

Merging weather radar fields with data from commercial microwave links using mergeplg

Erlend Øydvin, Maximilian Graf, Christian Chwala, Elia Covi

mergeplg

- A OpenSense python package for
 - Interpolation
 - Ground observations
 - Merging
 - Radar + ground observations
- Lives in the OpenSense ecosystem
- Comparison study

The screenshot shows the GitHub repository for 'mergeplg'. At the top, it indicates the repository is 'Public' and has 4 branches and 3 tags. The main content area displays a list of files and their commit history, including .github, docs, src/mergeplg, tests, .cruft.json, .git_archival.txt, .gitattributes, .gitignore, .gitmodules, .pre-commit-config.yaml, .readthedocs.yaml, LICENSE, README.md, nofile.py, and pyproject.toml. The right sidebar contains metadata: 'About' (Merging methods for rainfall sensor data), 'Releases' (v0.1.0 Latest), 'Packages' (No packages published), 'Contributors' (cchwalla, eoydvin, dependabot, EllaCovi), 'Deployments' (pypi), and 'Languages' (Python 100.0%). The bottom section shows the README for 'mergeplg', which describes it as a collection of methods to merge rainfall sensor data from point, line, and grid geometries, and notes it is in a very early stage of development.

mergeplg Public

Edit Pins Unwatch 3 Fork 5 Star 0

main 4 Branches 3 Tags

Go to file Add file Code

eoydvin Reorganize interpolator and merger code (#47) 8eea81d · last month 25 Commits

.github	Bump the actions group across 1 directory with 2 update...	2 months ago
docs	Reorganize interpolator and merger code (#47)	last month
src/mergeplg	Reorganize interpolator and merger code (#47)	last month
tests	Reorganize interpolator and merger code (#47)	last month
.cruft.json	adding skeleton based on cookiecutter template	11 months ago
.git_archival.txt	adding skeleton based on cookiecutter template	11 months ago
.gitattributes	adding skeleton based on cookiecutter template	11 months ago
.gitignore	Initial config changes (#5)	11 months ago
.gitmodules	removed pycomlink submodule which was part of the ra...	3 months ago
.pre-commit-config.yaml	Add RADOLAN method and example notebook with Ope...	8 months ago
.readthedocs.yaml	adding skeleton based on cookiecutter template	11 months ago
LICENSE	adding skeleton based on cookiecutter template	11 months ago
README.md	Add RADOLAN method and example notebook with Ope...	8 months ago
nofile.py	Add additive radar-CML merging with IDW and with Krig...	9 months ago
pyproject.toml	Allow to use merging and interpolation functions without...	3 months ago

README BSD-3-Clause license

mergeplg

CI: passing docs: passing

pypi: not found conda: not found python: 3.10 | 3.11 | 3.12 | 3.13

mergeplg is a collection of methods to merge rainfall sensor data from point, line and grid geometries. Typically the sensors are rain gauges (point), CML or SML (line) and weather radar or satellites (grid). This package is currently in a very early stage of development...

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mergeplg (Public)

4 Branches 3 Tags

Q Go to file

Add file Code

About

Merging methods for rainfall sensor data provided as point, line and grid

Readme

BSD-3-Clause license

Activity

Custom properties

0 stars

3 watching

5 forks

Report repository

Releases 3

v0.1.0 (Latest) on Apr 1

+ 2 releases

Packages

No packages published

[Publish your first package](#)

Contributors 4

cchwalla Christian Chwalla

eoydvin

dependabot[bot]

EllaCovi

Deployments 6

pypl 3 months ago

+ 5 deployments

Languages

Python 100.0%

mergeplg BSD-3-Clause license

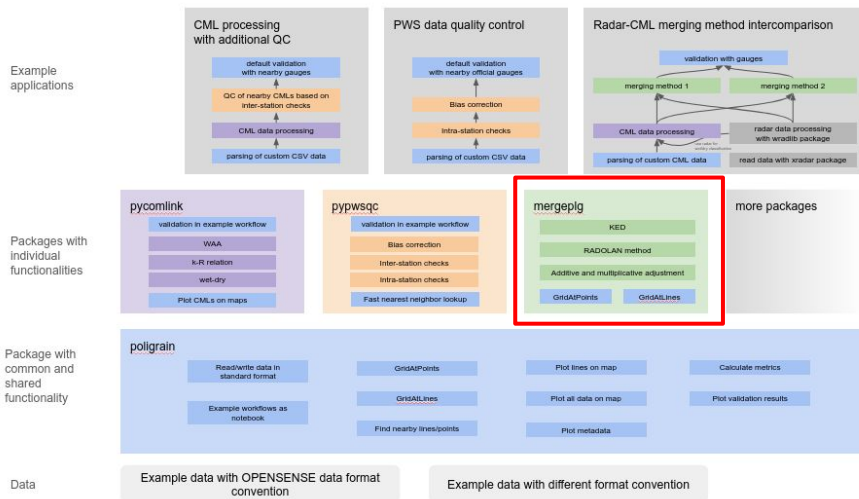
CI: passing tests: passing

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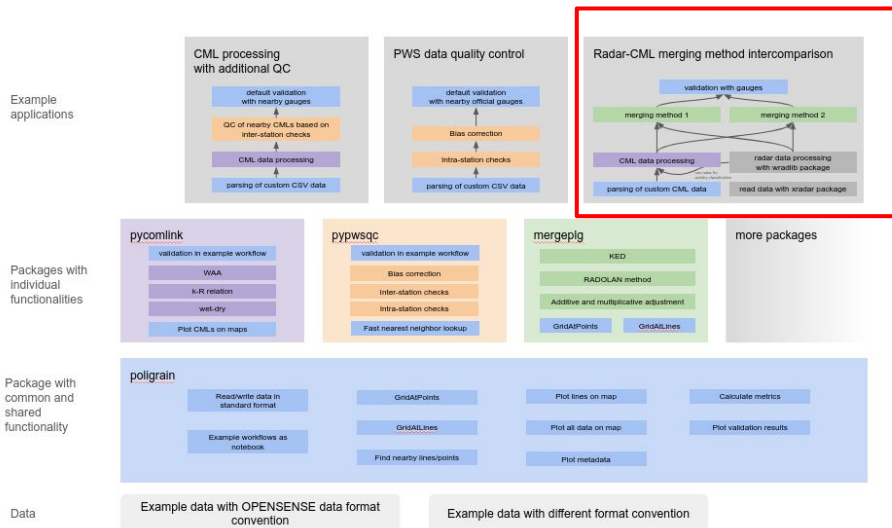
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Data

OpenMRG

[Adersson et al. \(2022\)](#)

OpenRainER

[Covi et al. \(2025\)](#)



Data - OpenMRG

350 CMLs (red lines) + radar

Reference: 10 rain gauge (black dots)

