

Physics of Linear Accelerators



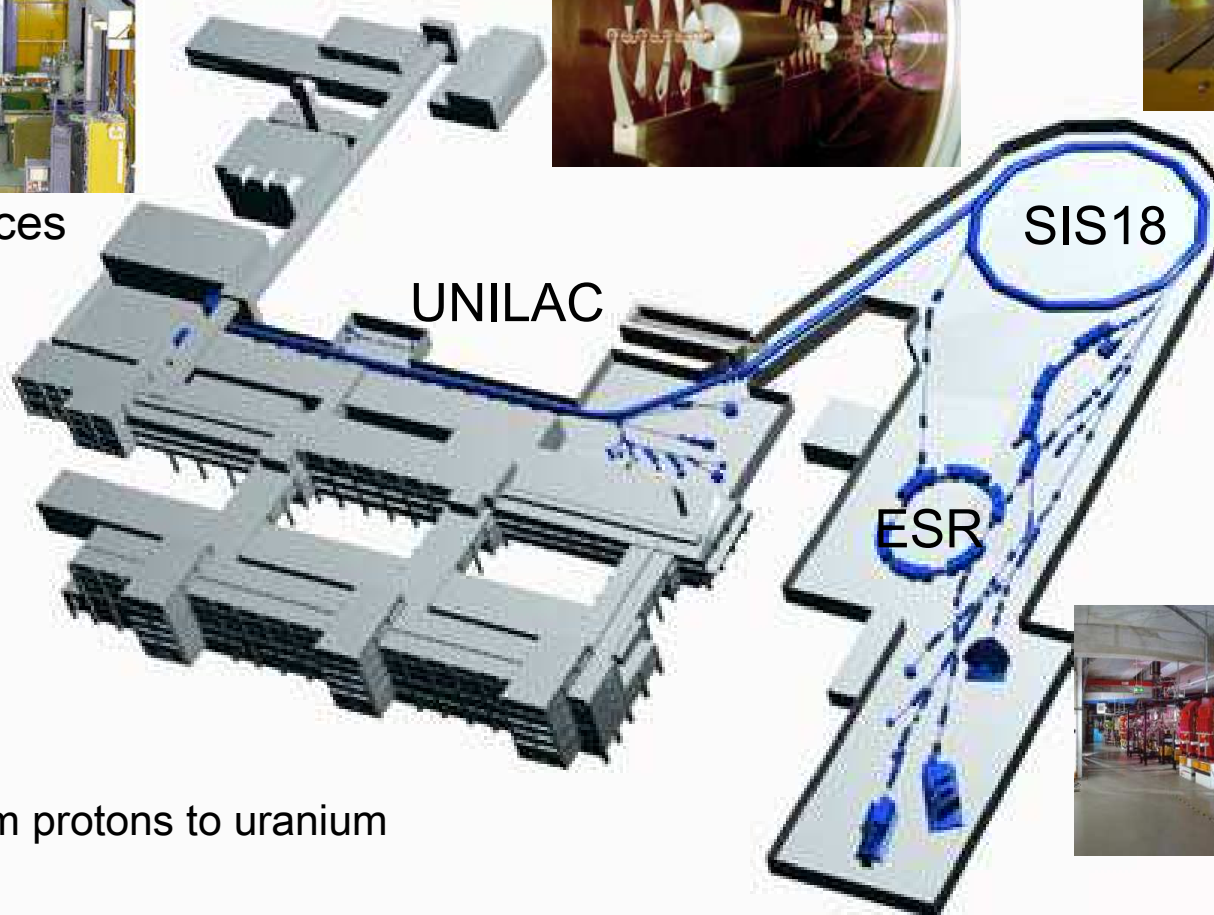
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- Provision of charged particles (ions)
- Accelerating cavities
- High voltage sparking
- Radio-frequency power sources
- Focusing and stability of beams
 - longitudinal
 - transverse
- Radio frequency quadrupole
- Beam self forces

GSI Accelerator Facilities



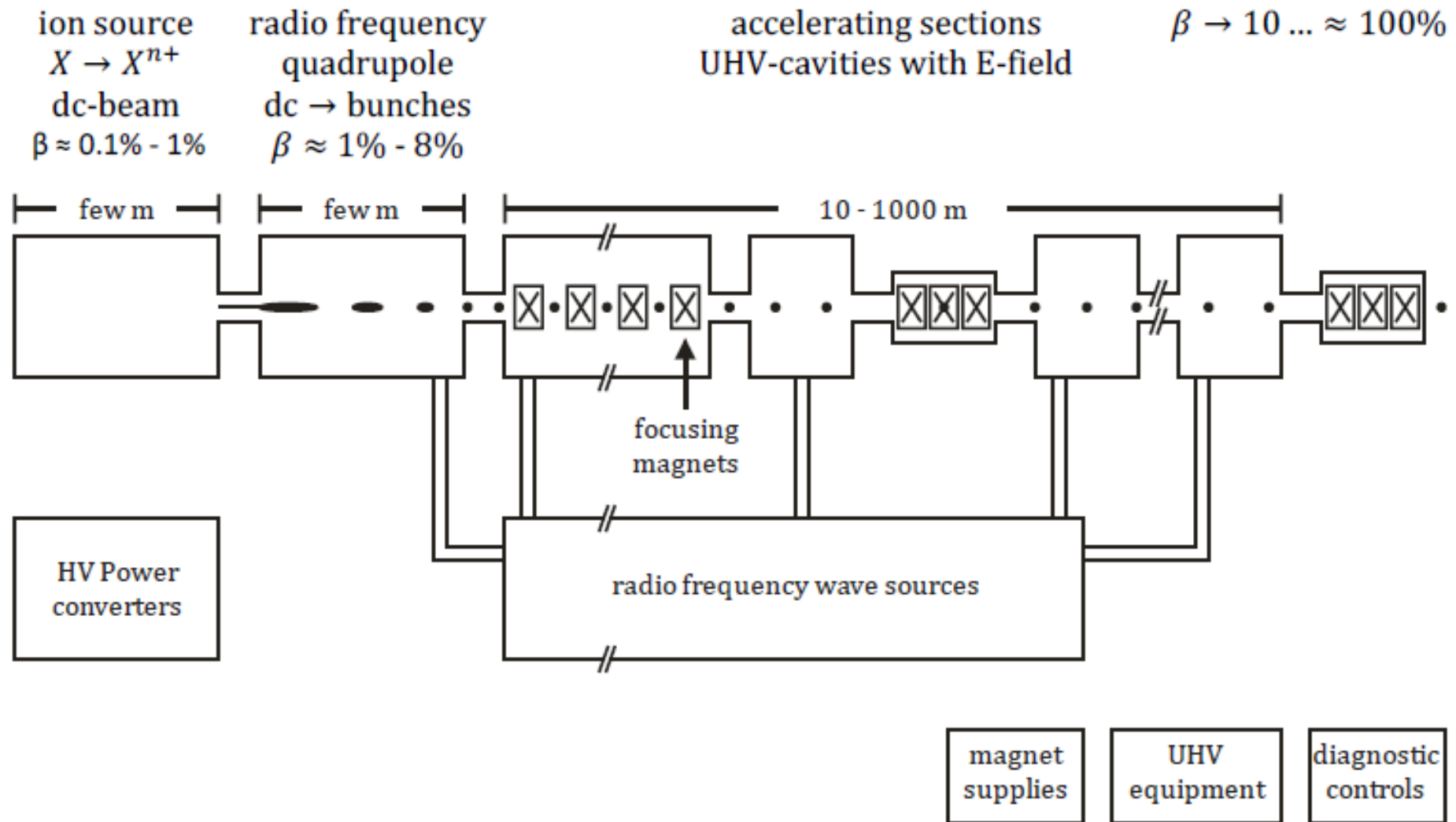
Ion Sources



all ions from protons to uranium



Modern Linear Accelerator (schematic)



Creation of Charged Particles

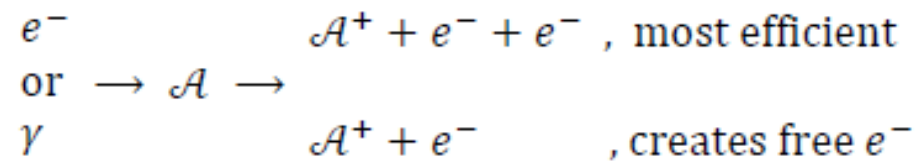


Ion Creation

- ▶ supply neutral atoms \mathcal{A} by:
 - injection of gas
 - vapping
 - sputtering, i.e. bombard surface with other ion species B^{n+}



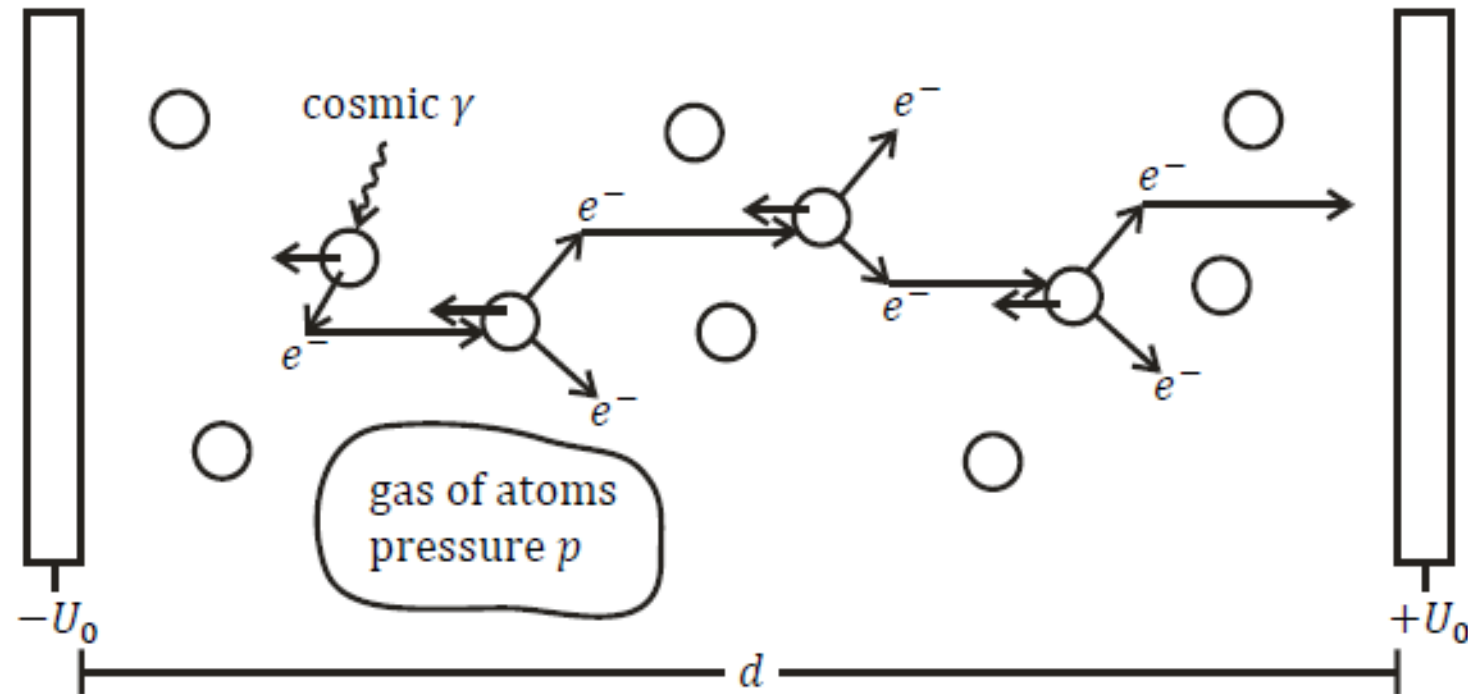
- ▶ collide atoms with photons or electrons e^-



