

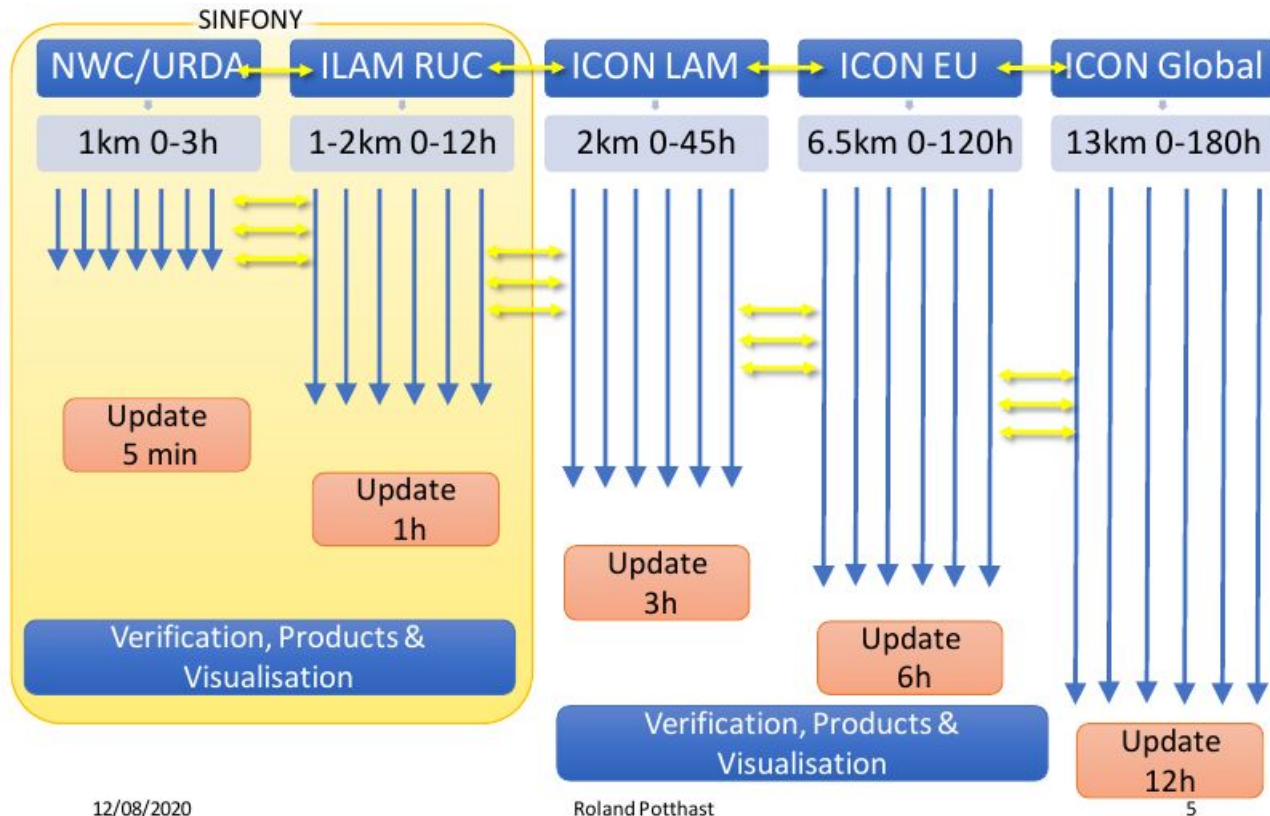
Towards Rapid Update Cycling of Cloud and Precipitation Observations at DWD

Lisa Neef¹

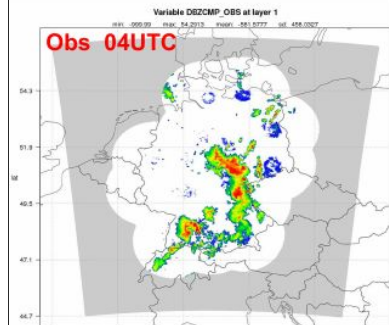
with input from: Lilo Bach^{1,2}, Kobra Khosravian¹, Christian Welzbacher¹, Uli Blahak¹

