The image shows the TAIGA-IACT telescope, a large-scale particle detector. It features a red metal frame supporting a grid of approximately 20 white, circular Cherenkov detectors. A large, cylindrical photomultiplier tube is mounted on the right side of the frame. The entire structure is situated in a flat, snow-covered landscape under a twilight sky. A blue electrical control cabinet stands to the right of the main structure. The text is overlaid on a dark semi-transparent rectangle at the bottom of the image.

**First results of using CNNs for
estimation of primary particle energy
for the TAIGA-IACT telescope**

Introduction

- The first efforts to estimate energy of primary particles using CNN
- Based on small dataset (MC) with "soft" cleaning
- Framework: TensorFlow

The Dataset

- Events: 40768
- Protons/gamma: 20238 / 20530
- Soft cleaning 6pe-3pe
- Sample divided randomly into two sets: train (**80%**) & test (**20%**)
- Additional sample for "blind" check (14997 events)

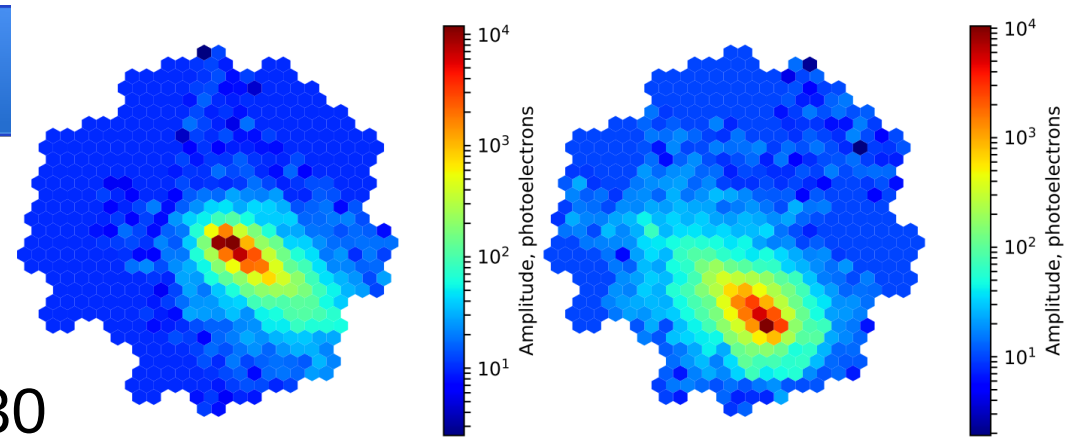
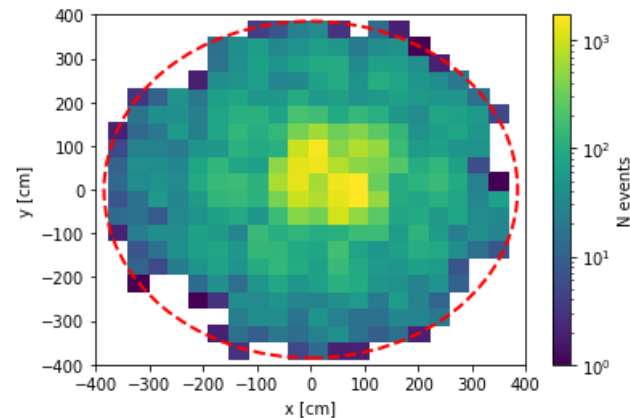
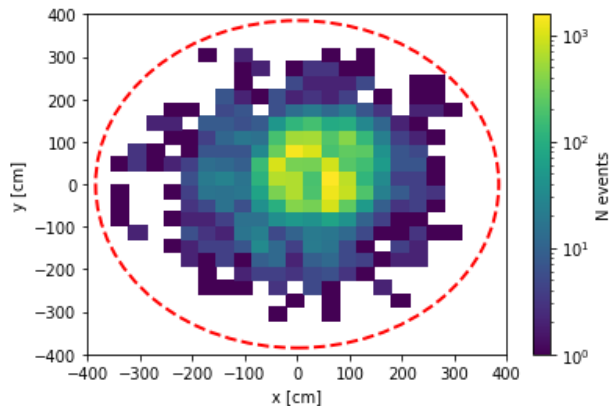
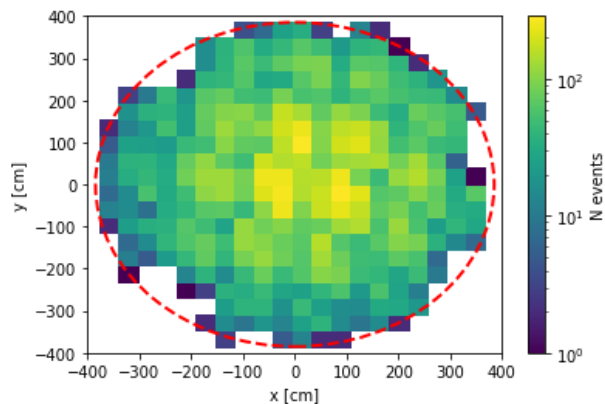