August 2015

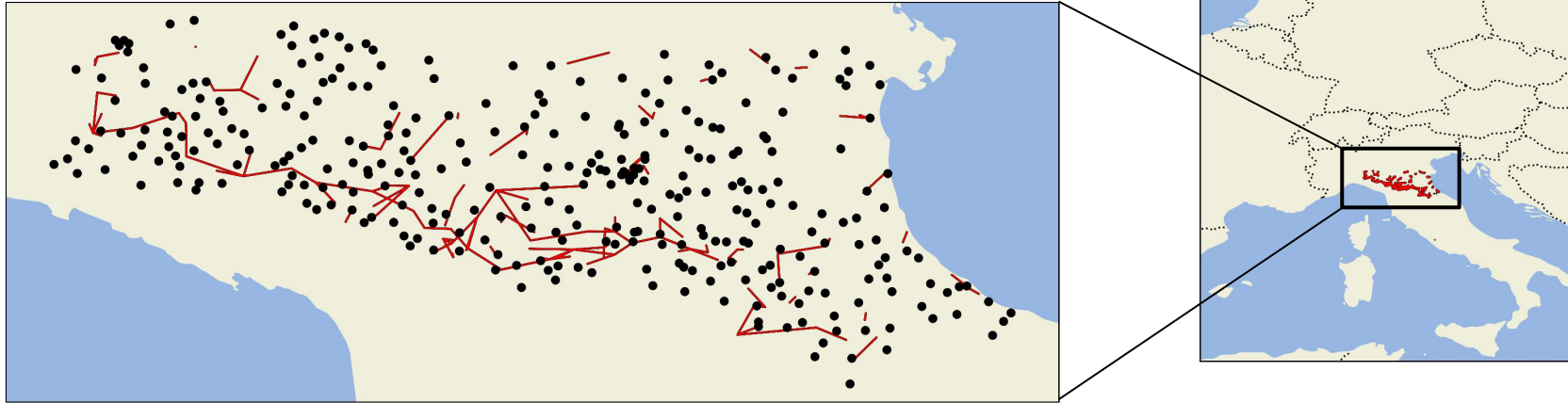


Data - OpenRainER

114 CMLs (red lines) + radar

Reference: 319 rain gauge (black dots)

August 2022

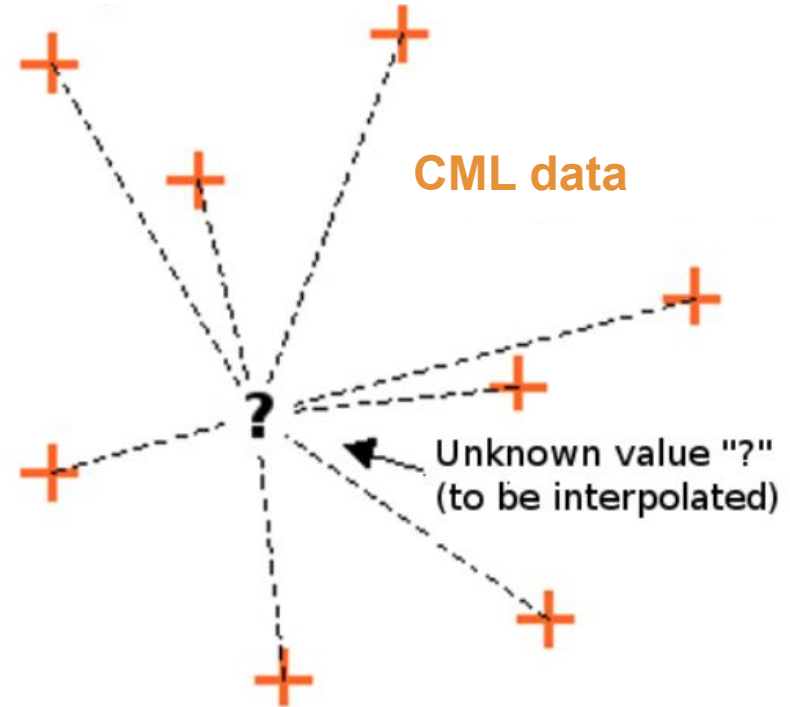


Interpolation methods

Goal: Optimally weight CML data to estimate unknown value

1. interpolateIDW
 - a. Uses inverse distance weighting
 - b. CML midpoint
2. interpolateBKpoint
 - a. Uses Ordinary Kriging
 - b. CML midpoints
3. interpolateBKline
 - a. Uses Ordinary Block Kriging
 - b. CML line

CML data

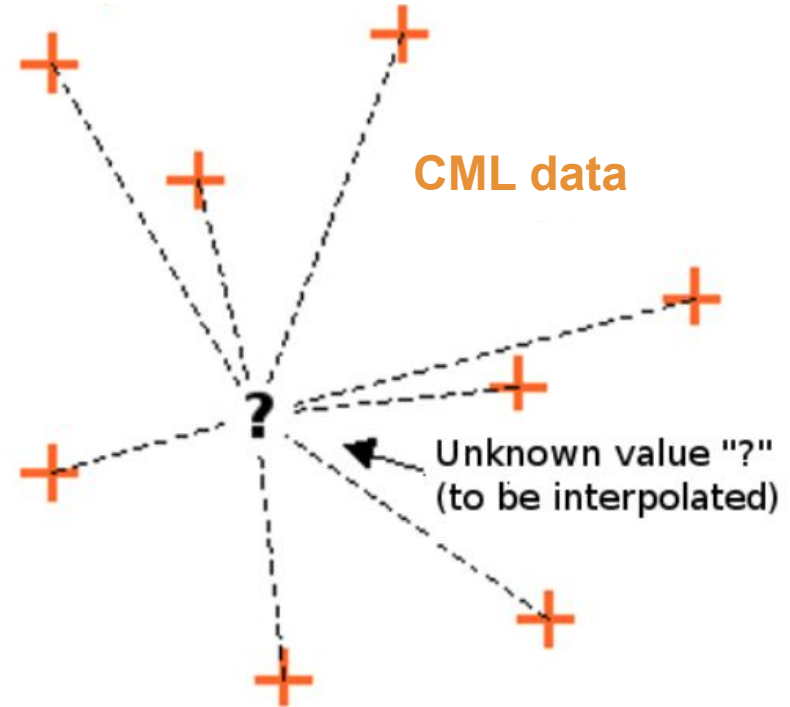


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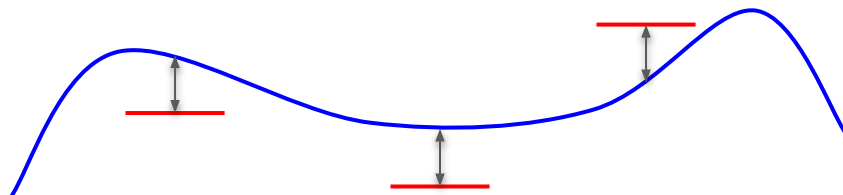


Merging methods

Additive merging:

- Estimate difference between radar and CML
- Interpolate difference (IDW, Kriging)
- Add interpolated difference to radar map

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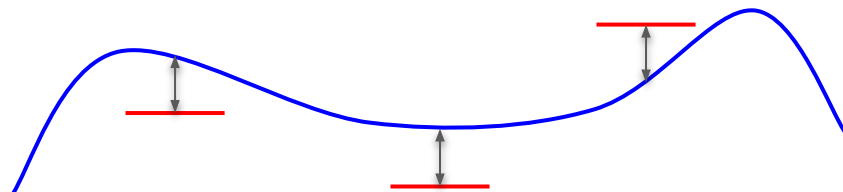