¹Deutscher Wetterdienst, ²MetBW Bundeswehr Geoinformation Service

Rapid Update Cycling in SINFONY

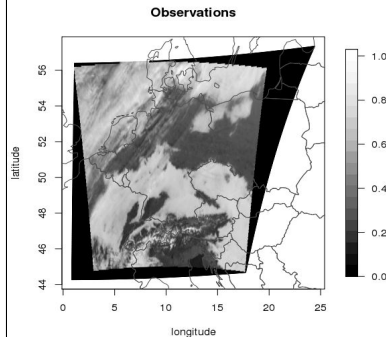


Radar



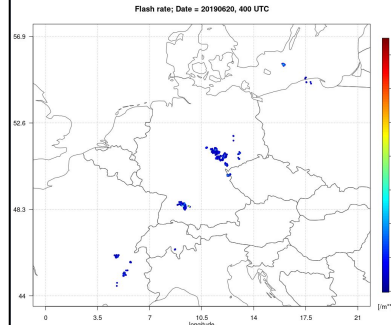
Precipitation

SEVIRI VIS Refl



Clouds & Cloud
Cover

Lightning



Cloud discharge

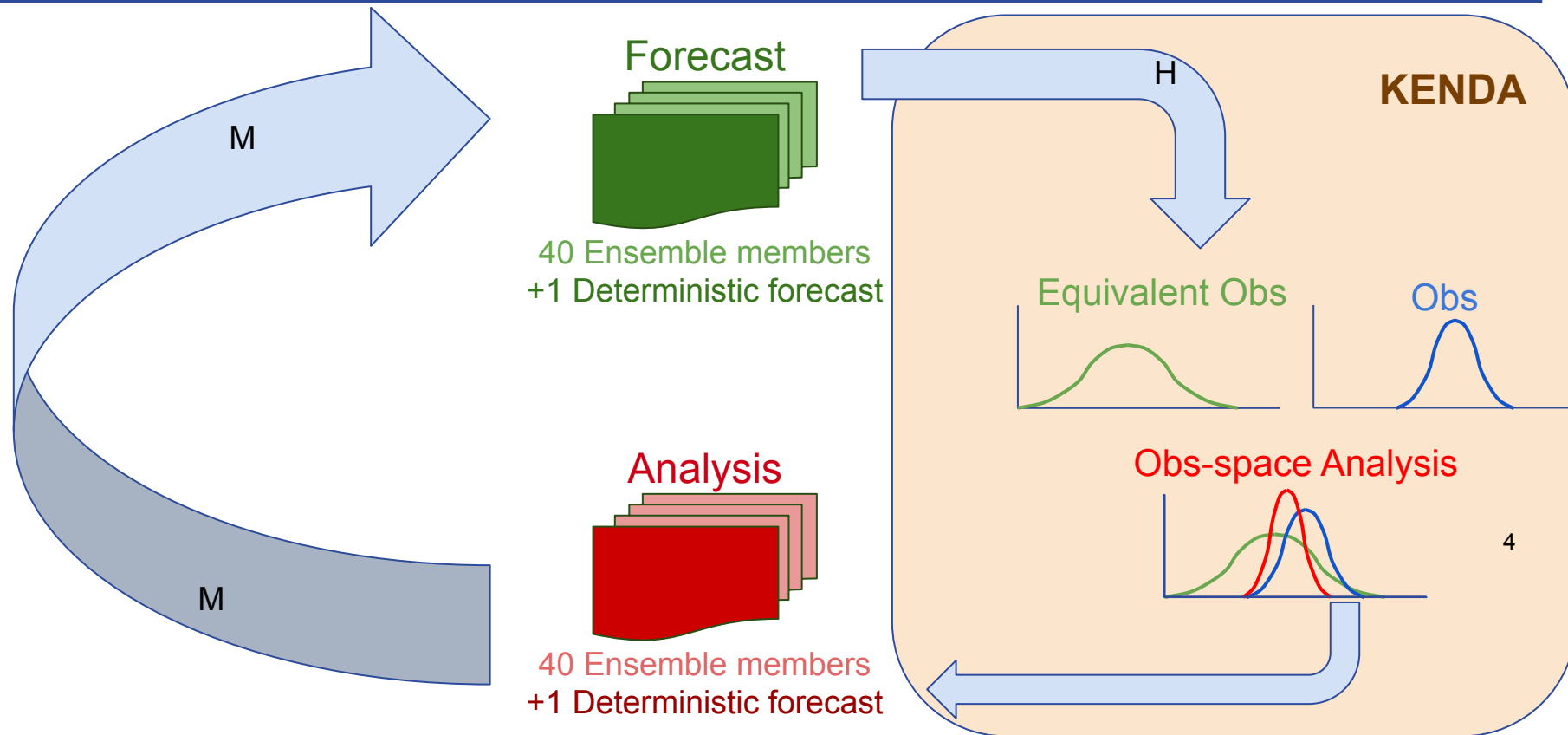
NWC Objects



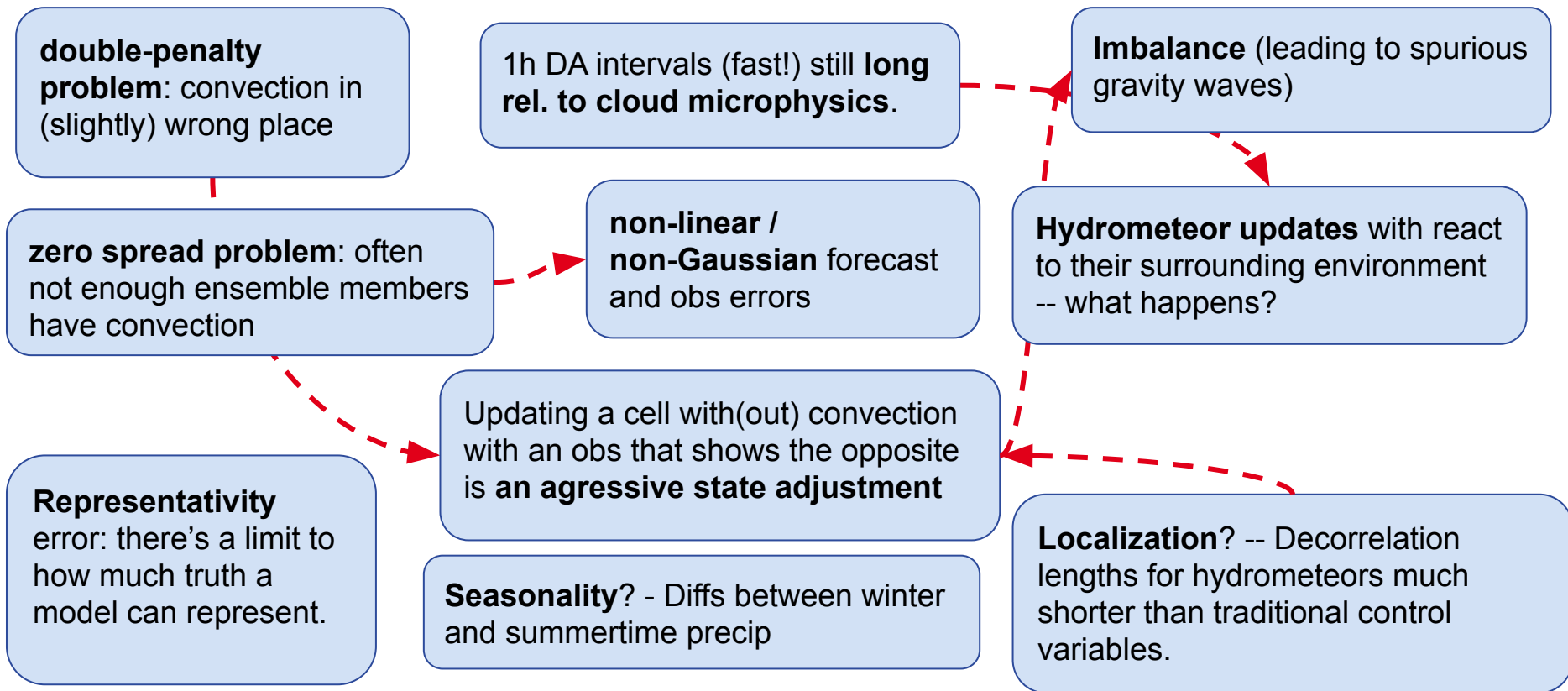
Precipitation +
Nowcasting
Knowledge

Data assimilation can use these observations to constrain precip and clouds, and also the variables related to it. But how well does this actually work?

Data Assimilation in ICON-LAM



Assimilation of Cloud and Precip ...but how?



