advanced plasma control, allowing the design of optimal control policies in complex environments leveraging modeling, simulation and experimental data

Backup slides

➡1. Data ecosystems and cross-device datasets

- Challenges: facility-specific data access, format, and schema; database curation; unsupervised or semi-supervised learning for automated labelling
- MFE area: disruptions, ELMs, instabilities

➡2. Extrapolation to new devices and transfer learning

- Challenges: strategies for transfer or extrapolation; institutional policies for operational certification
- MFE area: extrapolation to ITER; transfer learning to a new device

➡3. Real-time control and prediction

- Challenges: streaming data, advanced compute hardware (FPGA, ASICs)
- MFE area: disruption mitigation, stability boundaries

➡4. Near-real-time analysis

- Challenges: multi-channel, high-bandwidth data; automated analysis; advanced compute hardware
- MFE area: fast cameras, multi-channel fluctuation diagnostics, magnetics

➡5. Surrogate models for simulations

- Challenges: robustness, convergence
- MFE area: plasma-surface interactions, turbulence and transport, RF, stellarator configuration, multi-scale calculations

➡6. Physics-based models

- Challenges: strategies to blend physics and ML models; Bayesian inference
- MFE area: ELMs and stability boundaries

➡7. Big data

- Challenges: data product pipeline, automated analysis, data mirroring and provenance
- MFE area: 2 PB/day at ITER, high bandwidth diagnostics

➡8. Plant operation

- Challenges: real-time monitoring and information synthesis
- MFE area: thermal power generation, nuclear environment, cryogenics, superconducting magnets, vacuum systems, and diagnostic instrumentation