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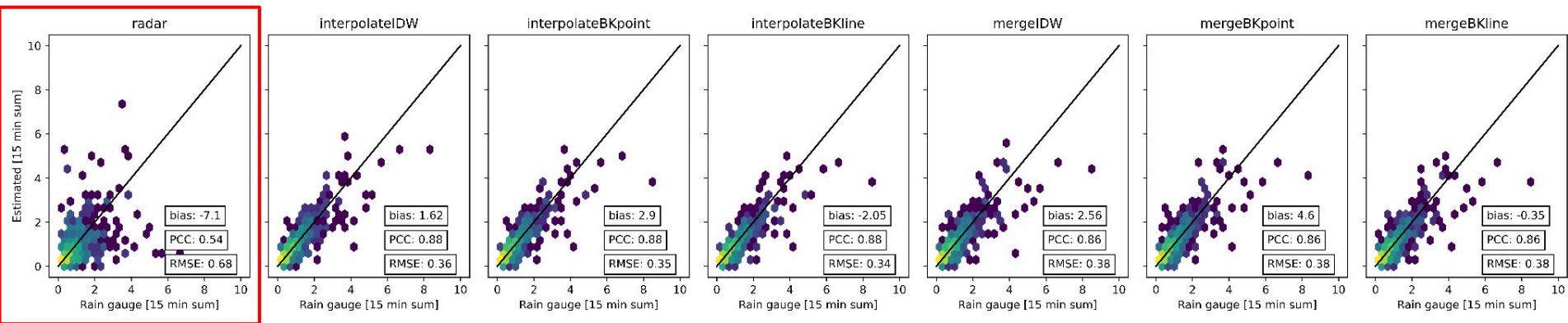
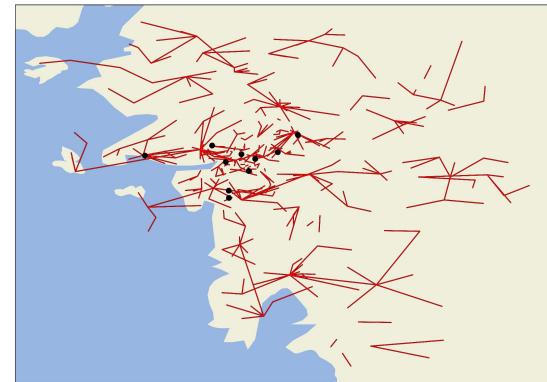


Results OpenMRG

Radar performs good

Interpolated CMLs performs better than radar

Radar merged with CMLs performs similarly good as interpolated CML data

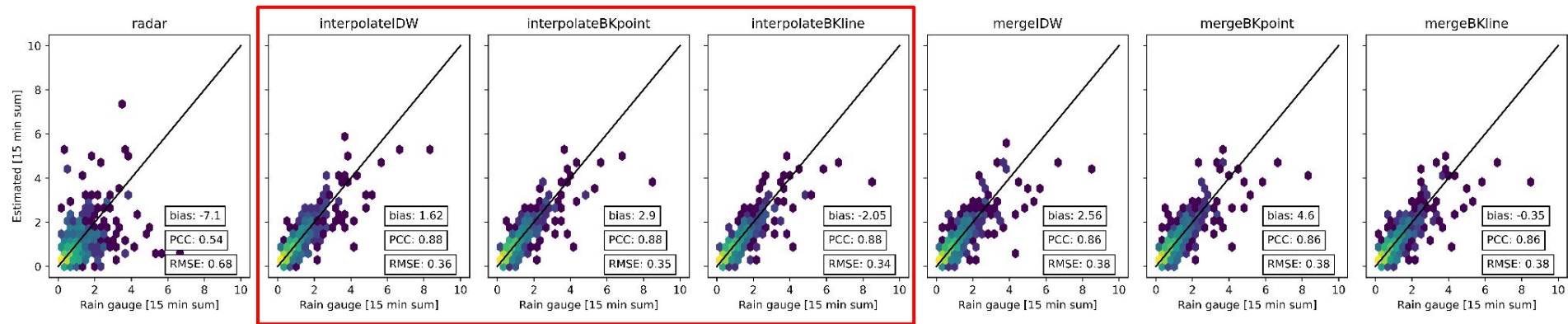
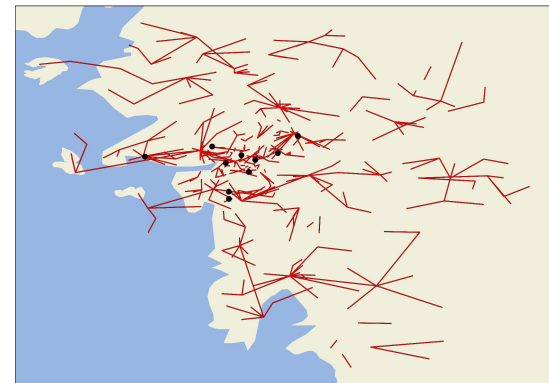


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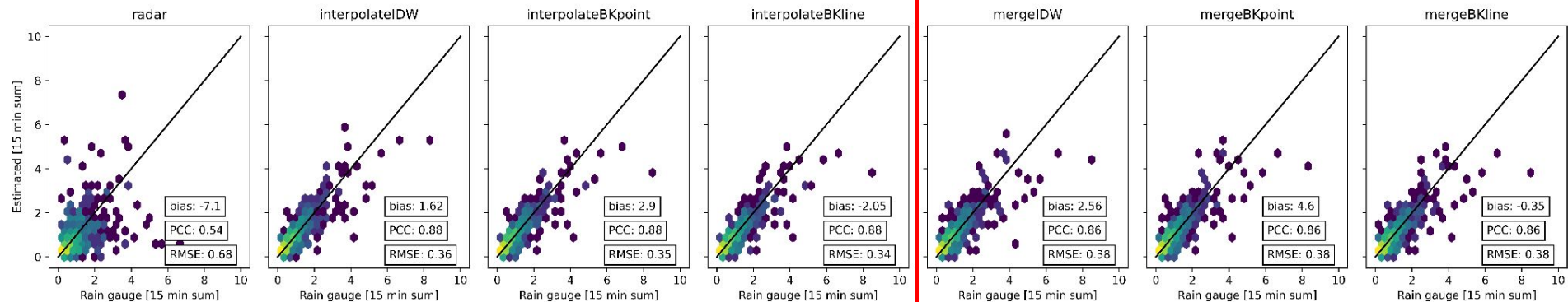
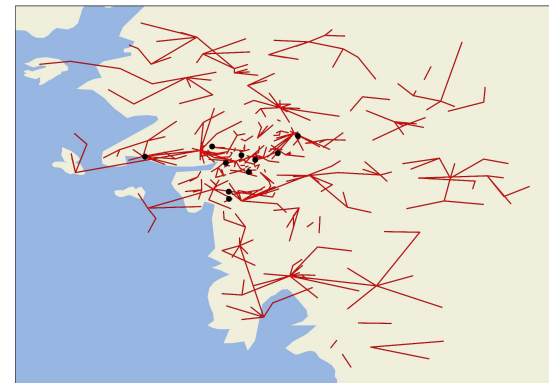


