Reconstruction radio signals from air-showers with autoencoder

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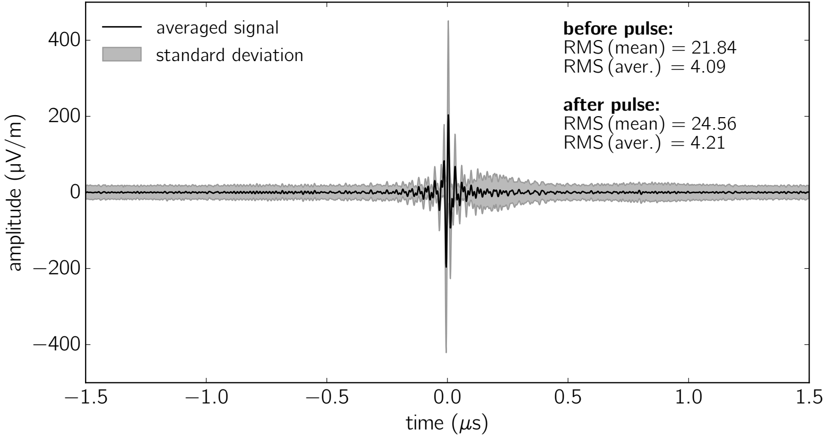
Deep learning: motivation



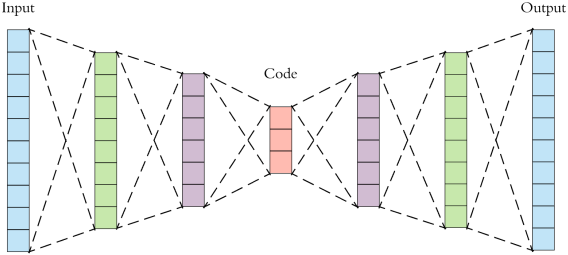
Average of 400 events, expected noise reduction with factor $\sqrt{400} = 20$

$\Rightarrow$ Noise is not white/contain features

$\Rightarrow$ Train autoencoder to learn these features

Chosen architecture (autoencoder)

- Unsupervised neural network with compressed representation
- Use Keras and Tensorflow with GPU support
- Based of 1D convolution layers
- ReLu ($\max(0, x)$) activation function
- Max pooling (and upsampling) after convolutional layers
- Binary crossentopy loss function and RMSprop optimizer
- Train networks via uDocker on SCC ForHLR II cluster



Learning strategy and training pipeline

Datasets:

- 25k upsampled ($\times 16$) traces with real background + low-amplitude simulations ($< 100\,\mu$V/m) with randomly located pulse

Training and evaluation:

- Depth (D) and number of filters per layer as free parameters
- Primary evaluate by loss metrics
- Blind test with full-pipeline Offline reconstruction

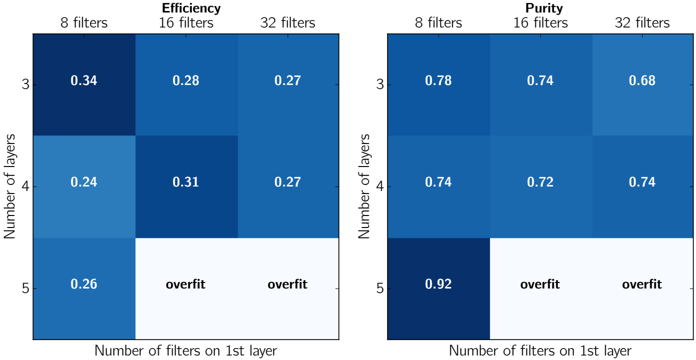
i-th encoding layer is described by the following ($i = 1, ..., D$):

$$S_i = S_{\min} \times 2^{D-i}\,,\ \ n_i = 2^{i+N-1}\,, \tag{1}$$

where S_i is a size of the i-th filter, n_i is a number of filters per layer
D and N are free parameters; $S_{\min} = 16$ is minimal size of layer
Size of input/output array: 4096 (1280 ns) – 25% of original trace

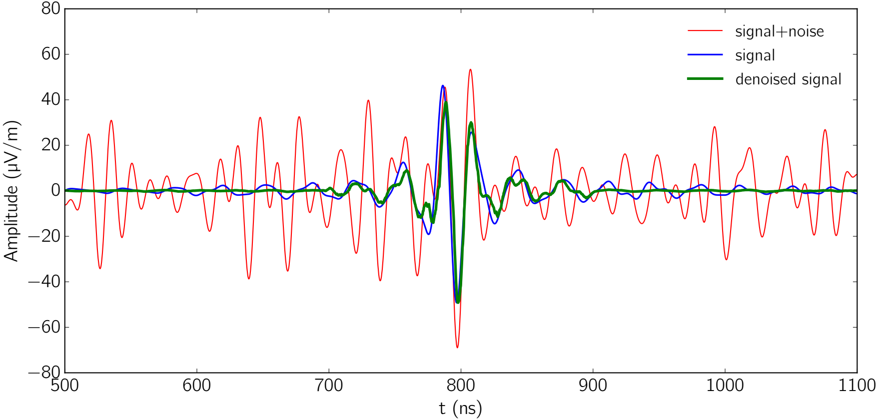
Threshold and metrics

- Threshold amplitude $\Leftrightarrow$ 5% tolerance to false positives
- Efficiency: $N_{\mathrm{rec.}}/N_{\mathrm{tot.}}$, fraction of events passed the threshold
- Purity: $N_{\mathrm{hit}}/N_{\mathrm{rec.}}$, fraction of events with reconstructed position of the peak: $|t_{\mathrm{rec.}} - t_{\mathrm{true}}| < 5$ ns