Creation of Charged Particles



Electron & Ion Production by controlled Discharge

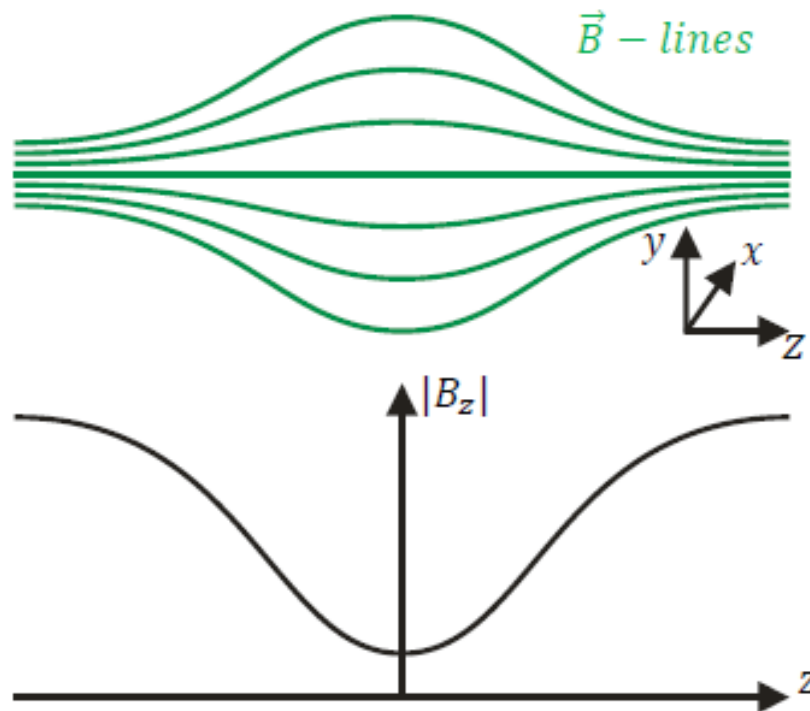


if p & d are properly chosen
→ continuous e^- & ion production

Confinement of Charged Particles



- ▶ without confinement ions & e^- move towards electrodes and get lost
- ▶ higher ion intensities require to confine ions inside “production” volume
- ▶ confinement by magnetic bottle:



$$\frac{v_x^2 + v_y^2}{|B_z|} = \text{const}$$

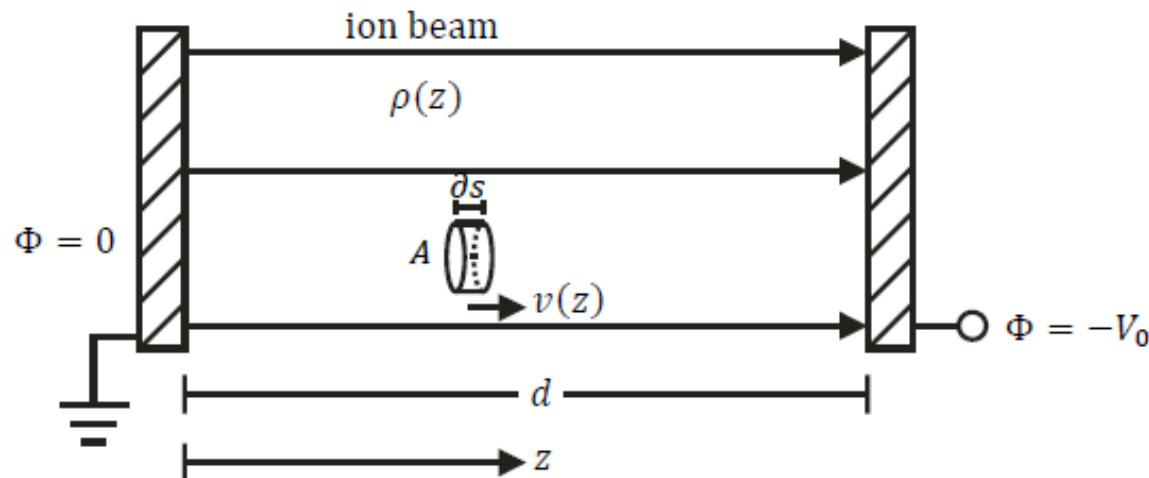
(see Jackson "class el. dyn.")

$$v_{tot}^2 - v_z^2 = |B_z| \cdot \text{const}$$

$$v_z^2 = \frac{2}{m} E_{kin} - |B_z| \cdot \text{const}$$

$\rightarrow |B_z| > B_c \rightarrow$ ion reflection along z-axis

Extraction of Charged Particles



$$I(z) = \frac{\partial q}{\partial t} = \frac{\rho(z) \cdot A \cdot \partial s}{\partial t} = \text{const!}$$

$$\frac{I}{A} := J = \rho(z) \cdot v(z) = \rho \cdot \dot{z} = \text{const!} (*)$$

$$\Rightarrow \frac{\partial J}{\partial z} = 0 \text{ continuity equation (1)}$$

$$\vec{\nabla} \vec{E} = \frac{\rho}{\epsilon_0}, \quad \vec{E} = -\vec{\nabla} \Phi$$

$$\Rightarrow \Delta \Phi = \frac{\delta^2 \Phi}{\delta z^2} = -\frac{\rho}{\epsilon_0} \text{ Poisson equation (2)}$$

$$\frac{m}{2} \dot{z}^2 = -q \Phi(z) \text{ energy preservation (3)}$$

$$\Rightarrow J = \frac{4}{9} \epsilon_0 \sqrt{\frac{2q}{m}} \cdot \frac{V_0^{3/2}}{d^2} \quad \text{Child-Langmuir Law}$$

- ▶ used simplification of planar plates (electrodes)
- ▶ real electrodes:
 - are curved
 - have beam holes (extraction electrode @ $-V_0$)

→ real currents may be lower (ions)

but scaling law $J \sim V_0^{3/2} d^{-2}$ holds

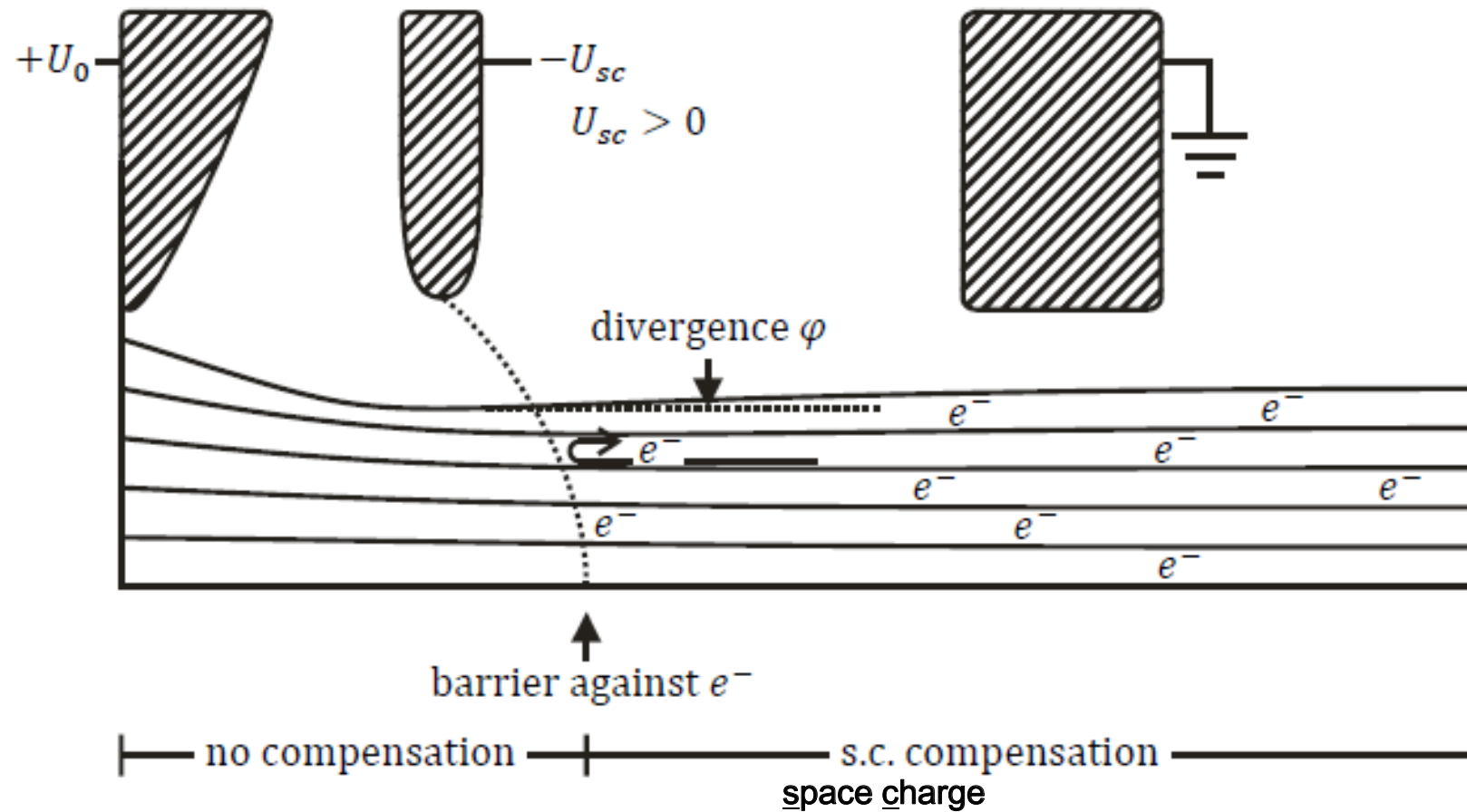
$$I = A \cdot J := P \cdot \frac{A_{\text{cathode}}}{d^2} \cdot V^{3/2}, \quad P \text{ is "Perveance"}$$