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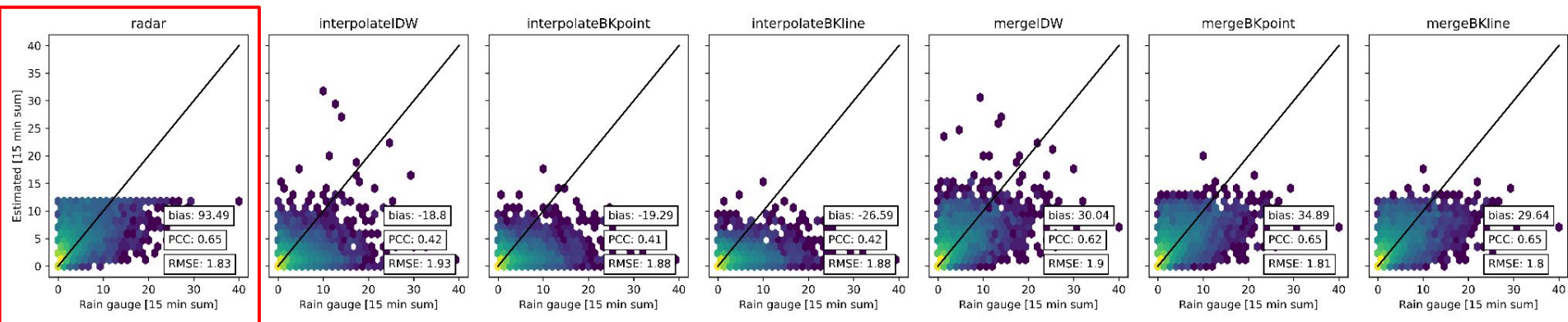
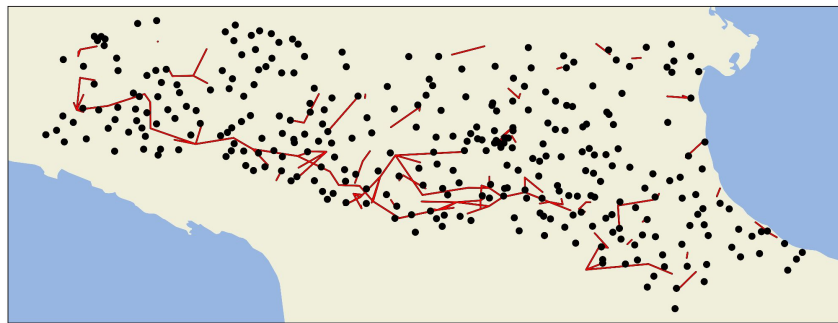


Results OpenRainER

Higher rainfall amounts

Interpolated CMLs, less good than radar

Radar merged with CMLs, better bias than radar

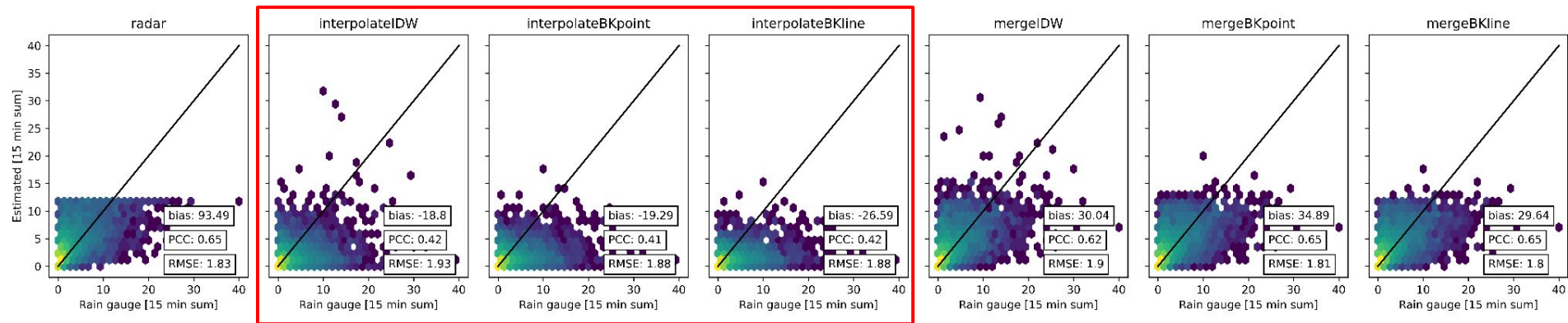
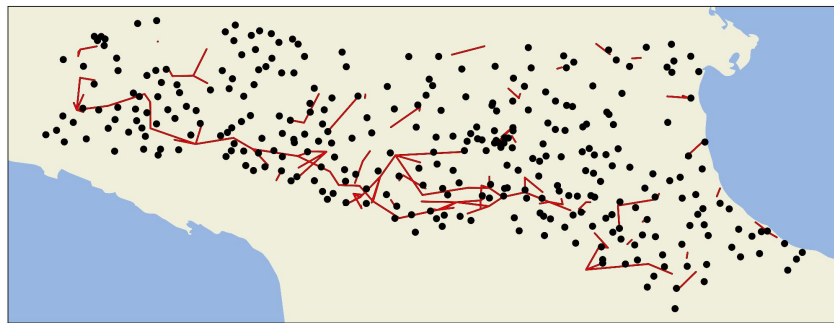


Results OpenRainER

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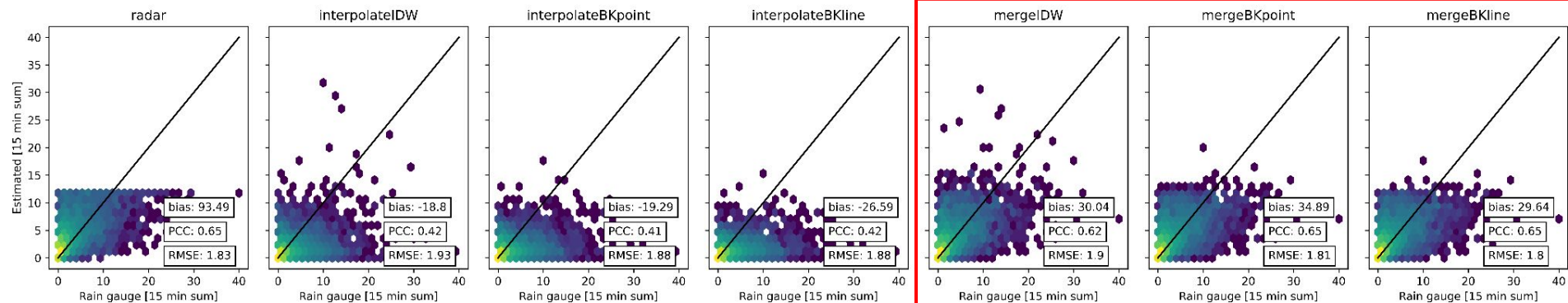
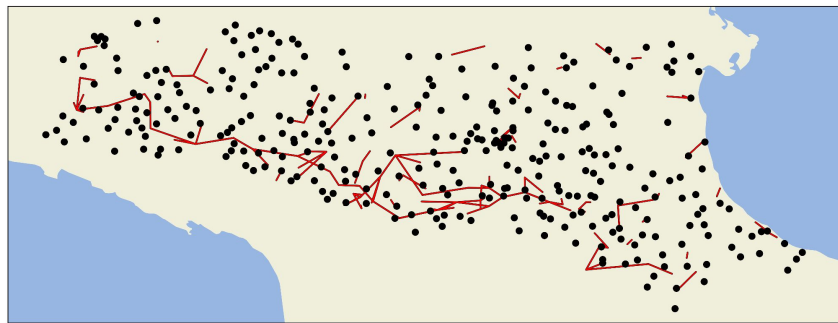


