tolerance.

Modular Software Design in CRP ropar 3th kar **Tobias Winchen**

for the CRPropa Developer Team

/ rectilinear propa (current.getCharg /ector3d pos = cur Vector3d dir = curren

.getDirection());

neutral particles

// arbitrary value > 1 candidate->detRedshift():

rmina step until n, yOut, yEri



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Simulation Framework **CR**/Propa

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Toolbox for Simulations of UHECR Propagation



Download: http://crpropa.desy.de

Online demo in your Browser: http://vispa.physik.rwth-aachen.de

Example in Python, but C++ would also be possible

1 from crpropa import * 2 sim = ModuleList()	1. Import + define empty simulation
<pre>4 sim.add(SimplePropagation(1*kpc, 10*Mpc)) 5 6 sim.add(Redshift()) 7 sim.add(PhotoPionProduction(CMB)) 8 sim.add(PhotoPionProduction(IRB)) 9 sim.add(PhotoDisintegration(CMB)) more interactions 17 obs = Observer() 18 obs.add(ObserverPoint()) 19 output = TextOutput('events.txt', Output.Event1D) 20 obs.onDetection(output) 21 sim.add(obs) </pre>	2. Add modules
<pre>23 source = Source() 24 source.add(SourceUniform1D(1 * Mpc, 1000 * Mpc)) 25 source.add(SourceRedshift1D()) 26 27 composition = SourceComposition(1 * EeV, 100 * EeV, -1) 28 composition.add(1, 1, 1) # H 29 composition.add(4, 2, 1) # He-4 30 composition.add(14, 7, 1) # N-14 31 composition.add(56, 26, 1) # Fe-56 32 source.add(composition) 33 34 34 35 35 35 35 35 35 35 35 35 35 35 35 35</pre>	3. Define sources
<pre>34 sim.setShowProgress(True) 35 sim.run(source, 200, True) 36</pre>	4. Execute modules on output of sources

Overview Object Oriented Design



are independent and stateless to enable parallel processing

New objects can be coded in C++ or Python (Interface generated using SWIG) by the user Without recompiling CRPropa core.

Candidate: Stores Data on Particle



Modules: Modify Candidate

Prototype Propagator

1. Save current state:
PreviousState = CurrentState

- 2. Make step
 - CurrentStep=NextStep
 - Update position according to CurrentStep
- 3. Set NextStep to maximum

exit module

Prototype Interaction

- 1.If not applicable: Do nothing
- 2.Calculate probability to interact in current step according to current candidate state
- 3.If no interaction:
 - Limit next step to small fraction of m. free path
 - exit module
 - If interaction:
 - Modify current particle
 - add secondaries
 - Repeat from 2

- Candidate has individual step size
- Every module limits the stepsize to a small fraction of its mean free path
 - Order does not matter
 - Modules are independent, no communication required
- Modularity in interactions is paid for by random numbers as need to be generated in every cycle by every module (CRPropa not limited by RNG)

Module Features are Separate Objects

E.g. Observer



Example: Output particles crossing different planes



Does this Scale for Many Particles?



Implementation scales linearly with number of processed particles

How did we get There?

Several versions of CRPropa
 Previous modular codes
 →PAX, PXL, RDAS

Software development philosophy:

- KISS: Keep it simple, not stupid
- YAGNI: You ain't gonna need it
- Refactor often and early
- Dev. Substeps:
 - \rightarrow Make it work
 - \rightarrow Make it right
 - \rightarrow Make it nice
 - \rightarrow Make it fast (if needed)

- Code review (of substantial changes) git + pull requests (github)
- Unit Tests + Continuous Integration gtest + travis
- Minimize dependencies:
 - \rightarrow User should not need to compile dependencies
 - Dependencies should be standard / trivial available on supported platforms (Linux + Mac)
 - » Cmake
 - » Python
 - » Swig
 - » hdf5

or shipped in static version.

- » Healpix subset, eigen, kiss, (tinyxml, thread), hepid
- →Boost (and ROOT) are known to cause problems

Conclusion



CRPropa3 highly modular code design

- User friendly (all dependencies except python + swig) shipped + compiles using standardized tool chain (cmake)
- \rightarrow Highly modular
- Easily extendable (C++/python modules and features without recompiling)
- \rightarrow Scales linearly to high particle numbers
- →Webpage / Code / Issue-tracker / Examples / Documentation / ...

https://crpropa.desy.de/ https://github.com/CRPropa/CRPropa3

Several approaches probably transferable to Next Generation CORSIKA