Extraction of Charged Particles



Triode Extraction:

insert a screening (sc) electrode that keeps e^- off from emitter



Accelerating Cavities

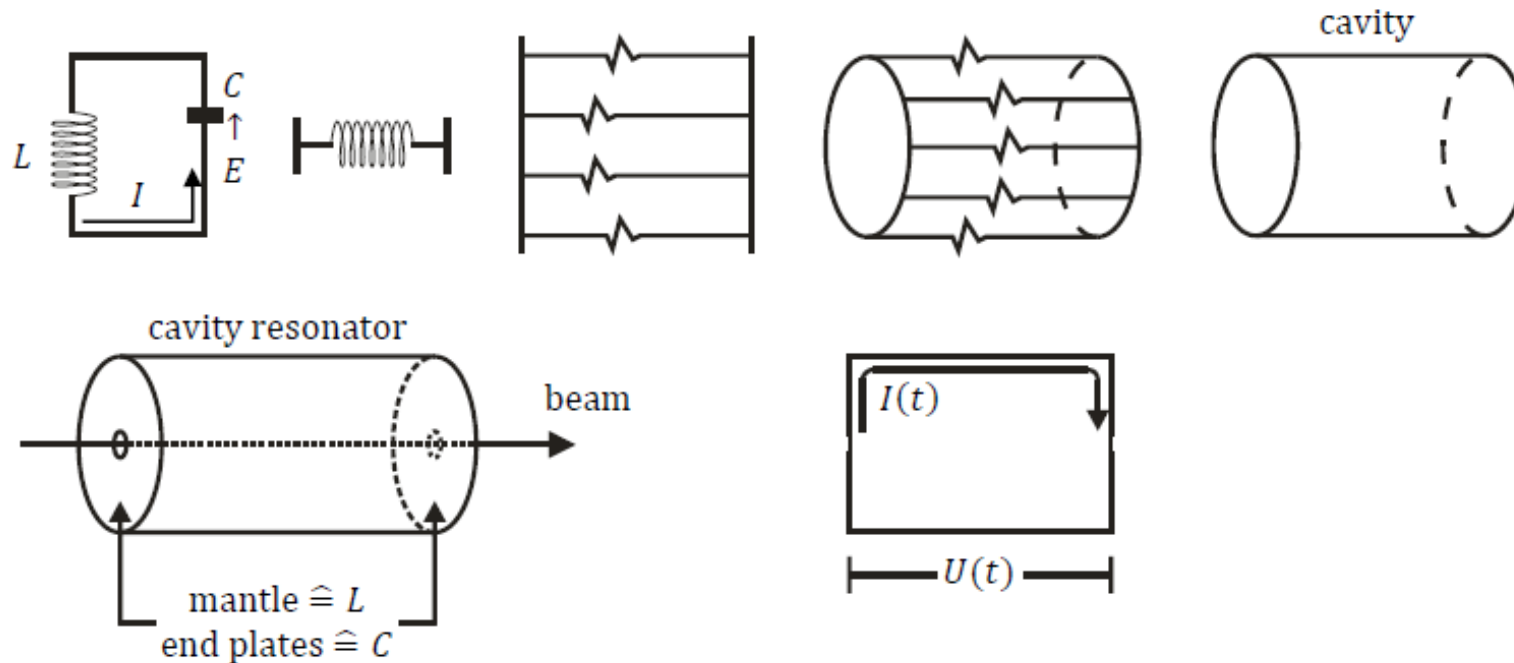


dc E-field strength $\leq 2 \frac{kV}{m}$, stronger \rightarrow arc discharge

max. accelerating E-field strength $\approx \omega^n$

$n: n(\omega, \text{material, geometry, rf pulse shape})$

n is under research!



cavity houses resonating em fields $E_0 \gg 2 \frac{kV}{m}$ and can be evacuated !!!

field description \rightarrow Maxwell's equations + boundaries

Accelerating Cavities



Maxwell's equations in vacuum:

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}; \quad \vec{\nabla} \times \vec{E} = -\dot{\vec{B}}$$

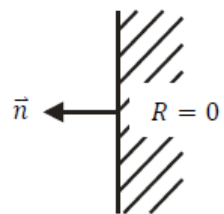
$$\vec{\nabla} \cdot \vec{B} = 0; \quad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \dot{\vec{E}}$$

$$c^2 = \frac{1}{\mu_0 \epsilon_0}; \quad \rho = 0; \quad \vec{J} = 0$$

$$\vec{\nabla}^2 \vec{E} - \frac{1}{c^2} \ddot{\vec{E}} = 0$$

boundaries:

vacuum sc-material



$$\vec{E} \times \vec{n} = 0, \quad E_{\parallel} = 0$$

suppose \vec{E}



$$\vec{E} \rightarrow \vec{J}$$

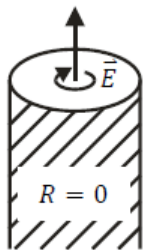
→ redistribution of charges

→ \vec{E} cancelled

$$\vec{B} \cdot \vec{n} = 0, \quad B_{\perp} = 0:$$

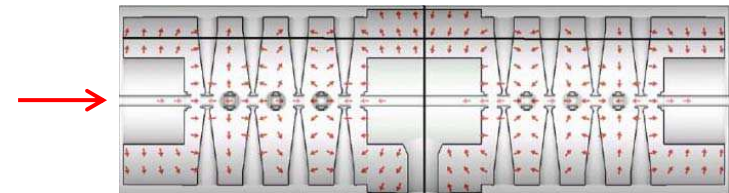
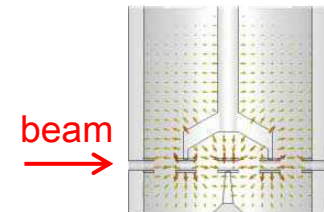
suppose $B_{\perp} \neq 0 \rightarrow$ at some $t < t_0$:

$$\dot{B}_{\perp} \neq 0, \quad \dot{B}_{\perp} = -\vec{\nabla} \times \vec{E}$$



\vec{E} will cause $\vec{J} \sim \vec{E}$

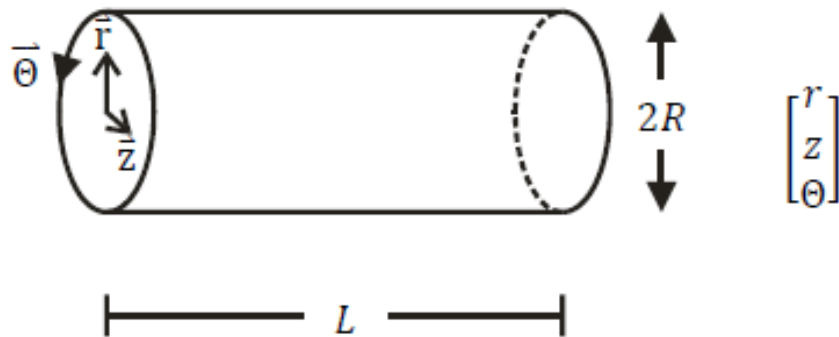
\vec{J} will cause \vec{B}_{\perp} opposite to $\vec{B}_{\perp} \rightarrow \vec{B}_{\perp}$ cancelled



e.m. field configuration in cavity ruled by:

- wave equation from Maxwell
- boundaries imposed by cavity inner surface shape

Simplest Cavity (Pillbox)



boundaries at material surface impose:

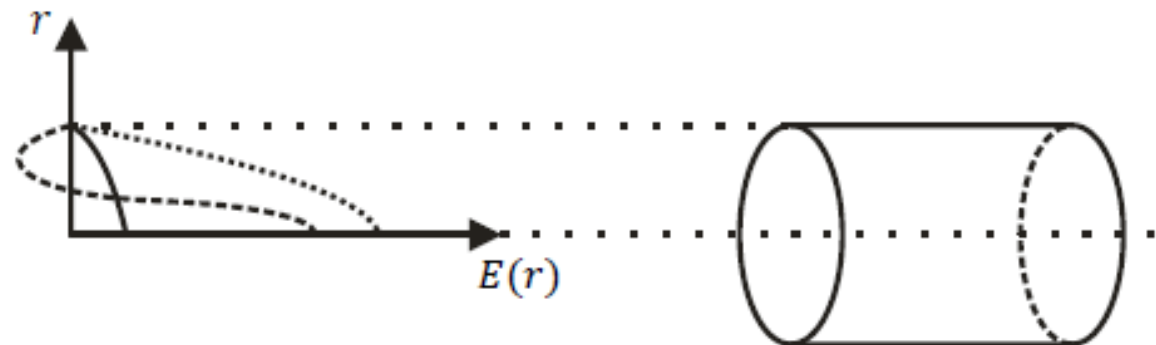
$$B_r(r = R) = 0 \quad B_z(z = 0, z = L) = 0$$

$$E_z(r = R) = E_\theta(r = R) = 0$$

$$E_r(z = 0, z = L) = 0$$

simplest Ansatz:

$$\vec{E} = \vec{e}_z \cdot E(r) \cdot e^{i\omega t}$$



Simplest Cavity (Pillbox)



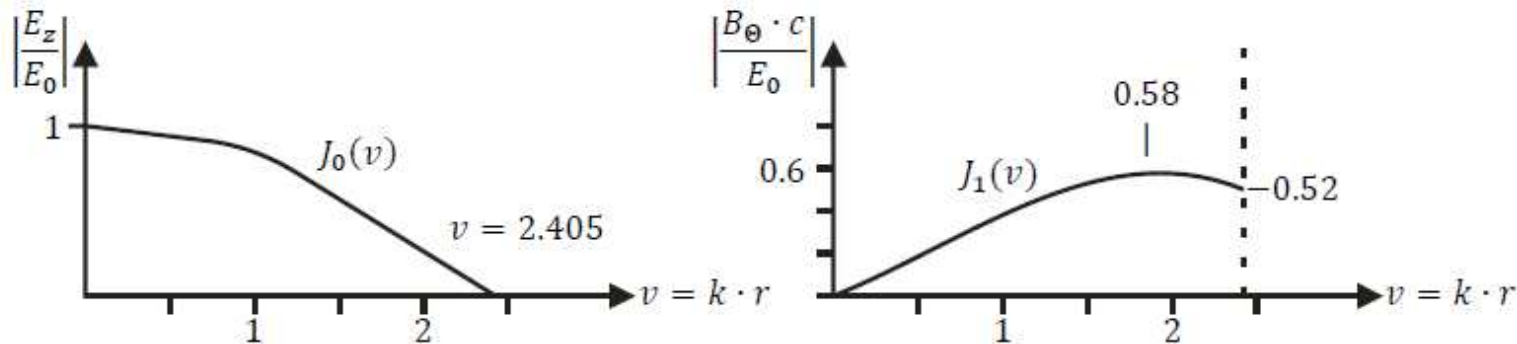
Wave equation + pillbox-geometry boundaries → Bessel diff equ. in r

$$\Rightarrow E(v) = E_0 \cdot J_0(v) \cdot e^{i\omega t} = E_z = \bar{E}(t, r)$$