Results OpenRainER

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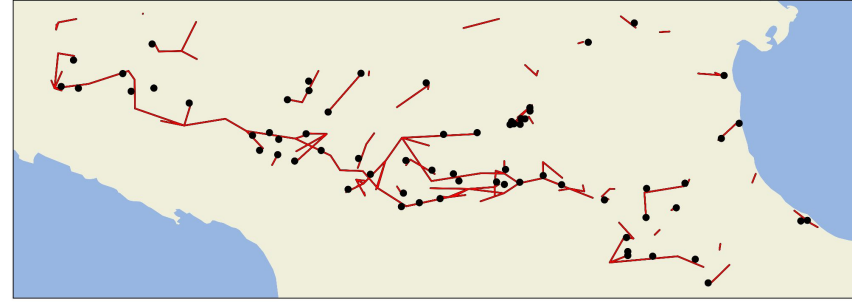
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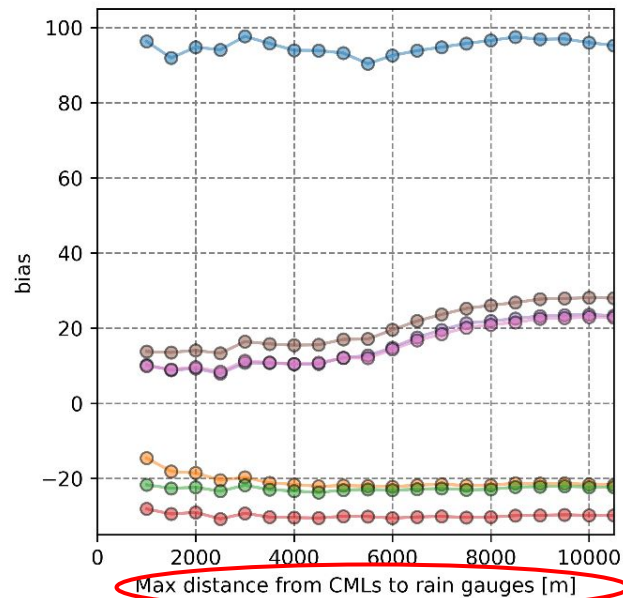
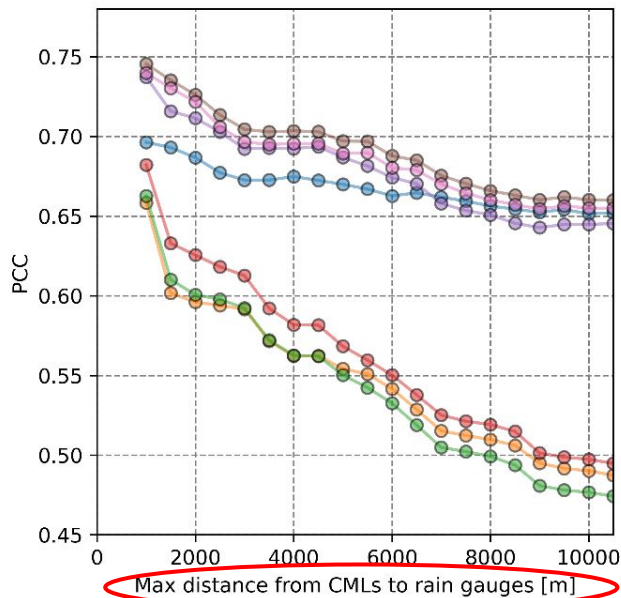
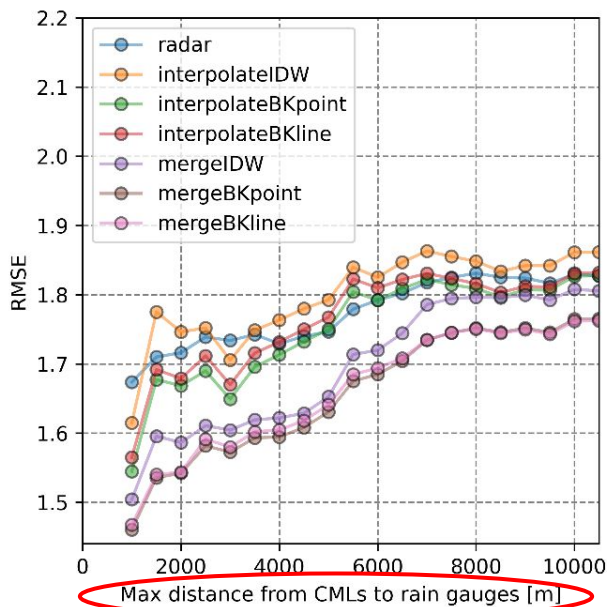
Use only rain gauges within 2 km of a CML



Analysis OpenRainER

Rain gauges within x meters of a CML

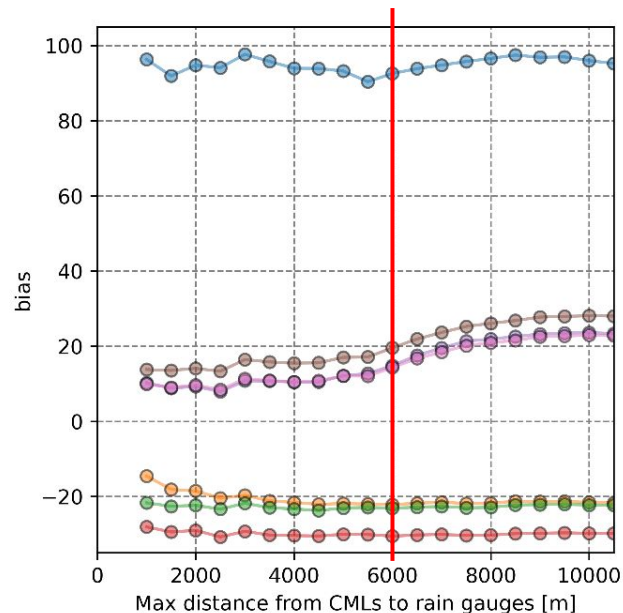
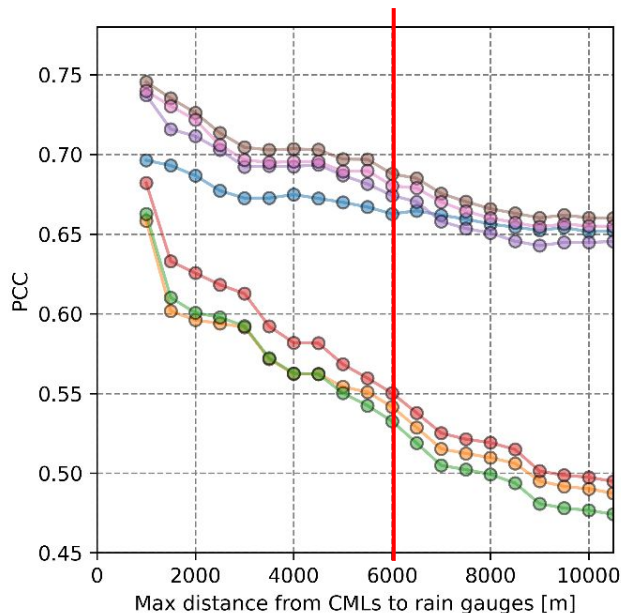
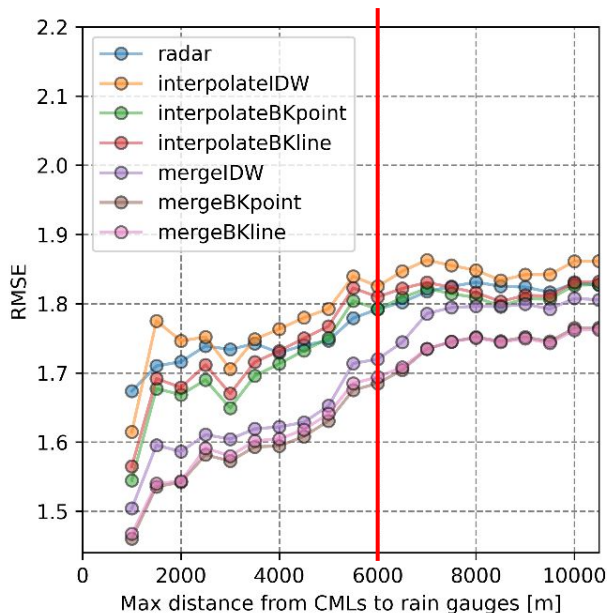
- For instance at 6000 m, only rain gauges within 6000 m of a CML is included
- Evaluated RMSE, PCC and bias