SEVIRI-VIS

background

forward
operator

examples

Radar

background

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Lightning

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examples

Nowcast Objects

background

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examples

- SEVIRI measures **reflectance in the visible band**, the percentage of incoming solar radiation reflected back from the earth's surface or clouds
- the visible channel is around 0.6 microm and is sensitive to the following cloud properties:
 - optical thickness
 - number of particles
 - effective radii



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MFASIS Cloud Forward Operator

Inputs

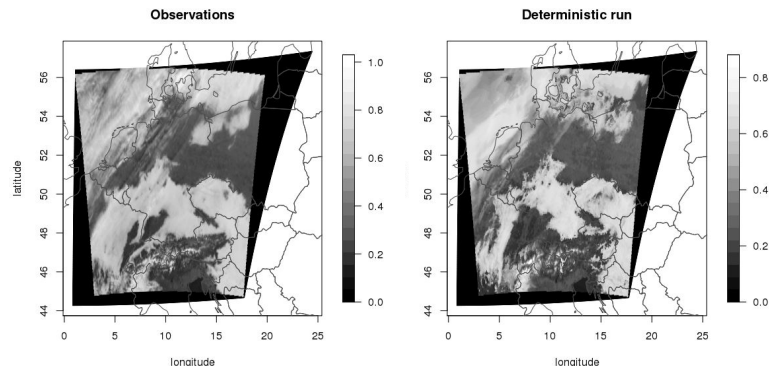
Temp
Pressure
Specific Humidity
Cloud ice, water,
snow
Cloud cover

Look-up Tables

Sun zenith angle
Particle radius
Albedo
Sat. zenith angle
Scattering angle
Optical thickness

Output

Fourier coefficients
of reflectance



Cloud and Precip Observations

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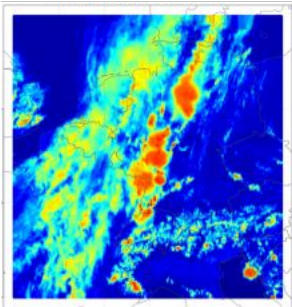
background

forward
operator

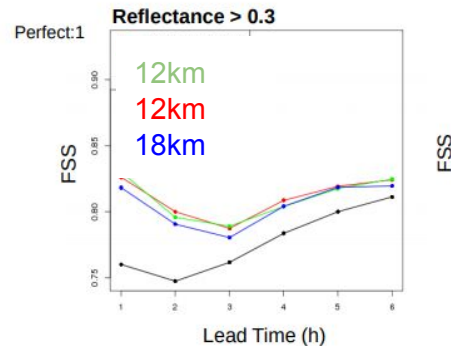
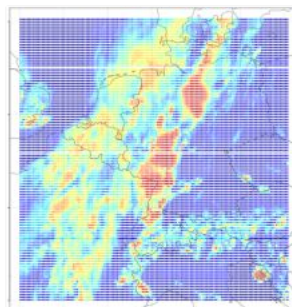
examples

Superobbing avoids representativity errors, overwhelming the system.

Full resolution



~12 km

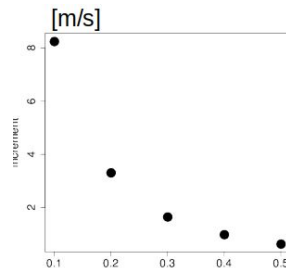


Adaptive Obs Error avoids shocks to the system

manually adjust assumed
obs error relative to first
guess departure:

$$\sigma_o^2 = \max(e_c^2, (o - b)^2)$$

wind
increment



obs error

Cloud and Precip Observations

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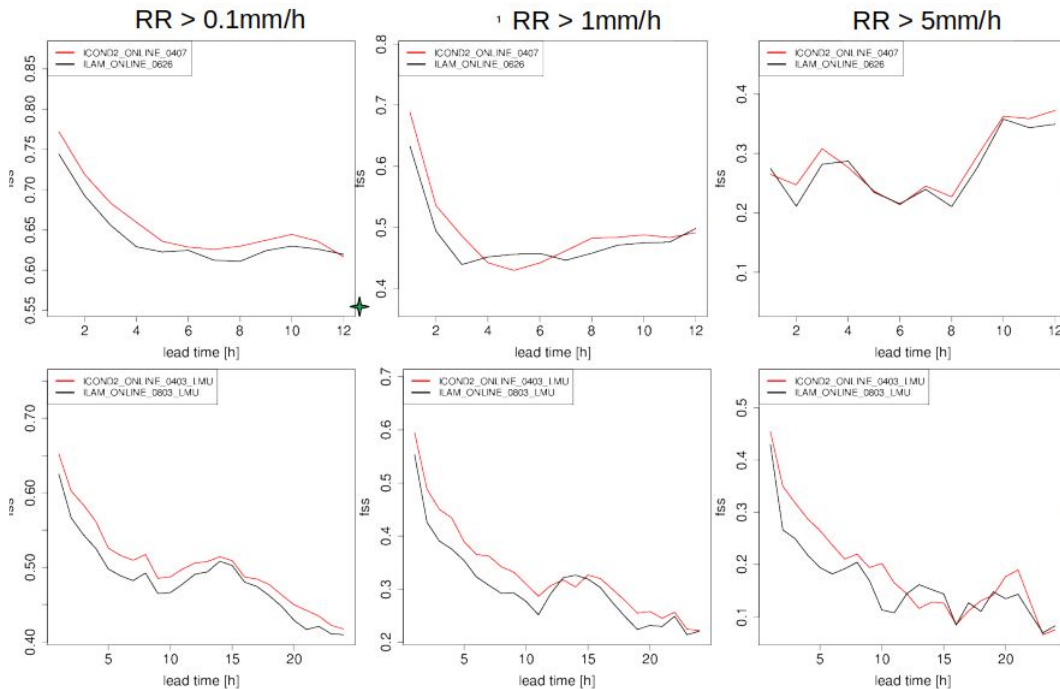
examples

Nowcast Objects

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examples



Cloud and Precip Observations

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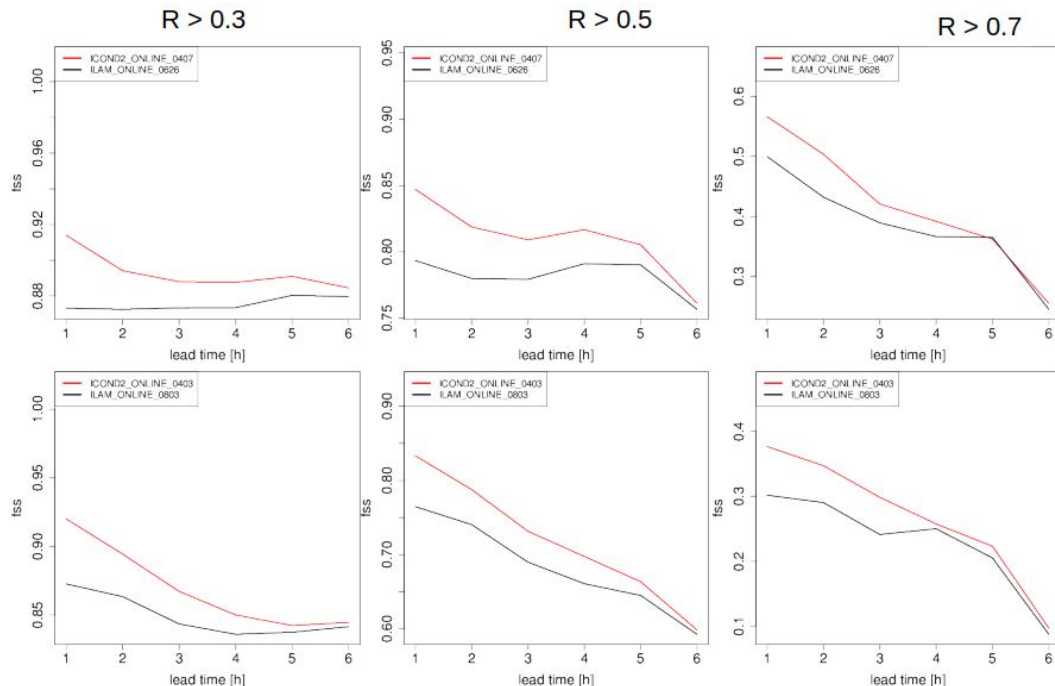
examples