Image CoG distribution

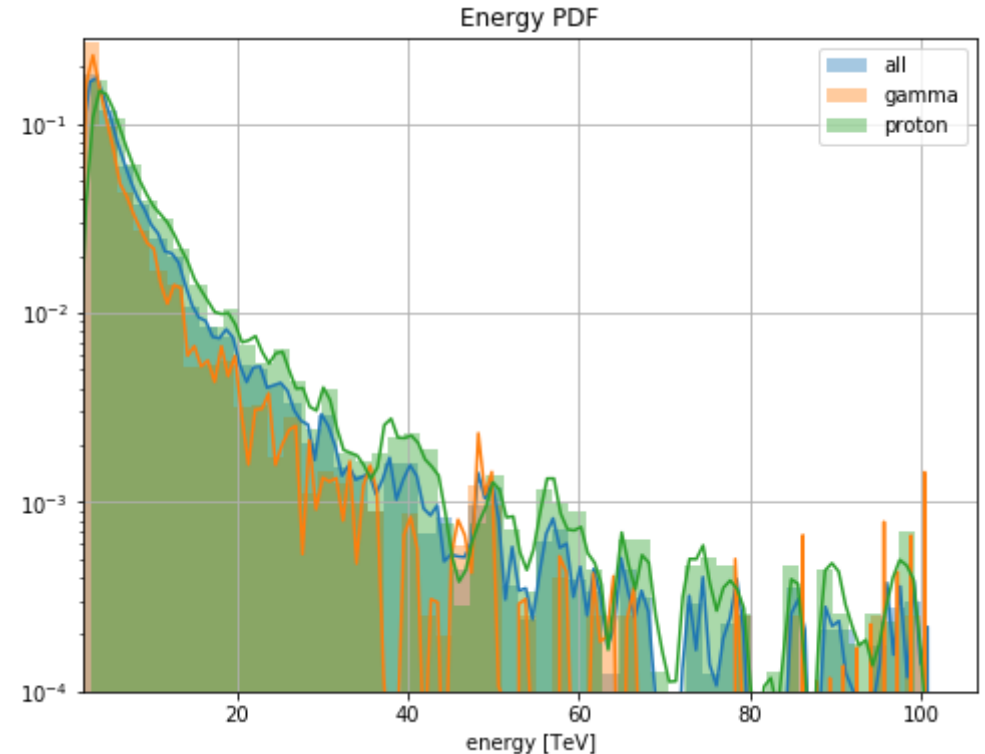
- Gamma-source is located in the camera center
- Proton images CoG dist \sim flat in camera coordinates