Analysis OpenRainER

Rain gauges within x meters of a CML

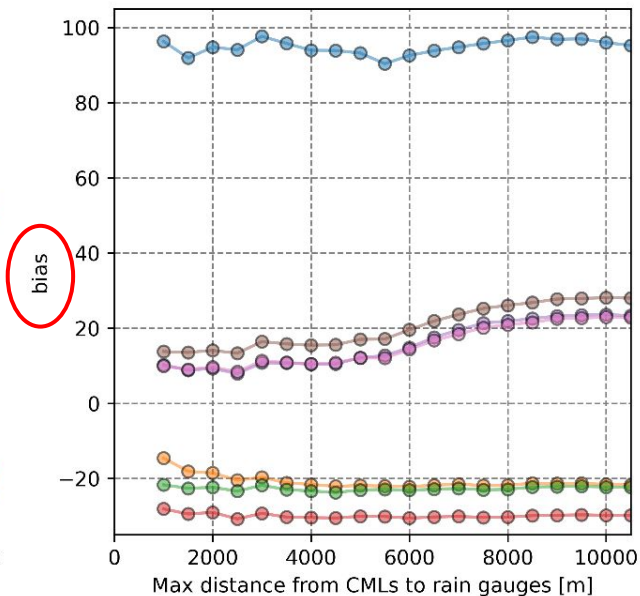
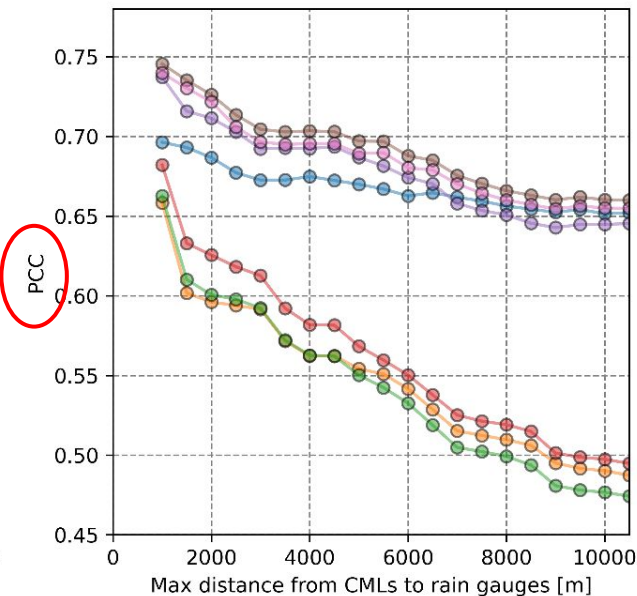
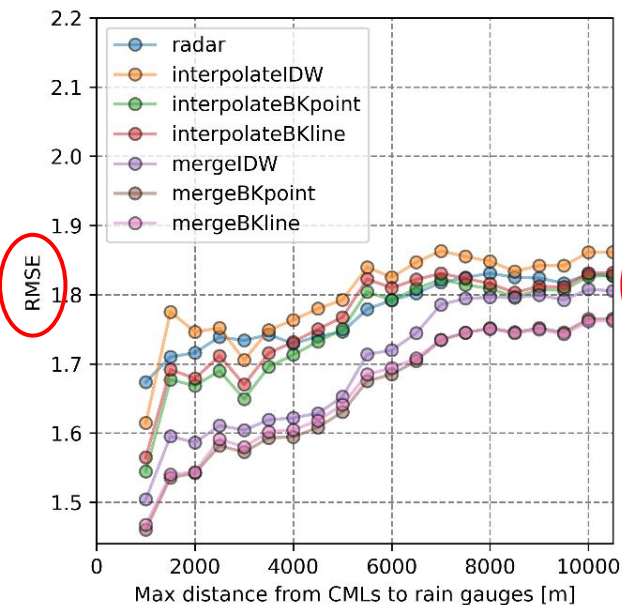
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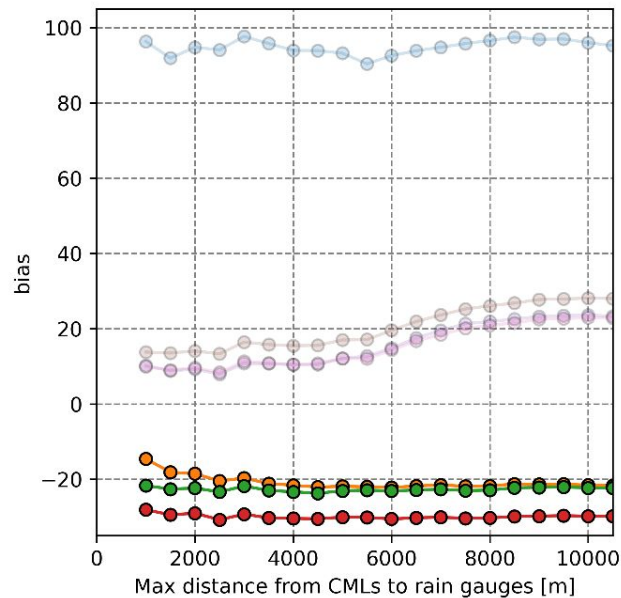
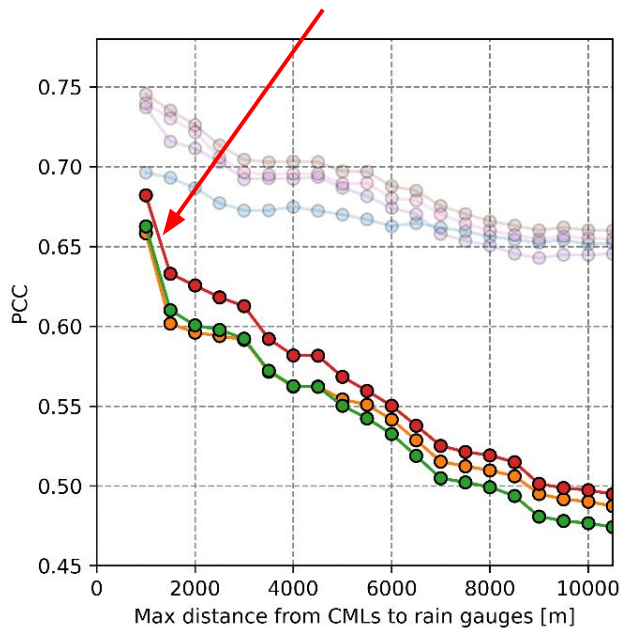
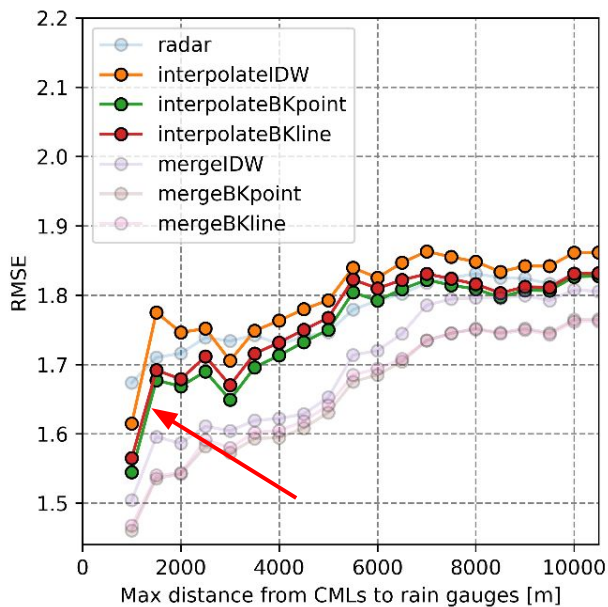
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Analysis OpenRainER