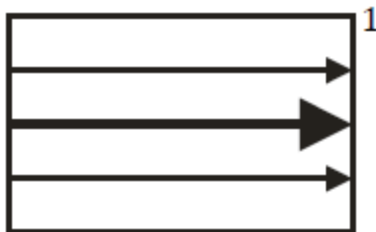
$$\bar{B}(v) = -\frac{E_0}{c} i \cdot J_0(v) \cdot e^{i\omega t} = B_\theta = \bar{B}(t, r), \quad \text{phase shifted } i \hat{=} 90^\circ$$

$$k^2 := \frac{\omega^2}{c^2}, \quad r = \frac{v}{k}$$

simplest case:



$\vec{E}: \vec{E} = E_z$, i.e. longitudinal:



$$f(R) = 114.75 \text{ MHz} \cdot \frac{1}{R[m]}, \quad \frac{\partial f}{\partial L} = 0 !$$

Pillbox with Drift Tubes



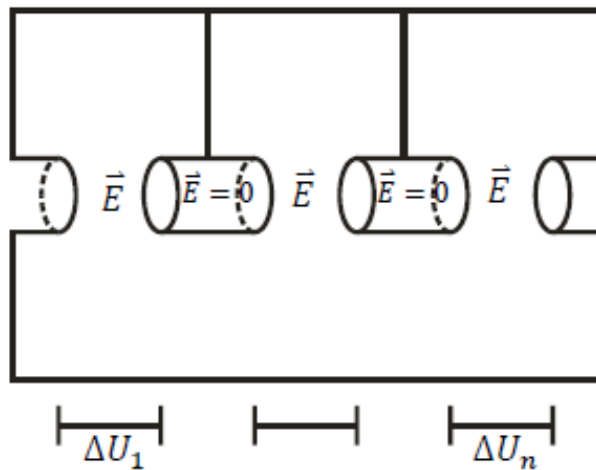
- ▶ sign of \vec{E} oscillates → how to accelerate?

- ▶ avoid “bad polarity”



long pill box not suitable for acceleration

drift tubes:

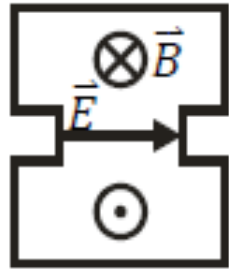


$$U_{tot} = \sum U_i$$

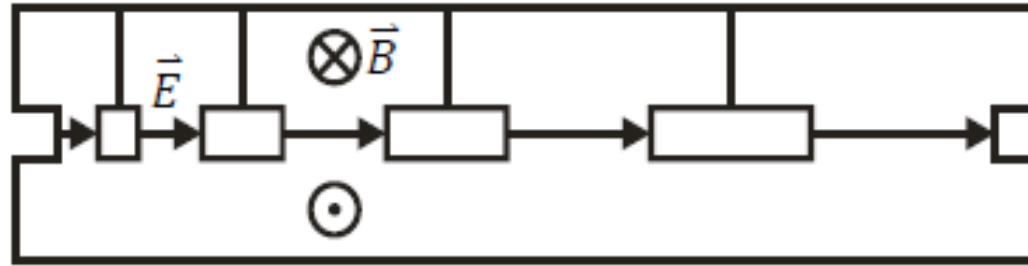
- ▶ no \vec{E} inside tubes
- ▶ \vec{E} between tubes
- ▶ tubes are voltage-dividers
- ▶ $\vec{E} \rightarrow$: part between tubes
- ▶ $\vec{E} \leftarrow$: part inside tubes
- ▶ DTL: Drift Tube Linac



Alvarez-Cavity Drift Tube Linac

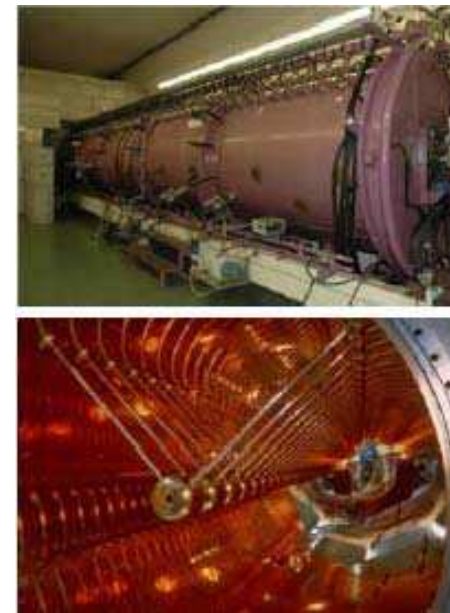


Pillbox



Alvarez

lengths of drift tubes increases since : $\omega_{rf} = \text{const}$, but part. velocity increases



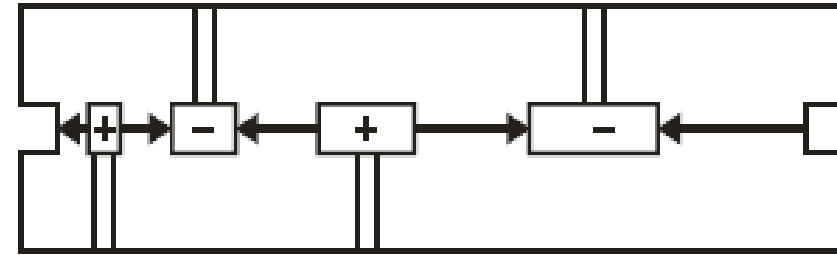
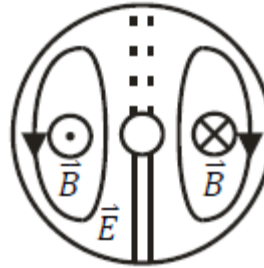
Other Cavity Types (examples)



H-Field Mode Cavity

from entrance:

from side:



standing e.m. wave cavities non-relativistic part. velocities

Quarter - Wave Resonator (QWR):



boundaries:

$$E_r(z = L) = 0 \rightarrow L = (2n - 1) \cdot \frac{\lambda}{4}$$

$$\downarrow$$

$$f = 75 \text{ MHz} \cdot \frac{2n - 1}{L[m]}$$

travelling wave, relativistic

30 GHz, 170 MV/m, 60 ns



2.9978 GHz Trav.Wave Cavity,
SLAC, California, U.S.A.



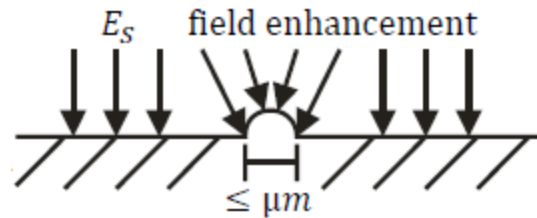
NLC/GLC, SLAC/KEK
11 GHz, 65 MV/m, 400 ns



High Voltage Sparking



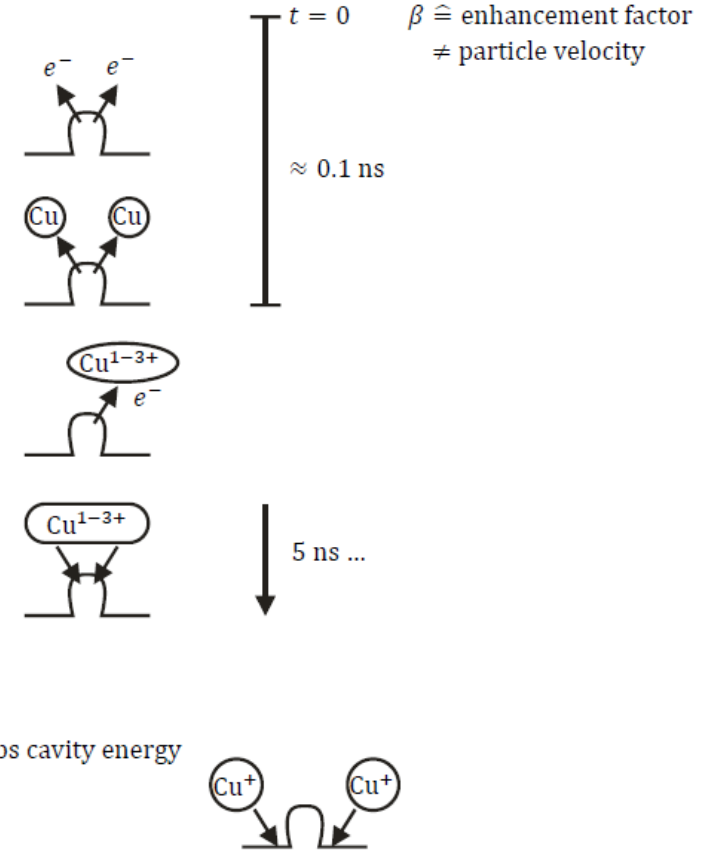
surface field E_S is limited



- nc-cavities:
- ▶ dirt
 - ▶ impurities
 - ▶ scratches
 - ⋮

break down process:

- ▶ local field $\rightarrow E_{S,L} = \beta_L \cdot E_S$
 - ▶ local current, e^- pulled up, heating, P_{loss}
 - ▶ emission of neutrals
 - ▶ ionization of neutrals
 - ▶ ion layer increases $E_{S,L}$
 $E_{S,L} > 10 \text{ GeV/m}$
 - ▶ exp. process
 - ▶ plasma (conducting)
 - el. short cut, which absorbs cavity energy
 - ions impact on surface
- \rightarrow damage



usual cavities: $E_S \leq 6E_{acc}$

E_S minimized: elliptical shape



$$\frac{E_S}{E_{acc}} \approx 2$$

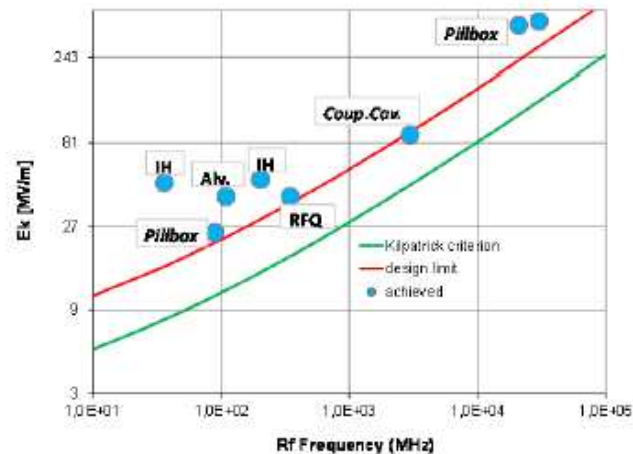
High Voltage Sparking



$E_{S,max}$ [material, ω , geometry, rf-pulse shape, surface treatment, "history"] under investigation!