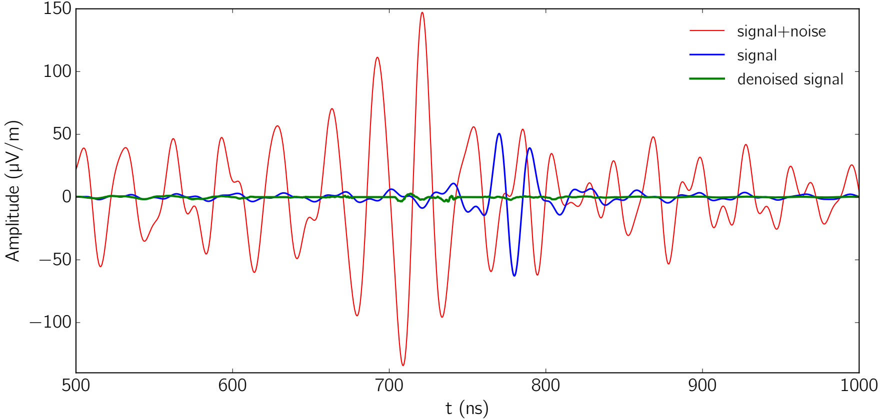
Best architecture contains $N_{\mathrm{dof}} = 10240$

Example: correct identification



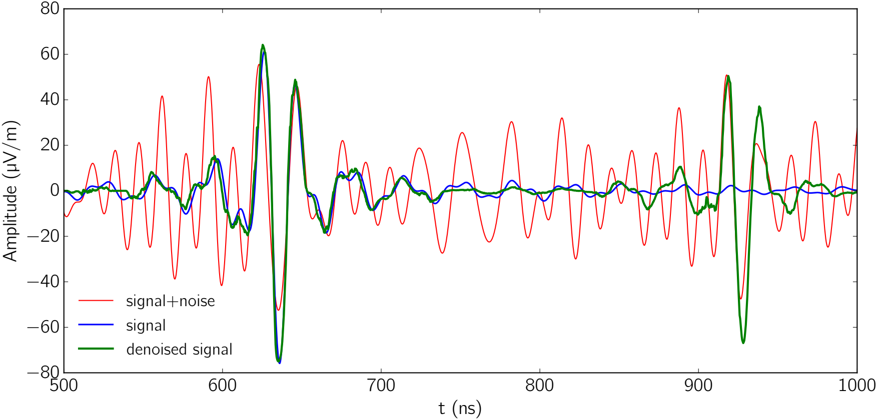
True signal and noise are identified correctly, noise is removed

Example: no identification



True signal is heavily distorted by noise, and removed as background

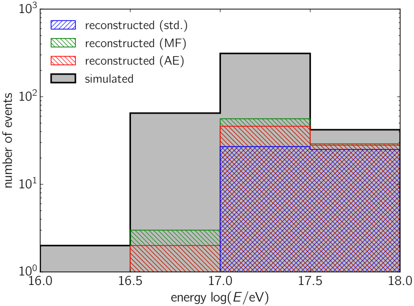
Example: double identification

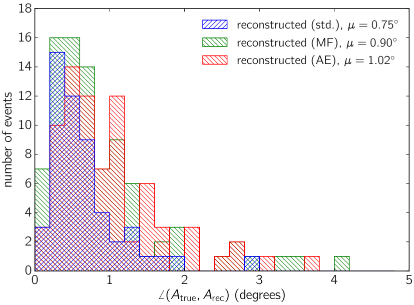


Signal-like RFI is identified as signal

Full-pipeline reconstruction with autoencoder

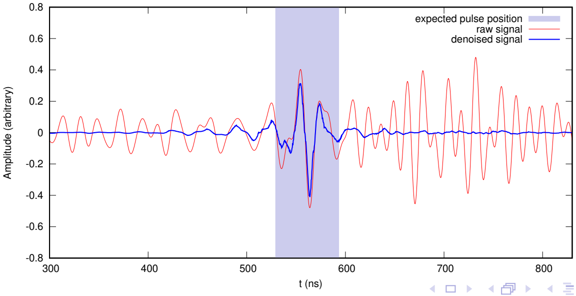
Autoencoder is binded with Tunka-Rex fork of Auger Offline
Reconstruction of CoREAS simulations (reproduction of 2012-2014 events)