Interpolated CML data

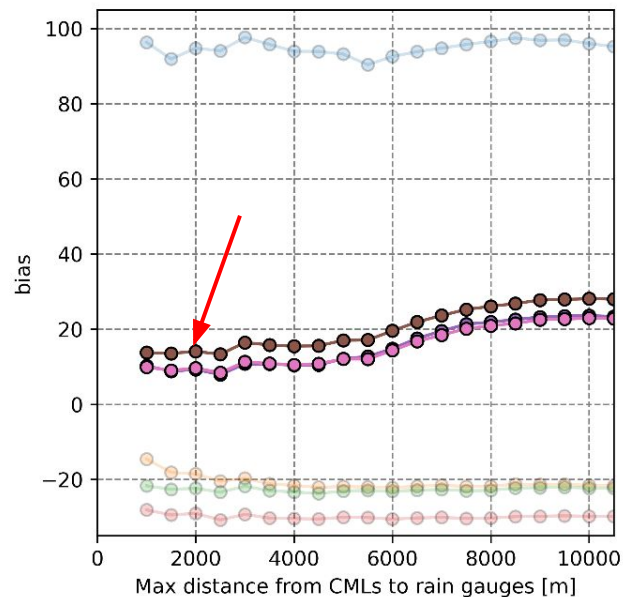
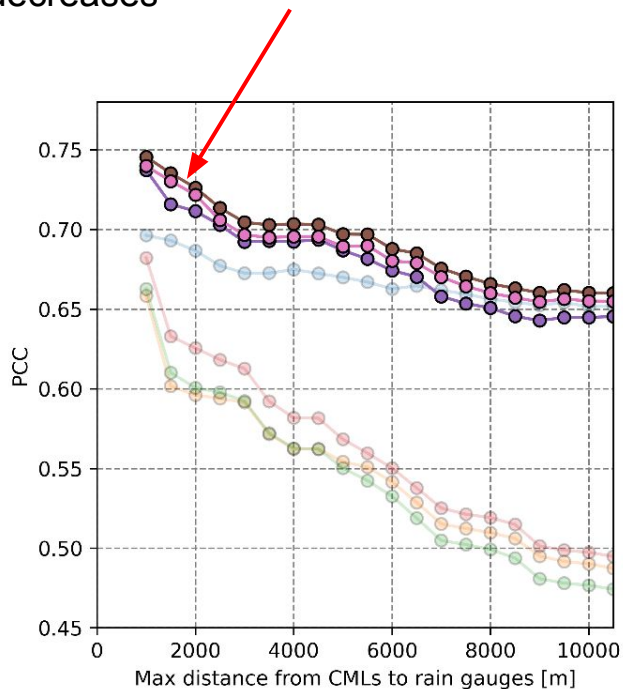
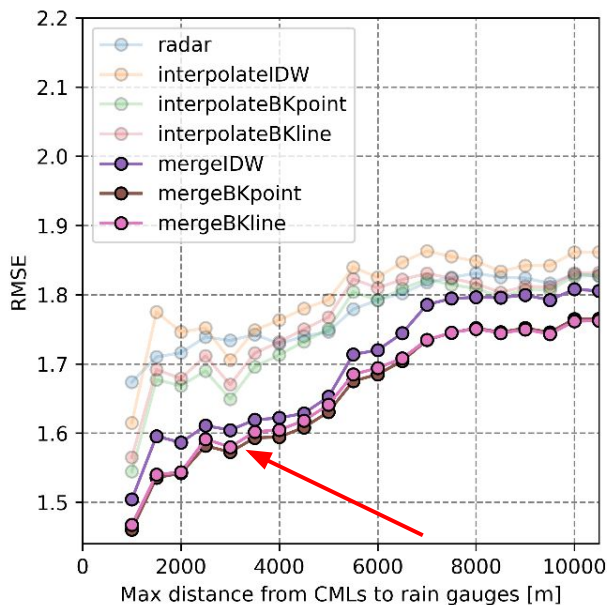
- Improves as distance decreases
- Kriging slightly better