Empirical (from late 40ies):

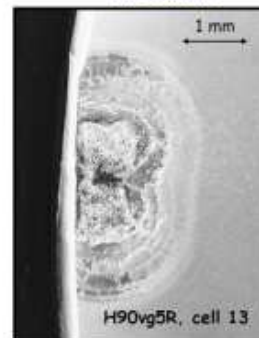
Kilpatrick-Criterion: $f[\text{MHz}] = 1.64 \cdot E_k^2 \cdot e^{\frac{8.5}{E_k^2}}$



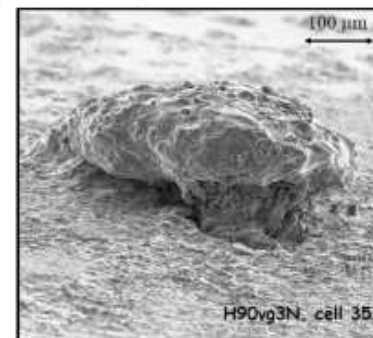
What Happens in an RF breakdown



Aluminum



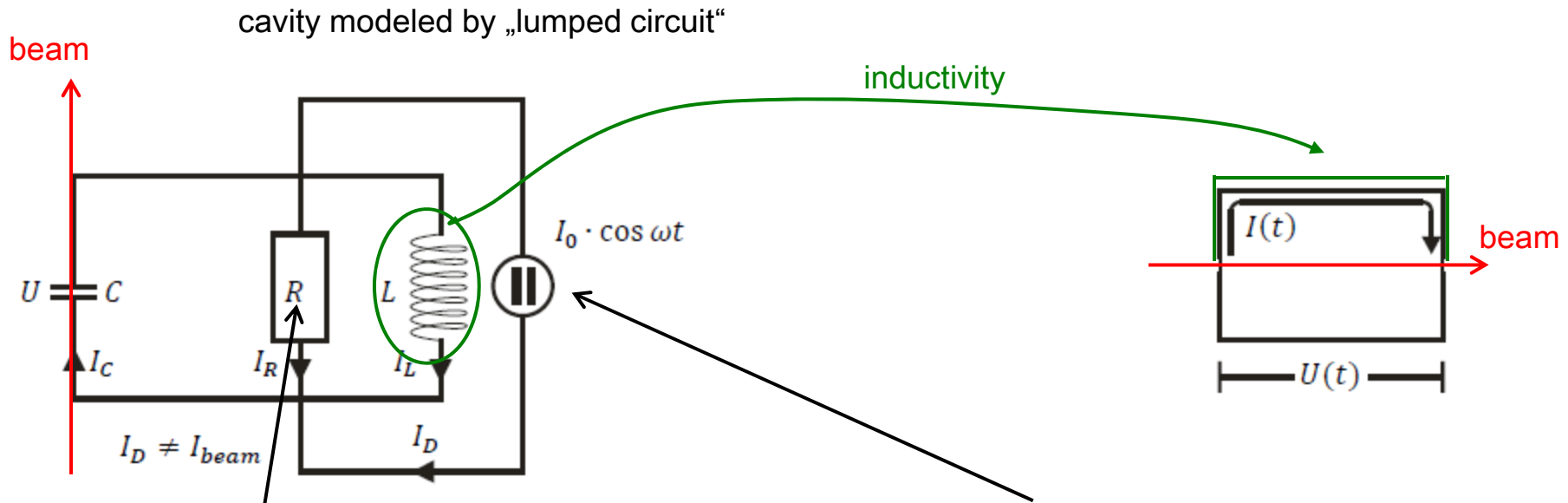
Stainless steel



Conditioning:

1. increase E_S until break down
 2. stop rf after break down
- burning away imperfections \approx several days!

Radio Frequency (RF) Power Sources



- ohmic losses (surface currents)
- R : the higher, the better !!

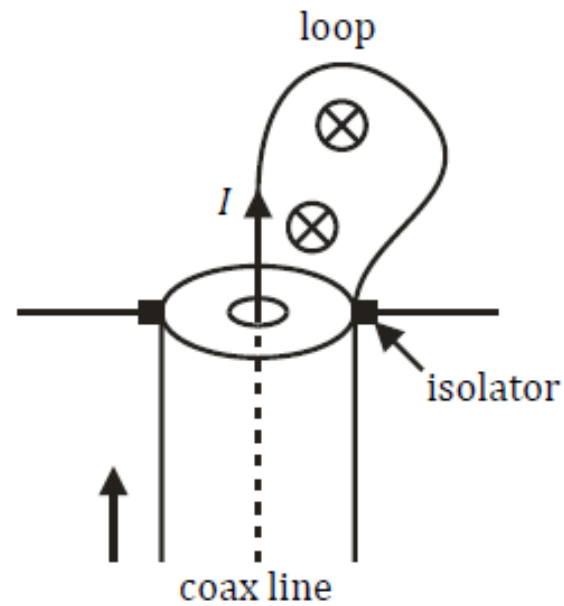
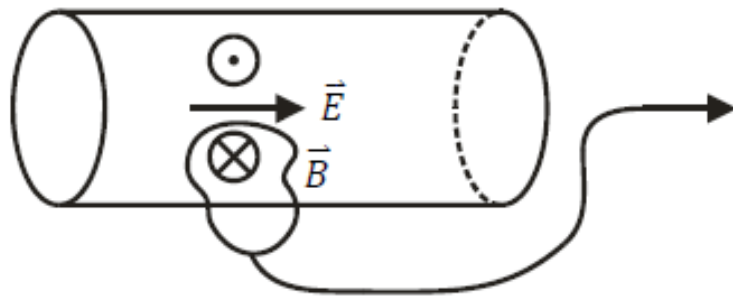
- compensation of ohmic losses (kW – MW)
- energy gain of particle beam (kW – MW)

Coupling Rf-Power into Cavity



Rf-Coupling:

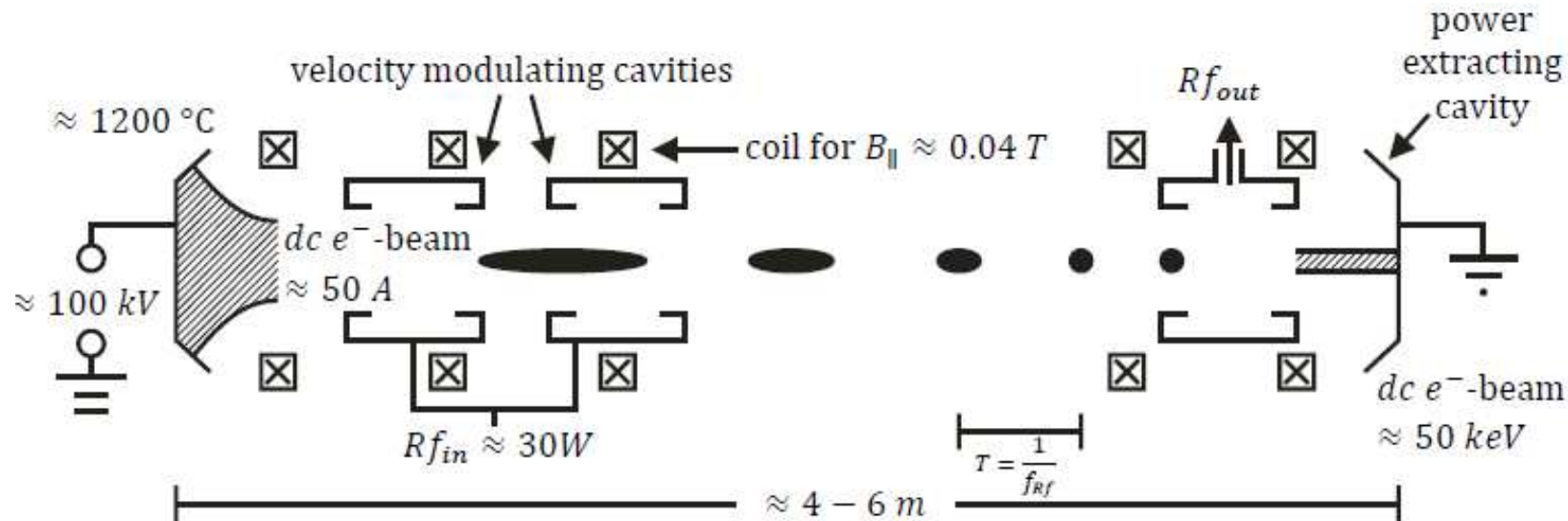
standing wave cavity:



inductive coupling: Alvarez, IH, CH, Pillbox



Klystron (example for rf-power source)



Gain $G \approx \frac{\text{Power } Rf, \text{ out}}{\text{Power } Rf, \text{ in}}$ measured in dB $1\text{ dB} \hat{=} \text{factor } 10$ $n\text{ dB} \hat{=} \text{factor } 10^n$

$\approx 50\text{ dB}$

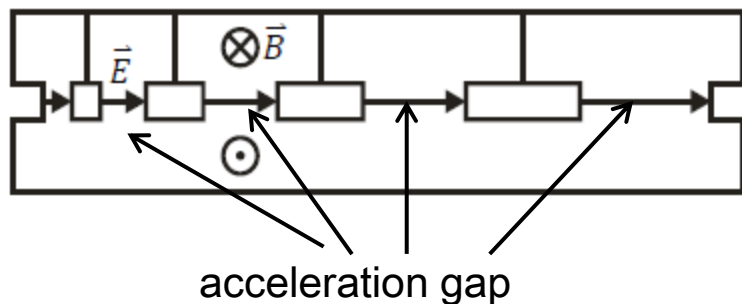
Efficiency $\eta := \frac{\text{Power } Rf, \text{ out}}{\text{e-Beam Power}}$

$\approx 40\% - 50\%$

power levels: kW– GW (cw – pulsed operation)

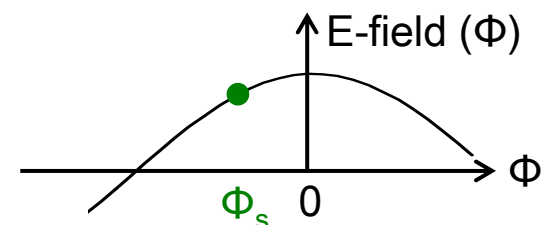


Longitudinal Beam Focusing and Stability



design (perfect) particle:

- ▶ τ_s from gap to gap
- ▶ energy gain ΔE_s per gap $\sim E_0 \cos(\Phi_s)$
- ▶ arrival at $\phi_i = \phi_s$ $s \hat{=}$ "synchronous"
- ▶ $E = E_{s,n}$ at gap, = kin. + rest energy



all gaps:

- operate at $\omega_{rf} = \text{const.}$
- are phase-locked

real particle i:

- arrives at gap n with phase $\Phi_{i,n} \neq \Phi_s$
- arrives at gap n with $E_{i,n} \neq E_{s,n}$
- gains $\Delta E_{i,n} \neq \Delta E_{s,n}$

Longitudinal Beam Focusing and Stability



defining:

- $\delta E :=$ (real energy – design energy) @ gap
- $\Phi :=$ real phase at gap

one finds the following equations for δE and Φ :

$$\delta E^2 + \frac{\beta^2 \cdot e \cdot q \cdot U \cdot E_s}{\pi \cdot h \cdot \eta} \cdot [\Phi \cdot \cos \Phi_s - \sin \Phi] = C$$

$$\delta \ddot{\Phi} \approx -\frac{2\pi h \cdot \eta}{\tau^2 \cdot \beta^2} \cdot \frac{e \cdot q \cdot U}{E_s} \cdot \sin \Phi_s \cdot \delta \Phi$$

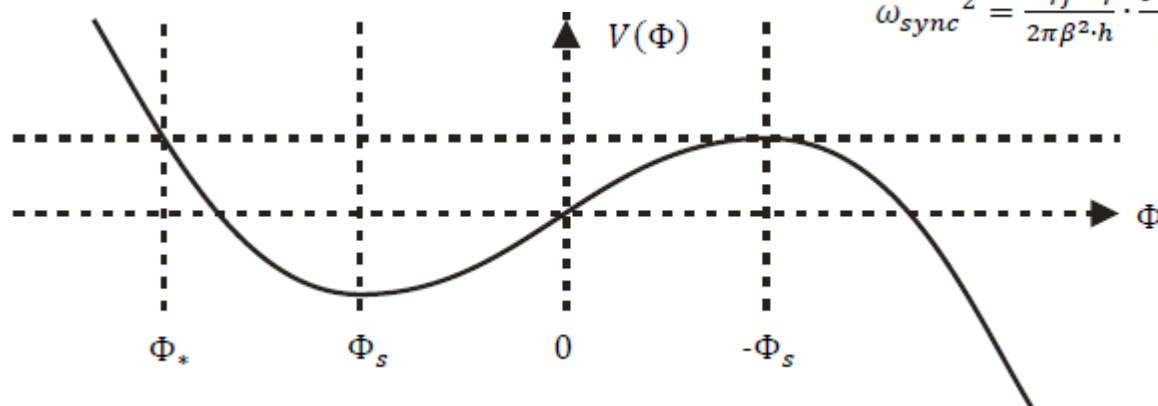
$$\eta := -\gamma^2, \quad h=1$$

$$\delta E^2 + V(\Phi) = C$$

$$\delta \Phi = A \cdot e^{i\omega_{sync} t}$$

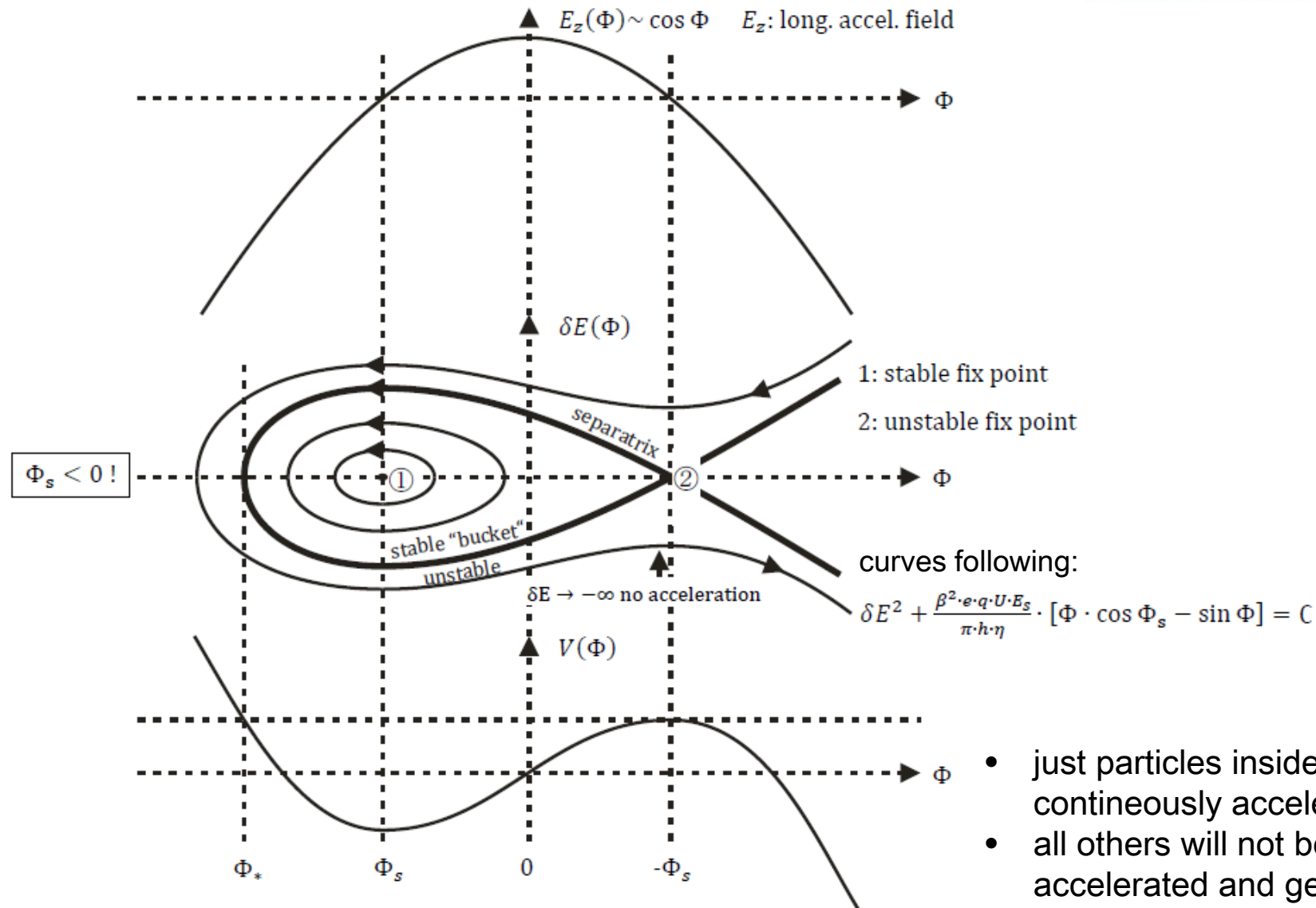
U = gap voltage

$$\omega_{sync}^2 = \frac{\omega_{rf}^2 \cdot \eta}{2\pi \beta^2 \cdot h} \cdot \frac{e \cdot q \cdot U}{E_s} \cdot \sin \Phi_s$$



- potential $V(\Phi_s)$ allows for stable (quasi-oscillating) motion around Φ_s
- $\Phi_* \approx 2\Phi_s$

Longitudinal Beam Focusing and Stability



- just particles inside bucket are continuously accelerated
- all others will not be accelerated and get lost

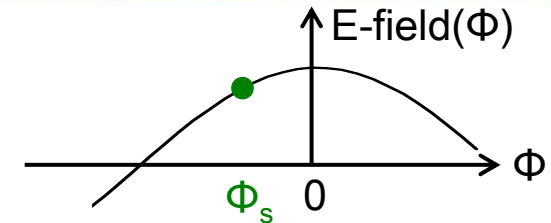
Longitudinal Beam Focusing and Stability



$$\text{acceleration: } \cos \Phi_s > 0 \rightarrow -\frac{\pi}{2} < \Phi_s < \frac{\pi}{2}$$

$$\omega_{sync}^2 > 0 \rightarrow -\pi < \Phi_s < 0$$

$$\rightarrow \text{stable acceleration for } 0 > \Phi_s > -\frac{\pi}{2}$$



Particles sufficiently close to Φ_s are longitudinally focused. But this leads to :

Transverse gap defocusing

$$\text{inside gap: } \vec{E} = -\vec{\nabla}\Psi; \vec{\nabla} \cdot \vec{E} = 0$$

$$\vec{\nabla} \cdot \vec{E} = -\vec{\nabla}^2\Psi \Rightarrow \frac{\partial^2\Psi}{\partial x^2} + \frac{\partial^2\Psi}{\partial y^2} + \frac{\partial^2\Psi}{\partial z^2} = 0$$

$$\frac{\partial^2\Psi}{\partial x^2} + \frac{\partial^2\Psi}{\partial y^2} = -\frac{\partial^2\Psi}{\partial z^2}$$

$$\text{part inside bucket: focusing in } \Phi \hat{=} \text{ along } z \rightarrow \frac{\partial^2\Psi}{\partial z^2} > 0$$

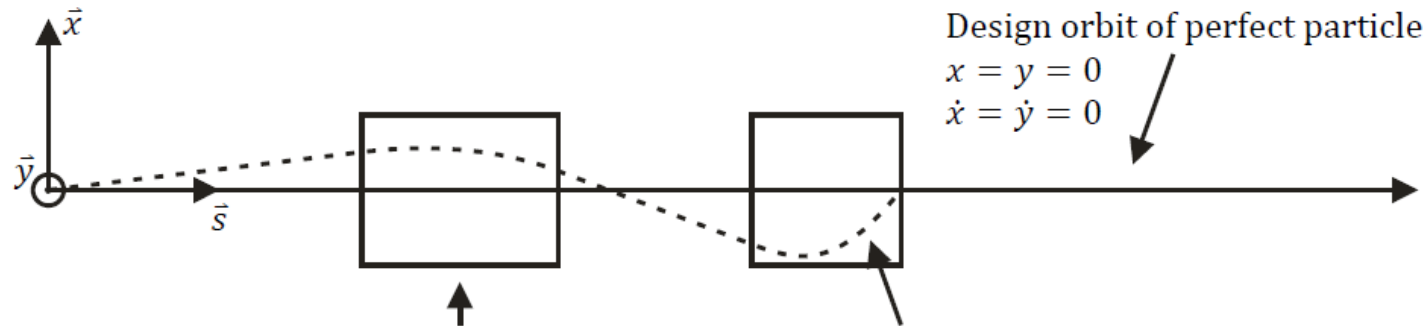
$$\rightarrow \left[\frac{\partial^2\Psi}{\partial x^2} + \frac{\partial^2\Psi}{\partial y^2} \right] < 0 \rightarrow \text{transverse defocusing!}$$

without transverse focusing, stable acceleration will cause transverse particle loss!