Nowcast Objects

background

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examples



June19

July19

Cloud and Precip Observations

SEVIRI-VIS

| | | |
|------------|------------------|----------|
| background | forward operator | examples |
|------------|------------------|----------|

Radar

| | | |
|------------|------------------|----------|
| background | forward operator | examples |
|------------|------------------|----------|

Lightning

| | | |
|------------|------------------|----------|
| background | forward operator | examples |
|------------|------------------|----------|

Nowcast Objects

| | | |
|------------|------------------|----------|
| background | forward operator | examples |
|------------|------------------|----------|

EMVORADO Forward Operator

Inputs

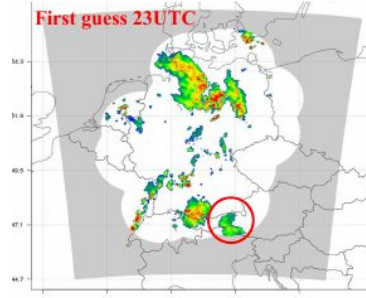
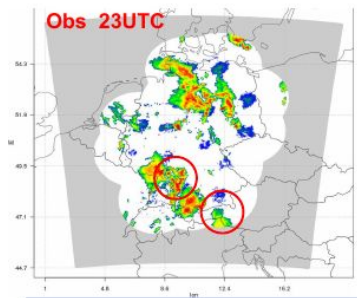
hydrometeors (qx)
hydrometeor
number densities

EMVORADO

scattering
attenuation
partial melting
beam broadening

Output

Simulated Z, Vr



Cloud and Precip Observations

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examples

Lightning

background

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operator

examples

Nowcast Objects

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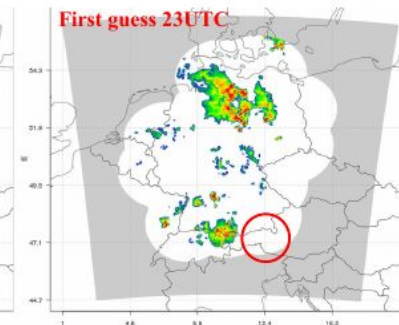
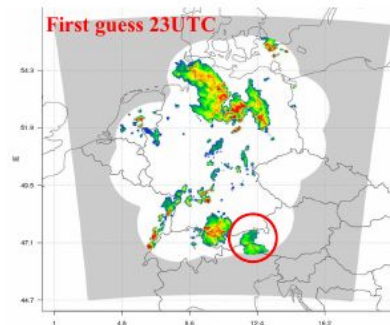
Updating Hydrometeors?

with qr qs qg update

without qr qs qg update

First guess 23UTC

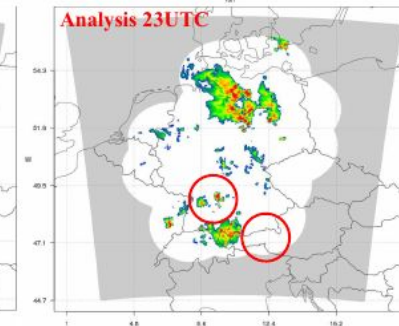
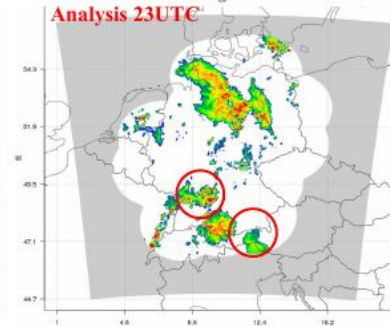
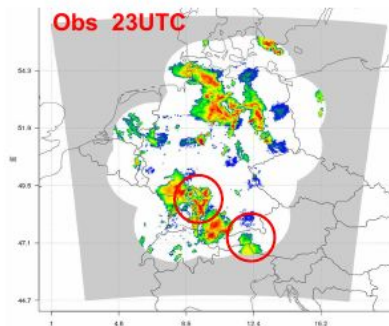
First guess 23UTC



Obs 23UTC

Analysis 23UTC

Analysis 23UTC



Cloud and Precip Observations

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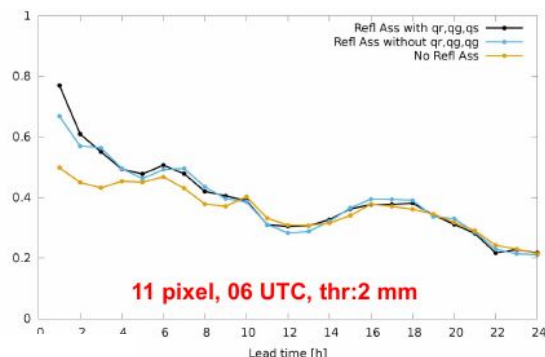
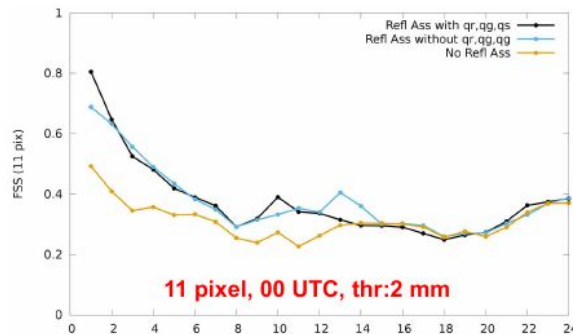
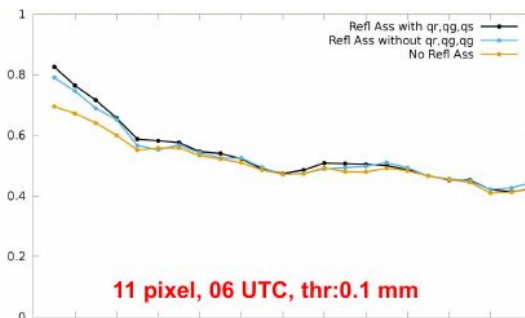
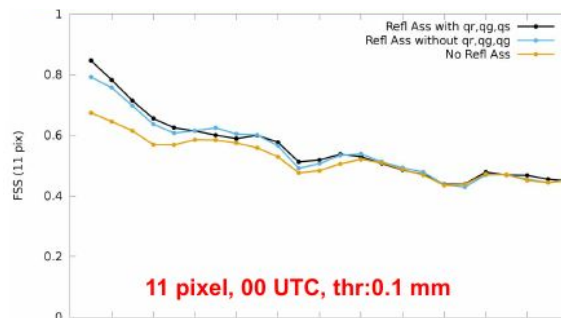
Nowcast Objects