Analysis OpenRainER

Merged CML and radar data

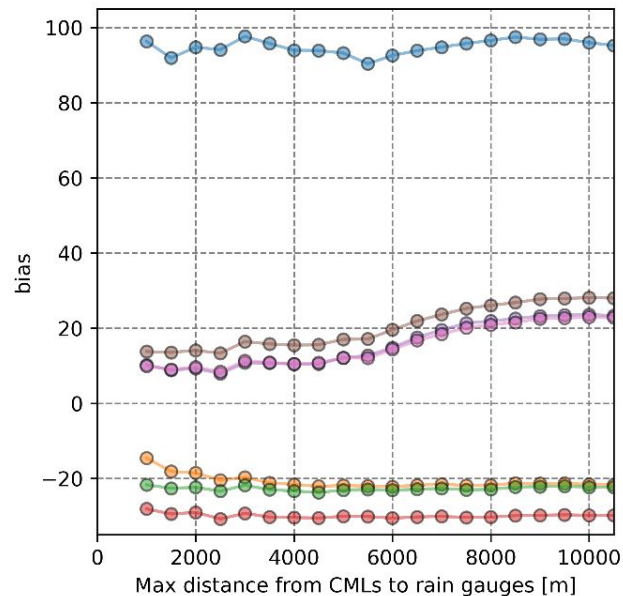
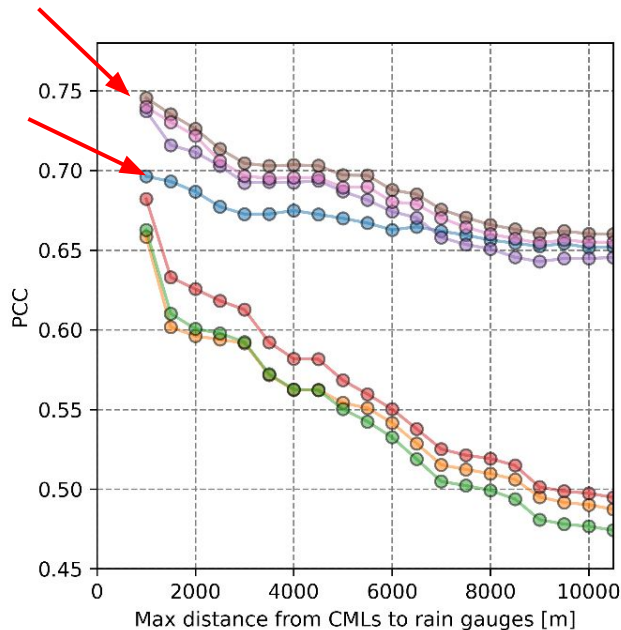
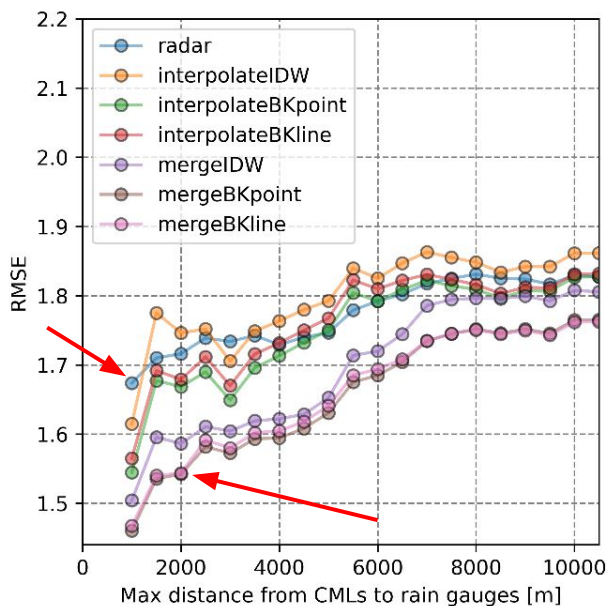
- Also improves as distance decreases
- Kriging slightly better



Analysis OpenRainER

When distance **decreases**

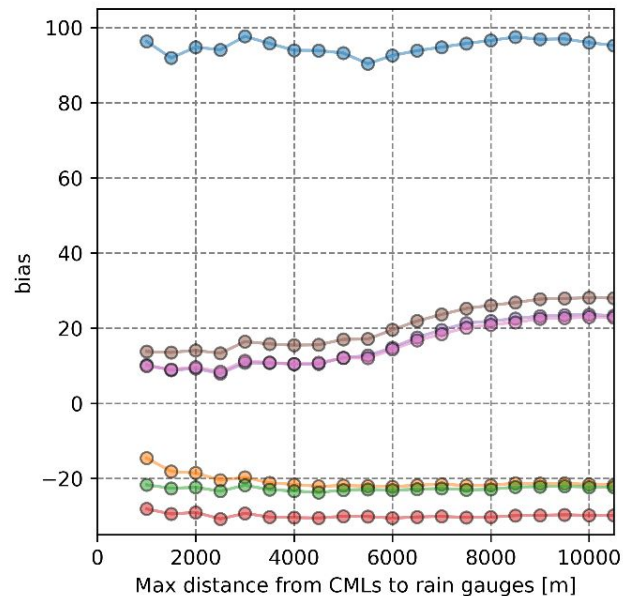
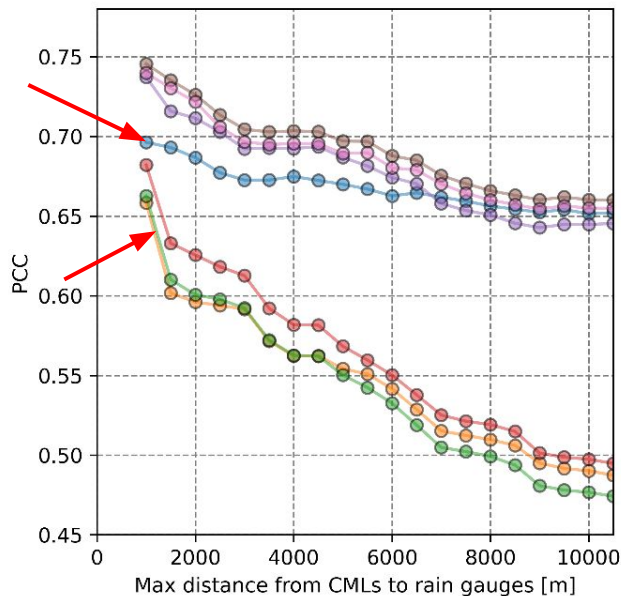
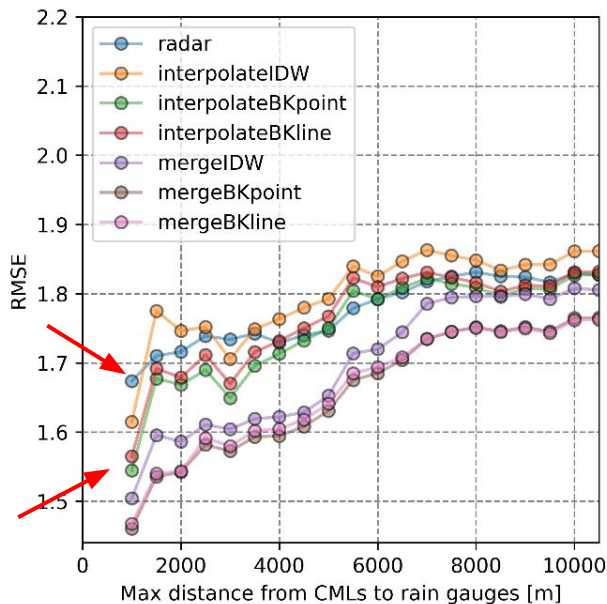
- Merged fields outperforms radar
- Interpolated fields almost as good as radar



Analysis OpenRainER

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Conclusions and perspectives

- CMLs perform good when there are many CMLs close to the reference
 - OpenMRG (radar PCC: 0.54, interpolateIDW PCC: 0.88)
- Merging radar with CML improves rainfall fields
 - OpenRainER (radar PCC = 0.7, mergeBKpoint approaching 0.75)
- OpenRainER seem to approach OpenMRG results
 - Further work: Investigate how CML densities affects the results
- Kriging variants slightly better than IDW
 - Event based analysis to better understand the strength and weaknesses

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