Transverse Beam Focusing and Stability

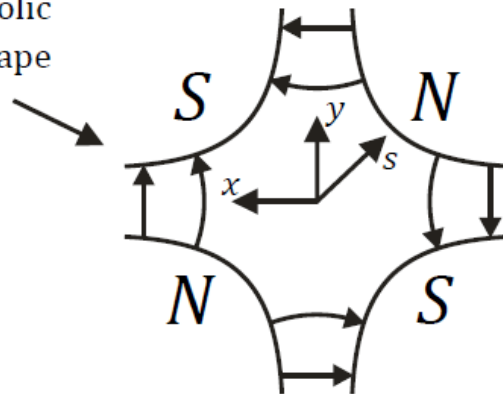


Transverse Differential Equations



- ▶ correction element for real particles i.e. $x \neq 0, y \neq 0, \dot{x} \neq 0, \dot{y} \neq 0$
- ▶ correction \sim displacement in x & y
- ▶ correction by quadrupoles (4-poles)

hyperbolic pole shape



$$\vec{B} = G \cdot \begin{bmatrix} y \\ x \\ 0 \end{bmatrix} \quad \begin{aligned} \vec{\nabla} \vec{B} &= 0 \\ \vec{\nabla} \times \vec{B} &= 0 \end{aligned}$$

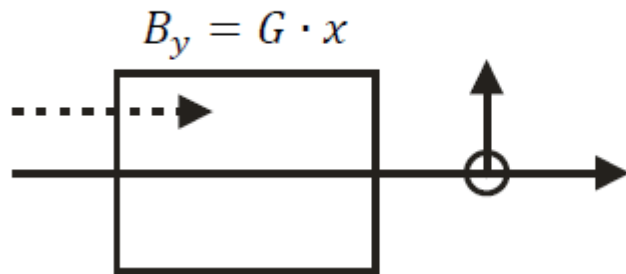
“Gradient $\left[\frac{T}{m} \right]$ ”

- ▶ focuses in x ($G > 0$)
- ▶ de-focuses in y ($G > 0$)
- ▶ $G < 0 \rightarrow$ vice versa

Transverse Beam Focusing and Stability



horizontal:



$$F_x = -q \cdot e \cdot v \cdot B = A \cdot m_0 \gamma \cdot \ddot{x}$$

$$-q \cdot e \cdot v \cdot B = A \cdot m_0 \gamma \cdot v^2 x'', \quad x'' := \frac{\partial^2 x}{\partial s^2}$$

$$x'' = -\frac{q \cdot e \cdot B}{A \cdot m_0 \gamma \cdot v} = -\frac{q \cdot e \cdot G}{p_0} \cdot x := -kx$$

$$= -kx$$

$$y'' = +ky$$

$$x = x_0 \cdot C + x'_0 \cdot S$$

$$\begin{bmatrix} x \\ x' \end{bmatrix} = \begin{bmatrix} C & S \\ C' & S' \end{bmatrix} \begin{bmatrix} x_0 \\ x'_0 \end{bmatrix} \quad \text{Wronsky matrix}$$

$$:= R \begin{bmatrix} x_0 \\ x'_0 \end{bmatrix}, \quad \det R = 1$$

$$\underline{k = \text{const.} < 0; \quad K := |k|}$$

$$C := \cosh[\sqrt{K}s], \quad S := \frac{1}{\sqrt{K}} \cdot \sinh[\sqrt{K}s]$$

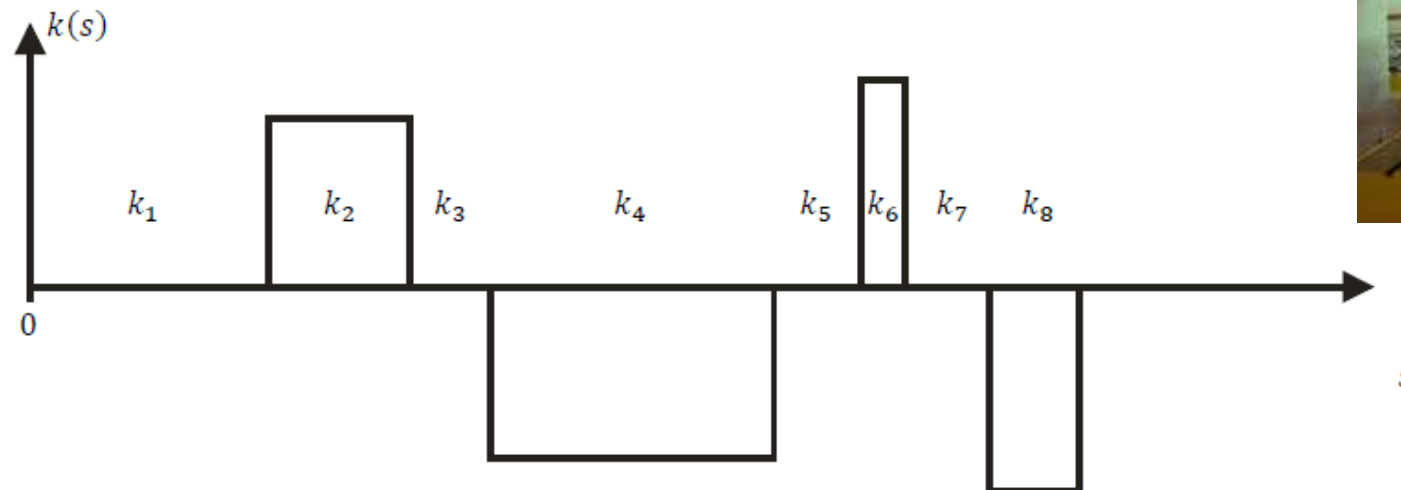
$$\underline{k = \text{const.} > 0}$$

$$C := \cos[\sqrt{k}s], \quad S := \frac{1}{\sqrt{k}} \cdot \sin[\sqrt{k}s]$$

Transverse Beam Focusing and Stability



- ▶ general solution too hard
- ▶ solve piecewise, since k is from finite elements



$$\begin{aligned} \begin{bmatrix} x \\ x' \end{bmatrix}_s &= R[k_n] \cdot R[k_{n-1}] \cdots R[k_2] \cdot R[k_1] \cdot \begin{bmatrix} x_0 \\ x'_0 \end{bmatrix} \\ &= \tilde{R}[k_1 \dots k_n] \begin{bmatrix} x_0 \\ x'_0 \end{bmatrix}, \quad \det \tilde{R} = \det[k_1] \cdot \det[k_2] \cdots \det[k_{n-1}] \cdot \det[k_n] \\ &= 1 \cdot 1 \cdots 1 \cdot 1 = 1 \end{aligned}$$

Transport Matrices



Drift, i.e. $k \equiv 0$ $\begin{matrix} x'' = 0 \\ y'' = 0 \end{matrix}$ $\begin{matrix} C = 1, C' = 0 \\ S = s, S' = 1 \end{matrix}$ $R_{Dx} = R_{Dy} = \begin{bmatrix} 1 & s \\ 0 & 1 \end{bmatrix}$

$$R_D = \begin{bmatrix} [R_{Dx}] & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & [R_{Dy}] \end{bmatrix} = \begin{bmatrix} 1 & s & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & s \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

rf-gap:

$$k = \frac{E_0 \cdot L_{gap} \cdot T \cdot q \cdot e \cdot 2\pi n}{m_0 c^2 \beta^3 \gamma^3 \lambda} \cdot \sin \Phi_s$$

quadrupole:

$$R_q(k > 0) = \begin{bmatrix} \cos \Omega & \frac{1}{\sqrt{|k|}} \sin \Omega & 0 & 0 \\ -\sqrt{|k|} \sin \Omega & \cos \Omega & 0 & 0 \\ 0 & 0 & \cosh \Omega & \frac{1}{\sqrt{|k|}} \sinh \Omega \\ 0 & 0 & \sqrt{|k|} \sinh \Omega & \cosh \Omega \end{bmatrix} \begin{matrix} (x, x') \text{ oscillation} \\ (y, y') \text{ exp.growth} \end{matrix}$$

$$R_q(k < 0) = \begin{bmatrix} \cosh \Omega & \frac{1}{\sqrt{|k|}} \sinh \Omega & 0 & 0 \\ \sqrt{|k|} \sinh \Omega & \cosh \Omega & 0 & 0 \\ 0 & 0 & \cos \Omega & \frac{1}{\sqrt{|k|}} \sin \Omega \\ 0 & 0 & -\sqrt{|k|} \sin \Omega & \cos \Omega \end{bmatrix} \begin{matrix} (x, x') \text{ exp. growth} \\ (y, y') \text{ oscillation} \end{matrix}$$

$$R_{gap} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ -\frac{k}{2} & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & -\frac{k}{2} & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & k & 1 \end{bmatrix}$$

Envelope Equations



second order beam moments:

- ▶ $\langle x x \rangle := \frac{x_j \cdot x_j}{N}$; square of rms-beam size
- ▶ $\langle x x' \rangle := \frac{x_j \cdot x'_j}{N}$; rms-beam correlation
- ▶ $\langle x' x' \rangle := \frac{x'_j \cdot x'_j}{N}$; square of rms-beam divergence

beam moments matrix $M :=$
$$\begin{bmatrix} \langle xx \rangle & \langle xx' \rangle & \langle xy \rangle & \langle xy' \rangle \\ \langle x'x \rangle & \langle x'x' \rangle & \langle x'y \rangle & \langle x'y' \rangle \\ \langle yx \rangle & \langle yx' \rangle & \langle yy \rangle & \langle yy' \rangle \\ \langle y'x \rangle & \langle y'x' \rangle & \langle y'y \rangle & \langle y'y' \rangle \end{bmatrix}$$

transport of beam moments from initial to final location:

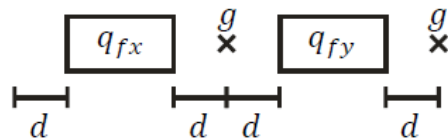
$$M_f := R M_i R^T$$

Periodic Lattice and Stable Envelope Criterion



Lattice: sequence of beam line elements

example:



d : drift

q_{fx} : horizontal focusing quadrupole

g : rf-gap

q_{fy} : vertical focusing quadrupole

Transport matrix: $R = R(g) \cdot R(d) \cdot R(q_{fy}) \cdot R(d) \cdot R(g) \cdot R(d) \cdot R(q_{fx}) \cdot R(d)$

Periodic Lattice $R_p = R^N$; $N = \#$ of lattice periods

when R^N is stable?

stable means $M_f = R^N M_i [R^N]^T \rightarrow \text{finite for } N \rightarrow \infty$

\Rightarrow lattice stable: $| \text{Trace}\{R\} | < 2$

example drift: $R(d) = \begin{bmatrix} 1 & L \\ 0 & 1 \end{bmatrix}$ $\text{Trace}\{R(d)\} = 2 \rightarrow \text{unstable}$