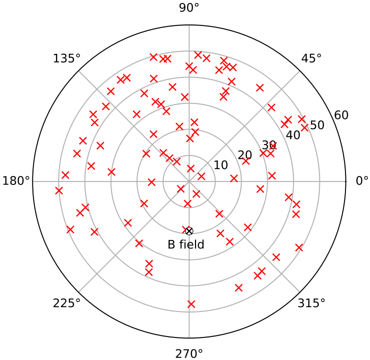
- Monte-Carlo tests show performance comparable to standard method and matched filtering
- "Stack more layers" works, but requires larger training sets
- Amplitude reconstruction degenerates when $\mathrm{SNR} < 1$
  trace is normalized to $[0; 1] \Rightarrow$ peak is hidden in noise

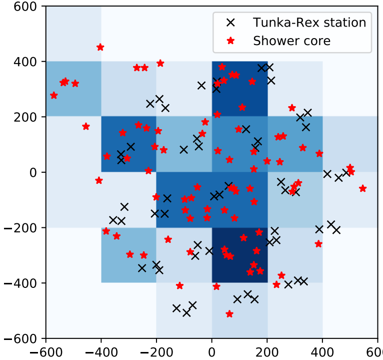
How to convince ourselves that the reconstruction is valid when the signal is not visible?



Data-driven benchmark

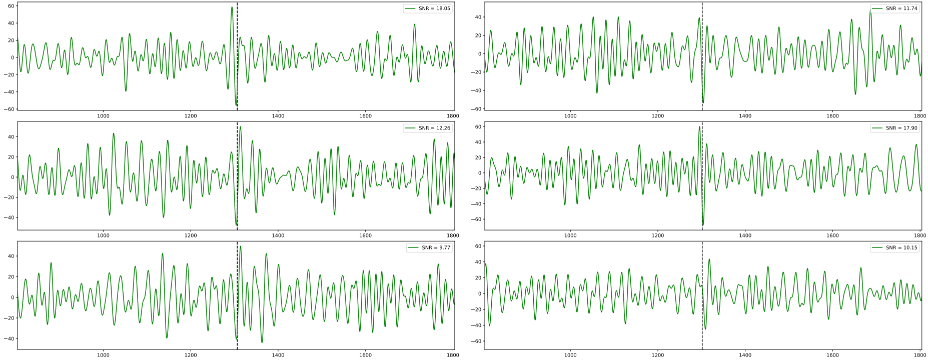
- Tunka-133/Tunka-Rex events with $E \in [10^{16} - 10^{17}]$ eV
- Almost zero events in this energy band by standard method
- Decreasing autoencoder threshold $0.395/0.500 \rightarrow 0.200/0.500$
- Cross-check cuts: direction reconstruction $\Delta\Omega < 5°$, clustering events



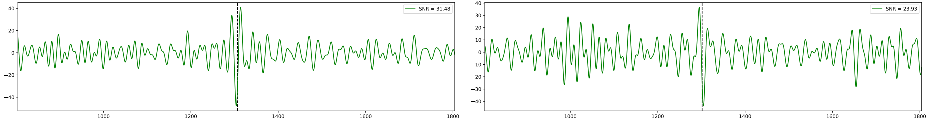


Example reconstruction

Two example events with $E = 30$ PeV

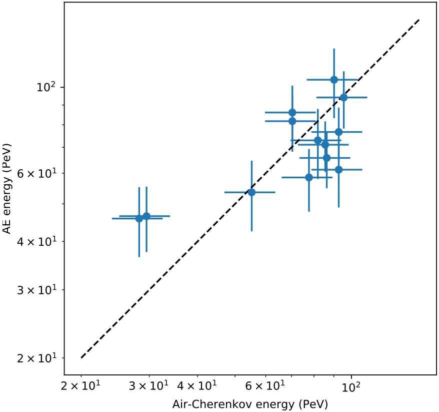


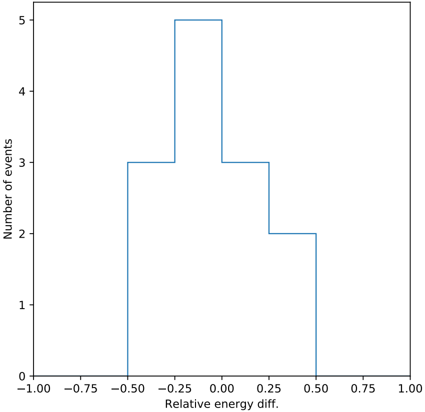
Coherent sum:



Energy reconstruction (after cuts)

Reconstruction based on single antenna method, $E = \kappa A_d e^{-\eta(d-d_0)}$
Normalization factor from standard reconstruction; $\mu = 0\%$, $\sigma = 26\%$





Conclusion

- The performance of Tunka-Rex autoencoder has been tested on real data
- Numbers of both true and false positives are increased when loosing cuts
- We can reconstruct arrival direction but struggling with energy reconstruction

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- Radio autoencoder can be used as self-trigger technique
- Need more sophisticated cuts to lower the threshold
- Need better training