background

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operator

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Precip Verification



Conv obs only

Conv+Radar

Conv+Radar+Hydrometeor Updates

plots by Kobra Khorsravian



Cloud and Precip Observations

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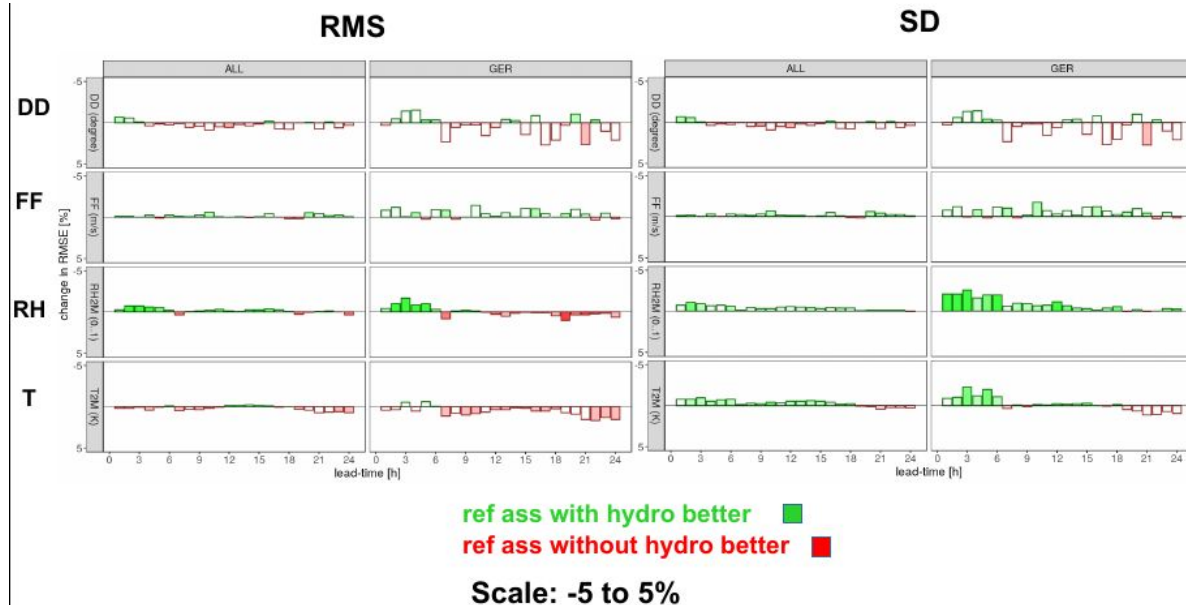
Nowcast Objects

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examples

Verification against SYNOP Data



plots by Kobra Khorsravian

SEVIRI-VIS

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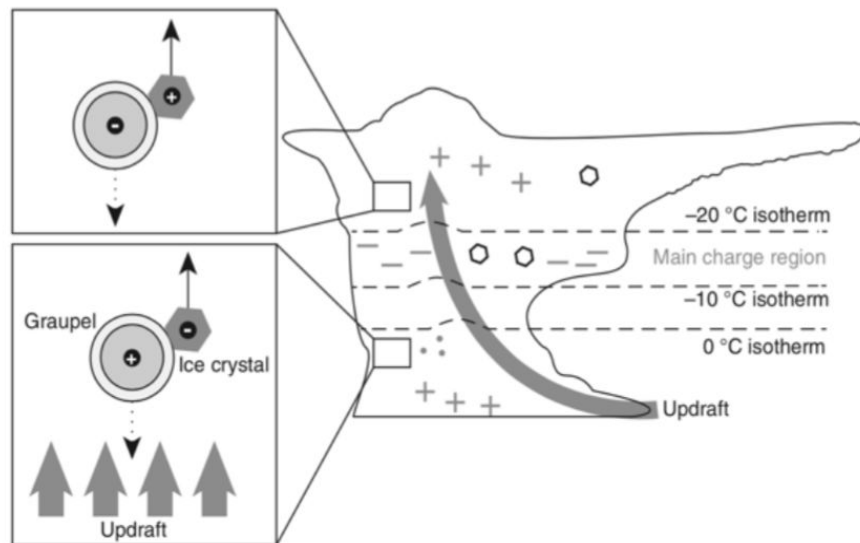
Nowcast Objects

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How does lightning happen?



SEVIRI-VIS

| | | |
|------------|------------------|----------|
| background | forward operator | examples |
|------------|------------------|----------|

Radar

| | | |
|------------|------------------|----------|
| background | forward operator | examples |
|------------|------------------|----------|

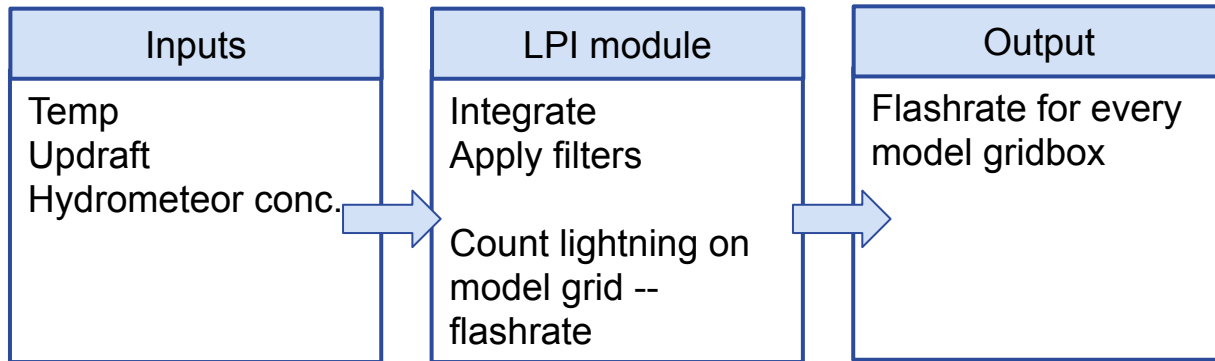
Lightning

| | | |
|------------|------------------|----------|
| background | forward operator | examples |
|------------|------------------|----------|

Nowcast Objects

| | | |
|------------|------------------|----------|
| background | forward operator | examples |
|------------|------------------|----------|