- Gamma images CoG mostly in the center of the camera

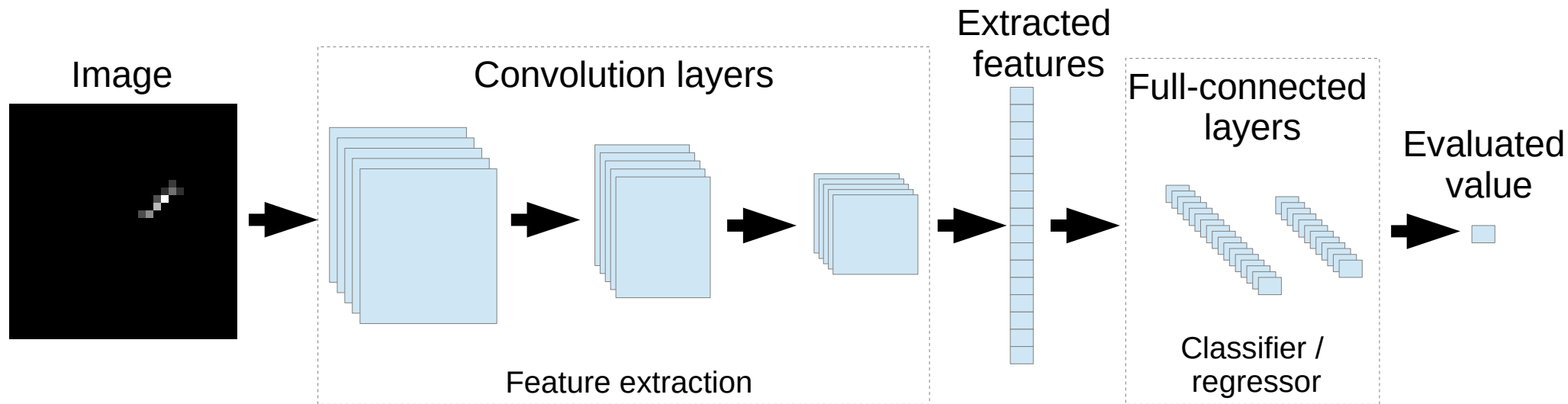
Energy distribution in sample

- Simulated events energy
 - Gamma 2 TeV - 100 TeV
 - Proton 3 TeV – 100 TeV
- 90 % with energy < 15 TeV



CNN architecture

- Convolution layers is used for feature extraction
- Full-connected layers is used for classification / regression



CNN for classification

- Input: Hexagonal image => oblique coordinates (31x32 pix)
- 3 convolution layers
 - 3x3 1x32 / 3x3 32x32 / 3x3 32x32
 - Averaged pooling ; Dropout 25%
 - ReLU activation
 - 288 extracted features
- 2 full-connected layers (32x16)
 - ReLU activation ; dropout 50%
- Output layer (2 neurons)
 - Sigmoid activation
- ~30k trained parameters

Data sample extension

- As dataset is not big enough (40K events) the sample for train was extended
- The images was rotated 5 time on 60 degrees around the center of the camera
- New sample for train: ~ 200K events

CNN for regression

- Input: Hexagonal image => oblique coordinates (31x32 pix)
 - 3 convolution layers (**Extracted from CNN for classification**)
 - 3x3 1x32 / 3x3 32x32 / 3x3 32x32
 - Averaged pooling ; Dropout 25%
 - ReLU activation
 - 288 extracted features
- 2 full-connected layers (32x16)
 - ReLU activation ; dropout 50%
- Output layer neuron
 - ReLU activation
- ~10k trained parameters

CNN for regression train

- To train the CNN all events was weighted using exponential fit of the primary energy pdf
- For the train all types of particles are used
- Mean square error is used as loss function

Results

- Currently the results of the achieved energy estimation are not good enough and are still in studying
- Events weighting method is not good enough and should be improved
- Other networks architectures and loss function should be tested

Future plans

- Continue studying of the event energy reconstruction
- More detailed studying of the particles classification (maybe it's worth to try to use Hillas parameters instead of Convolution layers)
- Tests for CNN with much bigger samples
- For the Hillas parameters extraction the **ctapipe** open python library can be used for the simulation and for real data analysis