Radio Frequency Quadrupole (RFQ)



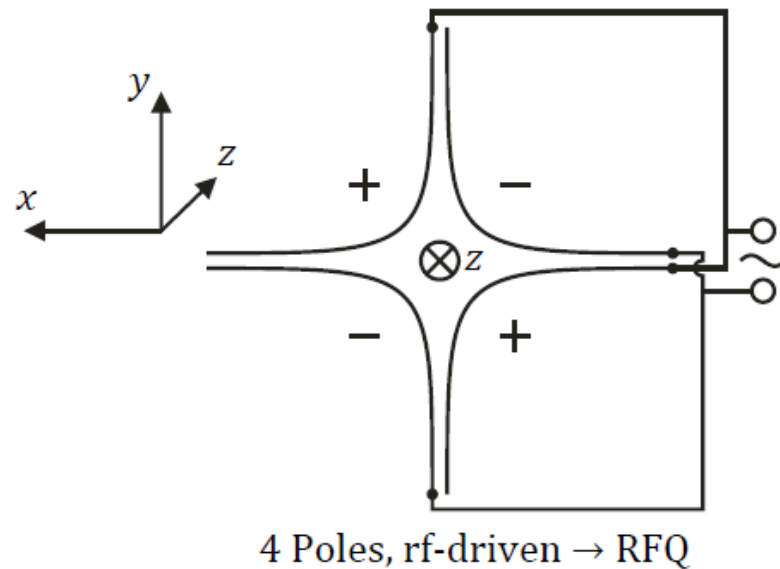
- ▶ Acceleration with static E -field: maximum beam energy limited by maximum dc-voltage that can be realized within reasonable dimensions. Limit is at some 10 MV.
- ▶ Dimensions can be decreased by using fields that oscillate in time $E(t) = E_0 \cos(\omega t)$
- ▶ Disadvantage of $E(t)$:
 - just particles that arrive within periodically occurring “good time slots” are accelerated
 - particles arriving outside a slot are decelerated, not accelerated, too weakly accelerated,
 - duration of “good slot” ΔT depends on frequency ω : $\Delta T \cdot \omega \approx 60^\circ$
 - beam durations from source/LEBT are much longer w.r.t. slot duration
 - particles outside slots will be lost
- ▶ Accelerate all particles, i.e. no losses:
 - need to arrange particles inside slots. This process is called “bunching”
 - particles within a “good slot” form the “bunch”
- ▶ Beam arranged into slots is “bunched beam”
- ▶ Bunched beam will de-bunch, i.e. exceed slot-border, if bunches are not kept together. This is due to tiny differences within individual particle velocities

Radio Frequency Quadrupole (RFQ)

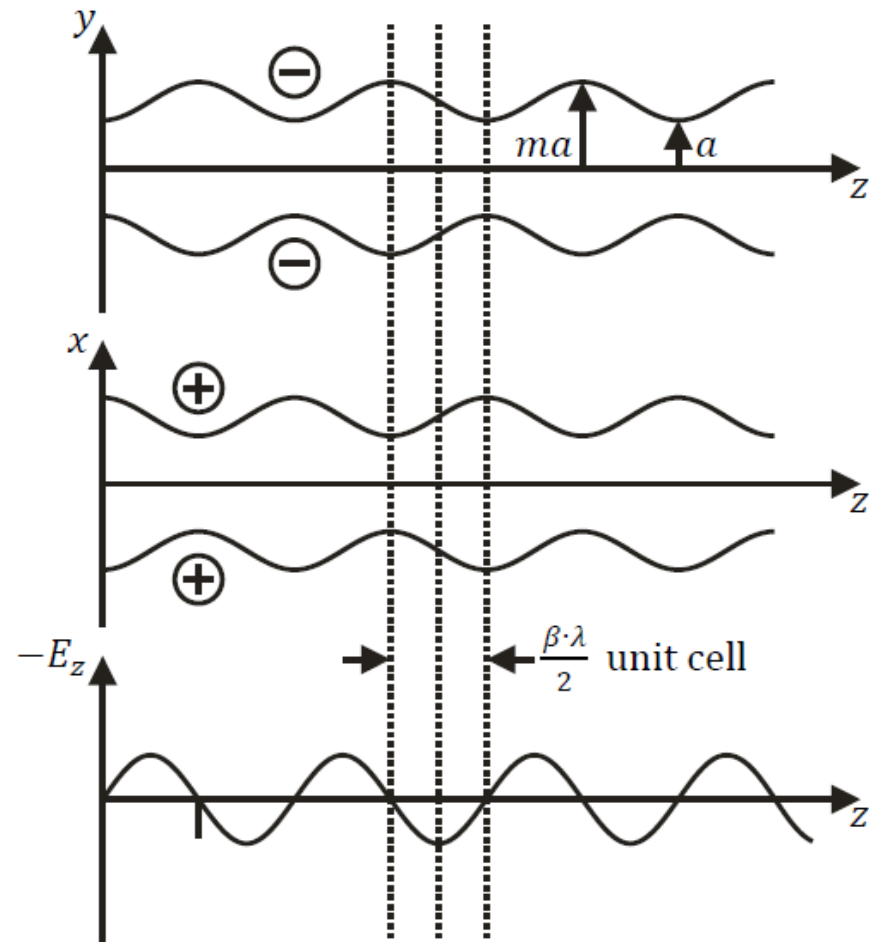


Bunching is done most efficiently (hadrons !) with Radio Frequency Quadrupole (RFQ):

bunching + focusing device:



- ▶ focusing in each plane changes with time
- ▶ particles move along z
- ▶ focusing varies along z
- net focussing like FODO



RFQ Example



HLI 4-rod RFQ, GSI/Germany



Deuterium - Uranium, length: 2.055 m, $\beta_{\text{in}} = 0.0023$, $\beta_{\text{out}} = 0.025$, res. frequency: 108.408 MHz

RFQ Example

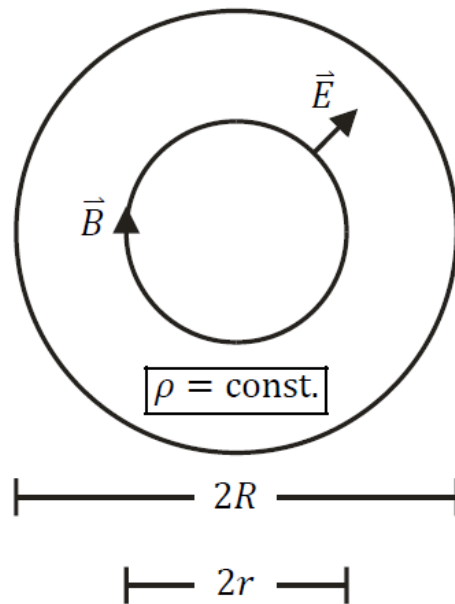


4-rod RFQ at SARAF/Israel



SARAF-RFQ: 3 MeV D⁺, res. frequency: 175 MHz, 250 kW CW

Defocusing from Beam Self Forces



$$E(r) = \frac{I \cdot r}{2\pi\epsilon_0 \cdot R^2 \cdot \beta \cdot c}$$

$$B(r) = \frac{\mu_0 \cdot I \cdot r}{2\pi R^2}$$

$$\ddot{r}_{sc} = \frac{e \cdot q}{A \cdot m_0 \cdot \gamma} [\vec{E} - \vec{v} \times \vec{B}] = \boxed{\ddot{r}_{sc} = \frac{e \cdot q \cdot I}{A \cdot m_0 \cdot \beta \cdot \gamma^3 \cdot 2\pi\epsilon_0 R^2 \cdot c} \cdot r} \quad \text{linear in } r!$$

↑ defocusing ↑ focusing

- full space charge (sc) is defocusing
- at relativistic energies sc forces vanish
- at low energies sc is very strong !

Reduction of Focusing Strength (Tune Shift)



space charge adds to diff. equation :

$$x'' + \left[k(s) - \frac{P}{R^2(s)} \right] x = 0 \quad \text{"Perveance" } P = \frac{e \cdot q \cdot I}{2\pi \epsilon_0 \cdot A \cdot m_0 \cdot c^3 \beta^3 \gamma^3}$$

dimensionless

$x(s)$ like harmonic oscillator $\sim e^{i\sqrt{k_{eff}} \cdot s}$

$$\sigma_{eff} := \frac{\text{phase advance}}{\text{length}} = \sqrt{k_{eff}}, \quad I \neq 0$$

$$\sigma_0 := \sqrt{k}, \quad I = 0$$

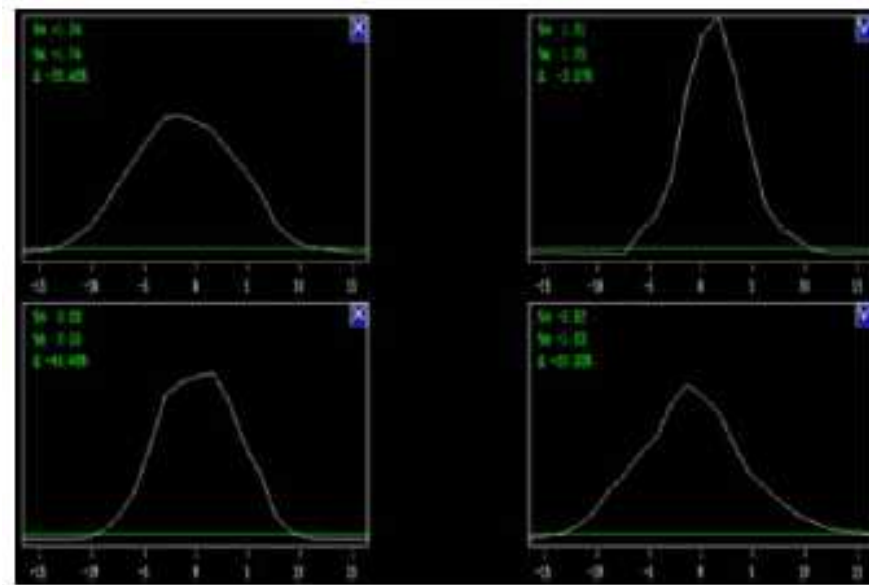
$$\rightarrow \boxed{\sigma_{eff}^2 = \sigma_0^2 - \frac{P}{R^2} := \sigma_0^2 - \text{sc-tune shift}}$$

$\sigma_{eff}^2 > 0$ limits achievable current

Tune Shift



transverse beam profiles



horizontal

vertical

$\rho = \text{const.}$ generally not true, generally ρ decreases with r

$$\rightarrow E(r) = \frac{\int_0^r \rho(r') r' dr'}{\epsilon_0 \cdot r} \rightarrow x'' + [k(s) + f(x)] \cdot x = 0 \quad \underline{\text{non-linear}}$$

non-linear forces reduce beam quality