Lightning Potential Index



$$\text{LPI} = f_1 \frac{1}{\Delta z} \int_{z_0^{\circ\text{C}}}^{z_{-20^{\circ\text{C}}}} w^2 \epsilon g_w(w) g_g(q_g) dz$$

$$\epsilon = 2 \frac{\sqrt{Q_i Q_l}}{Q_i + Q_l},$$

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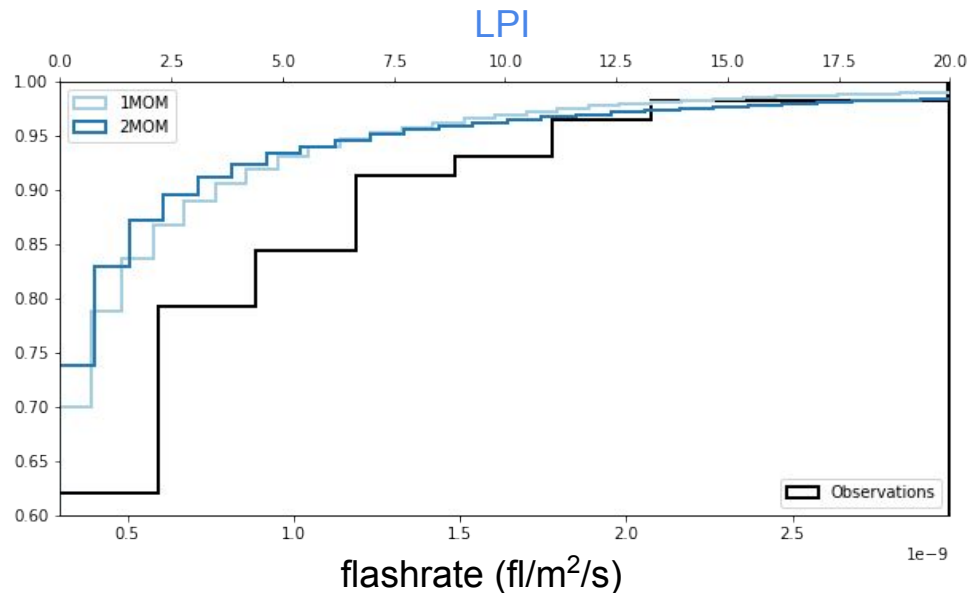
Nowcast Objects

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Scaling Lightning Potential Index to Flashrate



$$\text{FLR} = (1.56\text{E-}10) * \text{LPI}$$

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How does a patch of lightning get assimilated?

“Brute force” DA:

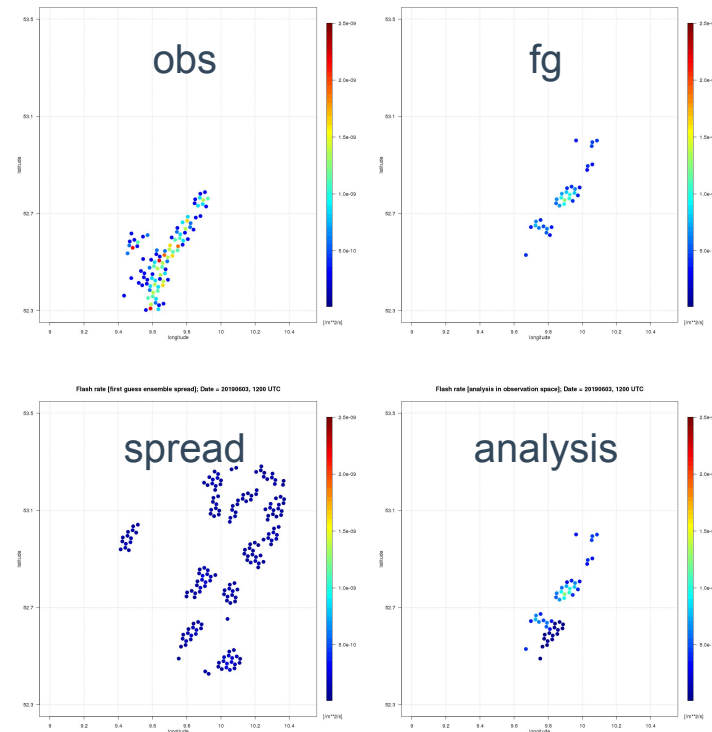
flashrate at every
model gridbox

$e^{\text{obs}} = 2$ flashes/box

assign height = 500
hPa



Obs assimilated:
 $181/3030 = 6\%$



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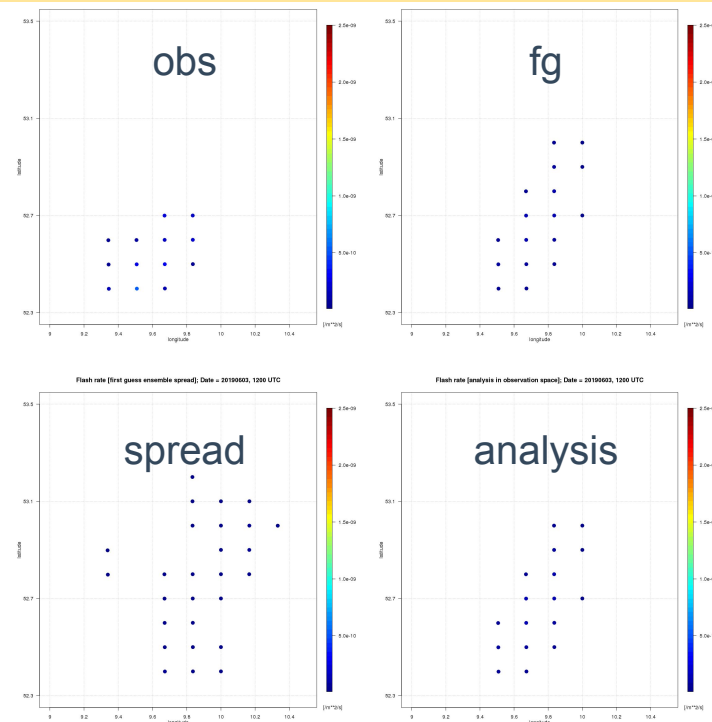
How does a patch of lightning get assimilated?

Superrobbed DA:

flashrate at every 4th
COSMO box (ca
12km)



Obs assimilated:
 $74/114 = 65\%$



Cloud and Precip Observations

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Verification against AIREP & TEMP humidity obs

Conv obs

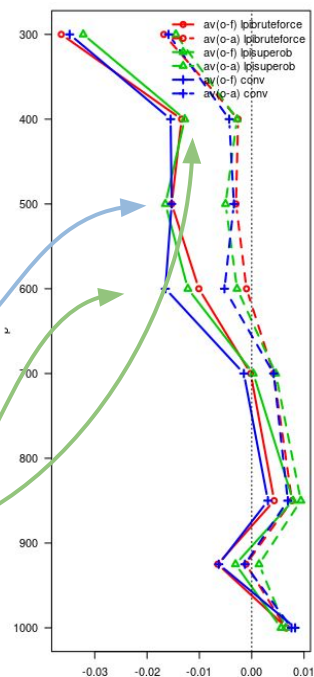
Conv obs + Lightn

Conv obs + Lightn Superob

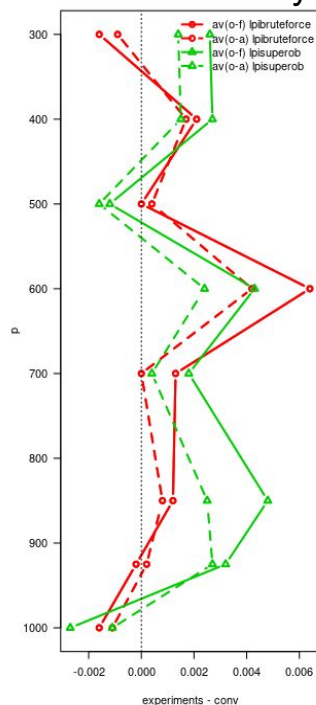
slight decrease
where obs inserted

larger increase
surrounding

bias



diff to conv-only



Cloud and Precip Observations

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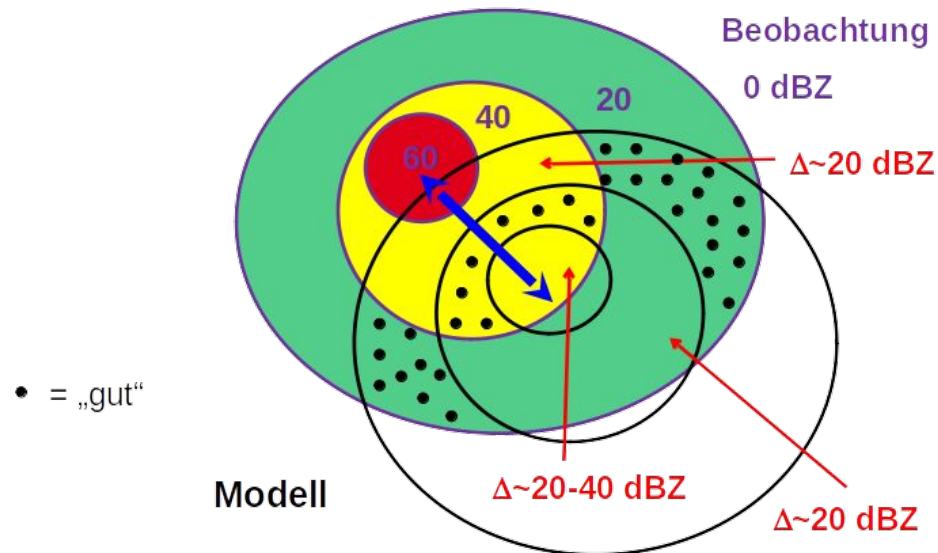
examples

Nowcast Objects

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schematic by Christian Welzbacher

SEVIRI-VIS

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KONRAD3D Objects

KONRAD3D (**KON**vectionsentwicklung in **RAD**arprodukten) is a deterministic method for:

object recognition

object tracking

object forecasting

...developed by Manuel Werner at DWD

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KONRAD3D Objects

Inputs

model-equivalent
3D radar data
(EMVORADO
output)

KONRAD3D

object detection
tracking
forecasting

Output

cell polygons
cell centroids
cell tracks
uncertainty ellipses
cell intensity
hail flag
cell velocity
cell volume
cell area
number of objects
cell VIL
& more...

“gridded features”

Cloud and Precip Observations

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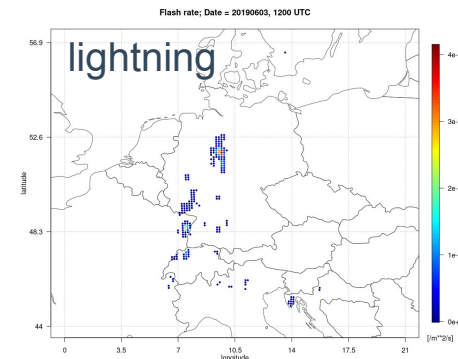
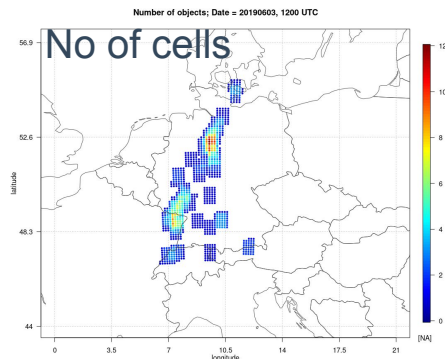
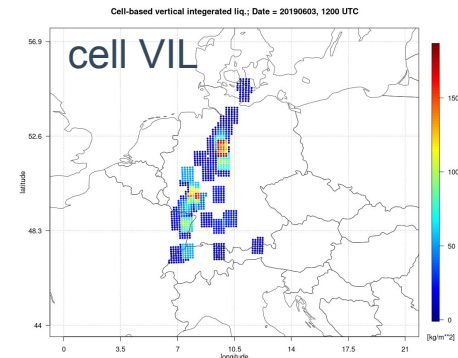
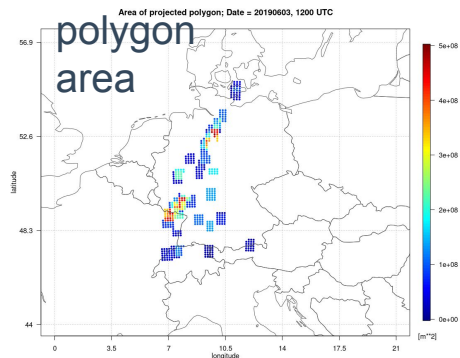
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Gridded Features Examples



Cloud and Precip Observations

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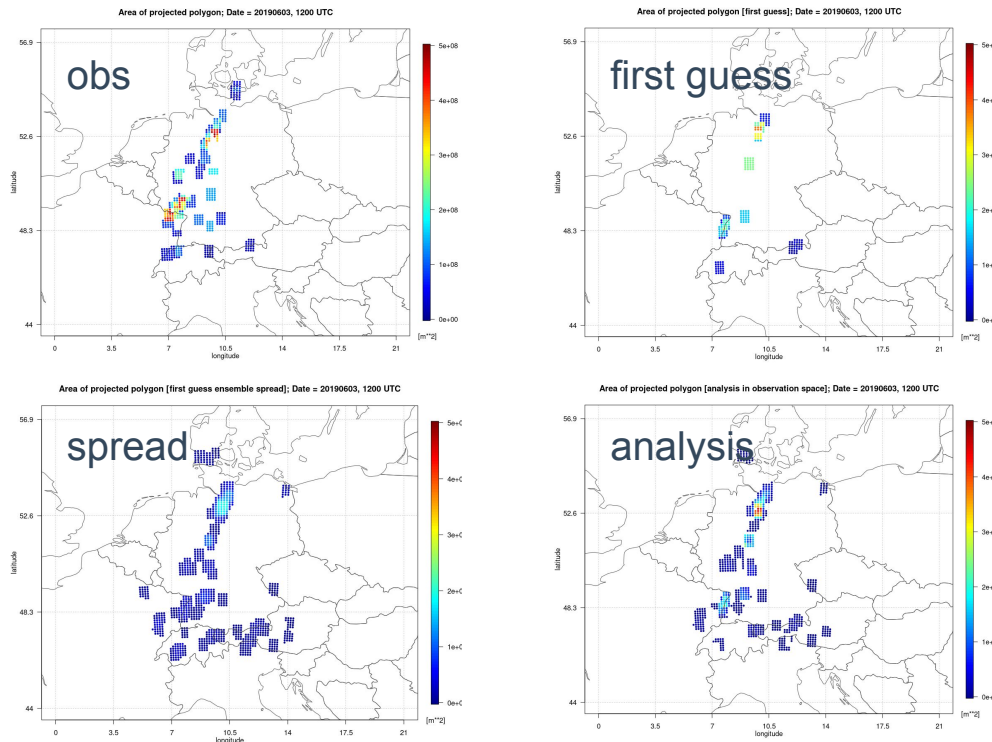
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Sample DA: Area of Projected Polygon



Cloud and Precip Observations

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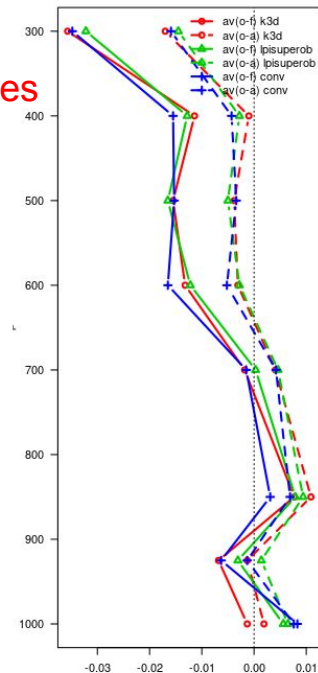
Verification against AIREP & TEMP humidity obs

Conv obs

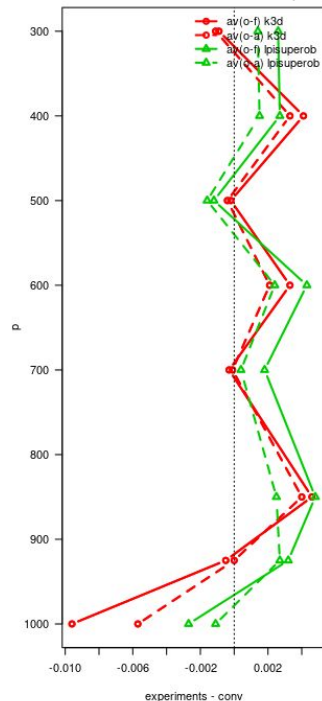
Conv obs + Gridded Features

Conv obs + Lightn Superob

bias



diff to conv-only



Successes

- Radar DA improves things pretty robustly
- Updating hydrometeors generally works well in radar DA
- SEVIRI-VIS obs improve precip & other variables, esp. if imbalance is avoided

Challenges

- Lightning most nonzero obs rejected due to zero spread
- Lightning & Features many unknowns remain
 - vertical position
 - obs error
 - localization

*Questions that need
answering*



- **Adaptive observation error** works well for cloud obs DA -- can we say the same for lightning?
- How do these results change for ICON with **2-moment microphysics**?
- How do we implement/tune new obs together while **moving towards operationality** at different speeds?
- Is making lightning DA “work” a worthwhile pursuit, or **should we treat lightning as a gridded feature**?
- How much still holds up after the **most recent ICON-LAM bug fix**?
- Do these obs have to be assimilated differently for **winter precip**?

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Referat FE12
Deutscher Wetterdienst

lisa.neef@dwd.de



Cloud and Precip Observations

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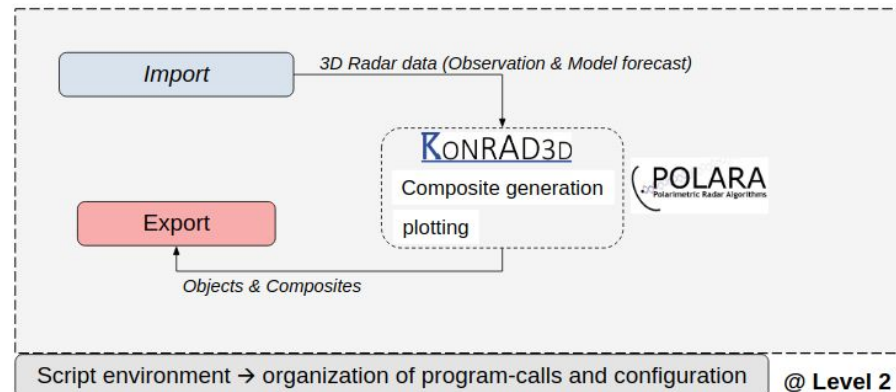
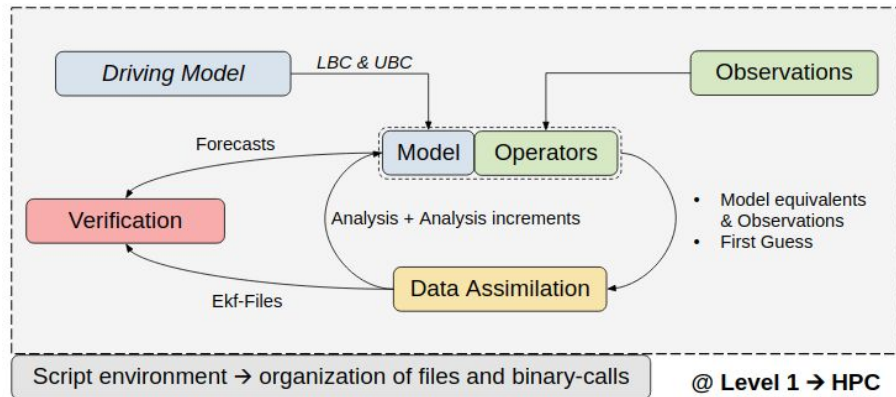
examples

Nowcast Objects

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examples



What we see:

- the ensemble is really not Gaussian
- the pull towards obs is strongest where the variance is highest
- this looks the way it should

